Bag of Words

BIL719– Computer Vision Pinar Duygulu Hacettepe University

Revisit Texture

- Texture depicts spatially repeating patterns
- Many natural phenomena are textures



radishes



rocks



yogurt

Texton Discrimination (Julesz)

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Human vision is sensitive to the difference of some types of elements and appears to be "numb" on other types of differences.

Search Experiment I



(a)



The subject is told to detect a target element in a number of background elements. In this example, the detection time is independent of the number of background elements.

Search Experiment II





In this example, the detection time is proportional to the number of background elements, And thus suggests that the subject is doing element-by-element scrutiny.

Heuristic (Axiom) I

Julesz then conjectured the following axiom:

Human vision operates in two distinct modes:

1. Preattentive vision

parallel, instantaneous (~100--200ms), without scrutiny, independent of the number of patterns, covering a large visual field.

2. Attentive vision

serial search by focal attention in 50ms steps limited to small aperture.

Then what are the basic elements?

Heuristic (Axiom) II

Julesz's second heuristic answers this question:

Textons are the fundamental elements in preattentive vision, including

1. Elongated blobs

rectangles, ellipses, line segments with attributes color, orientation, width, length, flicker rate.

2. Terminators

ends of line segments.

3. Crossings of line segments.

But it is worth noting that Julesz's conclusions are largely based by ensemble of artificial texture patterns. It was infeasible to synthesize natural textures for controlled experiments at that time.

Bag of words





I 🔨 / -

 $\sum_{i=1}^{n} \sum_{i=1}^{n} \sum_{i$ 뷥말 Torralba, MIT

Bag of words & spatial pyramid matching



Grauman & Darell, S. Lazebnik, et al, CVPR 2006 Torralba, MIT

Histogram Intersection

Histogram intersection





Slide credit: Kristen Grauman

Histogram based distances

Given two histograms: h1, h2, such that sum(h1)=sum(h2)=1

- Euclidean
 D(h1, h2) = sum ((h1 h2).^2)
- Histogram intersection
 D(h1, h2) = 1-sum (min (h1, h2))
- X²
 D(h1, h2) = sum((h1-h2).^2 ./ (h1+h2))

Capturing the "essence" of texture

• ...for re





- We don't want an actual texture realization, we want a texture invariant
- What are the tools for capturing <u>statistical</u> properties of some signal?

Multi-scale filter decomposition

Filter bank





Input image



Alyosha Efros, CMU

Filter response histograms



Alyosha Efros, CMU

Textons (Malik et al, IJCV 2001)

• K-means on vectors of filter responses



Textons (cont.)



Modelling I – Learning the Texton Dictionary

Varma, M. and Zisserman, A., IJCV 2005

Modelling II - Multiple Models Per Texture

Varma, M. and Zisserman, A., IJCV 2005

Textons

Walker, Malik, 2004

Torralba, MIT

Revisit Keypoint Matching

1. Find a set of distinctive keypoints

- 2. Define a region around each keypoint
- 3. Extract and normalize the region content
- 4. Compute a local descriptor from the normalized region
- 5. Match local descriptors

K. Grauman, B. Leibe

Hayes, Brown

Finding the objects (overview)

- 1. Match interest points from input image to database image
- 2. Matched points vote for rough position/orientation/scale of object
- 3. Find triplets of position/orientation/scale that have at least three votes
- 4. Compute affine registration and matches using iterative least squares with outlier check
- 5. Report object if there are at least T matched points

Matching Keypoints

- Want to match keypoints between:
 - 1. Query image
 - 2. Stored image containing the object
- Given descriptor x₀, find two nearest neighbors x₁, x₂ with distances d₁, d₂
- x_1 matches x_0 if $d_1/d_2 < 0.8$
 - This gets rid of 90% false matches, 5% of true matches in Lowe's study

Hayes, Brown

Simple idea

See how many keypoints are close to keypoints in each other image

Few or No Matches

But this will be really, really slow!

Hayes, Brown

Indexing local features

• Each patch / region has a descriptor, which is a point in some high-dimensional feature space (e.g., SIFT)

Indexing local features

• When we see close points in feature space, we have similar descriptors, which indicates similar local content.

Kristen Graun

Indexing local features: inverted file index

"Along I-75," From Detroit to	Butterfly Center, McGuire; 134	Driving Lanes; 85
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- For text documents, an efficient way to find all *pages* on which a *word* occurs is to use an index...
- We want to find all *images* in which a *feature* occurs.
- To use this idea, we'll need to map our features to "visual words".

Kristen Grauman

Visual words

• Map high-dimensional descriptors to tokens/words by quantizing the feature space

- Quantize via clustering, let cluster centers be the prototype "words"
- Determine which word to assign to each new image region by finding the closest cluster center.

Visual words

• Example: each group of patches belongs to the same visual word

Figure from Sivic & Zisserman, ICCV 2003 Kristen Grauman

Inverted file index

 Database images are loaded into the index mapping words to image numbers

Inverted file index

 New query image is mapped to indices of database images that share a word.

Kristen Grauman

Analogy to documents

China is forecasting a trade surplus of \$90bn (£51bn) to \$100bn this year, a threefold increase on 2004's \$32bn. The Commerce Ministry said the surplus would dicted 30% jump in expo a 18% China, trade, rise in imp elv to further a surplus, commerce, at China's exports, imports, US, deliber yuan, bank, domestic, the sur one fact foreign, increase, Xiaochua trade, value more to bo stayed within value of the yuan July and permitted it to band, but the US wants the yuan to be d to trade freely. However, Beijing has made that it will take its time and tread careful allowing the yuan to rise further in value.

Alyosha Efros, CMU

1.Feature detection and representation

- Sliding Window
 - Leung et al, 1999
 - Viola et al, 1999
 - Renninger et al 2002

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 - Leung et al, 1999
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 - Renninger et al 2002
- Regular grid
 - Vogel et al. 2003
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 - Fei-Fei et al. 2005
- Interest point detector
 - Csurka et al. 2004
 - Fei-Fei et al. 2005
 - Sivic et al. 2005
- Other methods
 - Random sampling (Ullman et al. 2002)
 - Segmentation based patches
 - Barnard et al. 2003, Russell et al 2006, etc.)

Feature Representation

Visual words, aka textons, aka keypoints: K-means clustered pieces of the image

- Various Representations:
 - Filter bank responses
 - Image Patches
 - SIFT descriptors

All encode more-or-less the same thing...

Interest Point Features

Detect patches

[Mikojaczyk and Schmid '02] [Matas et al. '02] [Sivic et al. '03]

Slide credit: Josef Sivic

Interest Point Features

Alyosha Efros, CMU

Patch Features

Alyosha Efros, CMU

dictionary formation

Clustering (usually k-means)

Slide credit: Josef Sivic

Clustered Image Patches

Fei-Fei et al. 2005

Image patch examples of codewords

Sivic et al. 2005

Visual synonyms and polysemy

Visual Polysemy. Single visual word occurring on different (but locally similar) parts on different object categories.

Visual Synonyms. Two different visual words representing a similar part of an object (wheel of a motorbike).

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Image representation

Alyosha Efros, CMU

Bags of visual words

- Summarize entire image based on its distribution (histogram) of word occurrences.
- Analogous to bag of words representation commonly used for documents.

Comparing bags of words

 Rank frames by normalized scalar product between their (possibly weighted) occurrence counts---*nearest neighbor* search for similar images.

$$sim(d_j,q) = \frac{\langle d_j,q \rangle}{\|d_j\|\|q\|}$$

$$=\frac{\sum_{i=1}^{V} d_{j}(i) * q(i)}{\sqrt{\sum_{i=1}^{V} d_{j}(i)^{2}} * \sqrt{\sum_{i=1}^{V} q(i)}}$$

for vocabulary of V words

Kristen Grauman

Vocabulary size

Influence on performance, sparsity

Results for recognition task wit 6347 images

Nister & Stewenius, CVPR 2006 Kristen Grauman

Can we be more accurate?

Can we be more accurate?

So far, we treat each image as containing a "bag of words", with no spatial information

Real objects have consistent geometry

Spatial Verification

DB image with high BoW similarity

Both image pairs have many visual words in common.

Slide credit: Ondrej Chum

Spatial Verification

DB image with high BoW similarity

Only some of the matches are mutually consistent

Slide credit: Ondrej Chum

What else can we borrow from text retrieval?

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Driving Lanes; 85

tf-idf weighting

- Term frequency inverse document frequency
- Describe frame by frequency of each word within it, downweight words that appear often in the database
- (Standard weighting for text retrieval)

Query Expansion

Results

Spatial verification

Query image

New results

New query

Chum, Philbin, Sivic, Isard, Zisserman: Total Recall..., ICCV 2007

Slide credit: Ondrej Chum