

BBM402-Lecture 6: Decidable Languages and the Halting Problem

Lecturer: Lale Özkahya

Resources for the presentation:
<https://courses.engr.illinois.edu/cs373/fa2010/lectures>

Decidable and Recognizable Languages

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- We just saw some example algorithms all of which terminate in a finite number of steps, and output yes or no (accept or reject). i.e., They decide the corresponding languages.

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- However A_{TM} is **Turing-recognizable!**

Proposition

There are languages which are recognizable, but not decidable

Recognizing A_{TM}

Program U for recognizing A_{TM} :

```
On input  $\langle M, w \rangle$   
  simulate  $M$  on  $w$   
  if simulated  $M$  accepts  $w$ , then accept  
  else reject (by moving to  $q_{rej}$ )
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Deciding vs. Recognizing

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If L and \bar{L} are recognizable, then L is decidable

Proof.

Program P for **deciding** L , given programs P_L and $P_{\bar{L}}$ for recognizing L and \bar{L} :

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- Which one to simulate first?

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- On input x , simulate **in parallel** P_L and $P_{\bar{L}}$ on input x until either P_L or $P_{\bar{L}}$ accepts

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- Which one to simulate first? Either could go on forever.
- On input x , simulate **in parallel** P_L and $P_{\bar{L}}$ on input x until either P_L or $P_{\bar{L}}$ accepts
- If P_L accepts, accept x and halt. If $P_{\bar{L}}$ accepts, reject x and halt.



Deciding vs. Recognizing

Proof (contd).

In more detail, P works as follows:

On input x

for $i = 1, 2, 3, \dots$

 simulate P_L on input x for i steps

 simulate $P_{\bar{L}}$ on input x for i steps

 if either simulation accepts, break

if P_L accepted, accept x (and halt)

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if P_L accepted, accept x (and halt)

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(Alternately, maintain configurations of P_L and $P_{\bar{L}}$, and in each iteration of the loop advance both their simulations by one step.)



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Note: Decidable languages are closed under complementation, but recognizable languages are not.

Decision Problems and Languages

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- A decision problem is represented as a **formal language** consisting of those strings (inputs) on which the answer is “yes” .

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Recursive Enumerability

- A Turing Machine on an input w either (halts and) accepts, or (halts and) rejects, or never halts.
- The language of a Turing Machine M , denoted as $L(M)$, is the set of all strings w on which M accepts.
- A language L is **recursively enumerable/Turing recognizable** if there is a Turing Machine M such that $L(M) = L$.

Decidability

- A language L is **decidable** if there is a Turing machine M such that $L(M) = L$ and M halts on every input.

Decidability

- A language L is **decidable** if there is a Turing machine M such that $L(M) = L$ and M halts on every input.
- Thus, if L is decidable then L is recursively enumerable.

Undecidability

Definition

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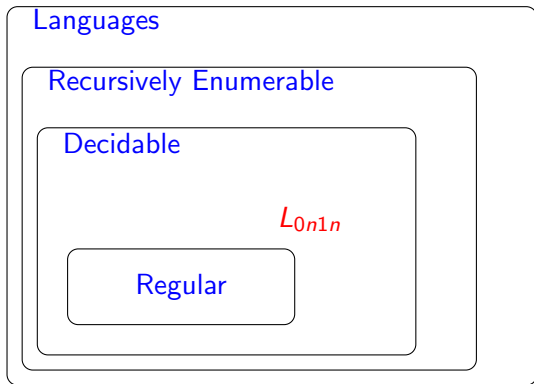
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- This means that either L is not recursively enumerable. That is there is no Turing machine M such that $L(M) = L$, or
- L is recursively enumerable but not decidable. That is, any Turing machine M such that $L(M) = L$, M does not halt on some inputs.

Big Picture



Relationship between classes of Languages

Machines as Strings

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- Any Turing Machine/program M can itself be encoded as a binary string. Moreover every binary string can be thought of as encoding a TM/program. (If not the correct format, considered to be the encoding of a default TM.)
- We will consider decision problems (language) whose inputs are Turing Machine (encoded as a binary string)

The Diagonal Language

Definition

Define $L_d = \{M \mid M \notin L(M)\}$.

The Diagonal Language

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Define $L_d = \{M \mid M \notin L(M)\}$. Thus, L_d is the collection of Turing machines (programs) M such that M does not halt and accept when given itself as input.

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Proposition

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- In what follows, we will denote the i th binary string (in lexicographic order) as the number i . Thus, we can say $j \in L(i)$, which means that the Turing machine corresponding to i th binary string accepts the j th binary string. ...→

Completing the proof

Diagonalization: Cantor

Proof (contd).

We can organize all programs and inputs as a (infinite) matrix, where the (i, j) th entry is Y if and only if $j \in L(i)$.

		Inputs \longrightarrow							
		1	2	3	4	5	6	7	\dots
TMs \downarrow	1	N	N	N	N	N	N	N	
	2	N	N	N	N	N	N	N	
	3	Y	N	Y	N	Y	Y	Y	
	4	N	Y	N	Y	Y	N	N	
	5	N	Y	N	Y	Y	N	N	
	6	N	N	Y	N	Y	N	Y	

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Suppose L_d is recognized by a Turing machine, which is the j th binary string. i.e., $L_d = L(j)$.

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Suppose L_d is recognized by a Turing machine, which is the j th binary string. i.e., $L_d = L(j)$. But $j \in L_d$ iff $j \notin L(j)$!



Acceptor for L_d ?

Consider the following program

On input i

Run program i on i

Output “yes” if i does not accept i

Output “no” if i accepts i

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Does the above program recognize L_d ?

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Does the above program recognize L_d ? No, because it may never output “yes” if i does not halt on i .

Models for Decidable Languages

Question

Is there a machine model such that

- all programs in the model halt on all inputs, and
- for each problem decidable by a TM, there is a program in the model that decides it?

Models for Decidable Languages

Answer

There is no such model!

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There is no such model! Suppose there is a programming language in which all programs always halt. Programs in this language can be described by binary strings, and can be simulated by TMs.

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There is no such model! Suppose there is a programming language in which all programs always halt. Programs in this language can be described by binary strings, and can be simulated by TMs. Consider the Turing Machine M_d

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- L_d not recursively enumerable, and therefore not decidable.
Are there languages that are recursively enumerable but not decidable?
- Yes, $A_{\text{TM}} = \{\langle M, w \rangle \mid M \text{ is a TM and } M \text{ accepts } w\}$

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Observe that $L(D) = L_d!$

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Observe that $L(D) = L_d!$ But, L_d is not r.e. which gives us the contradiction. □

A more complete Big Picture

