

FIG. 1 — Organization of a biological brain. (Red areas indicate active cells, responding to the letter X.)

AIN311

Fundamentals of Machine Learning

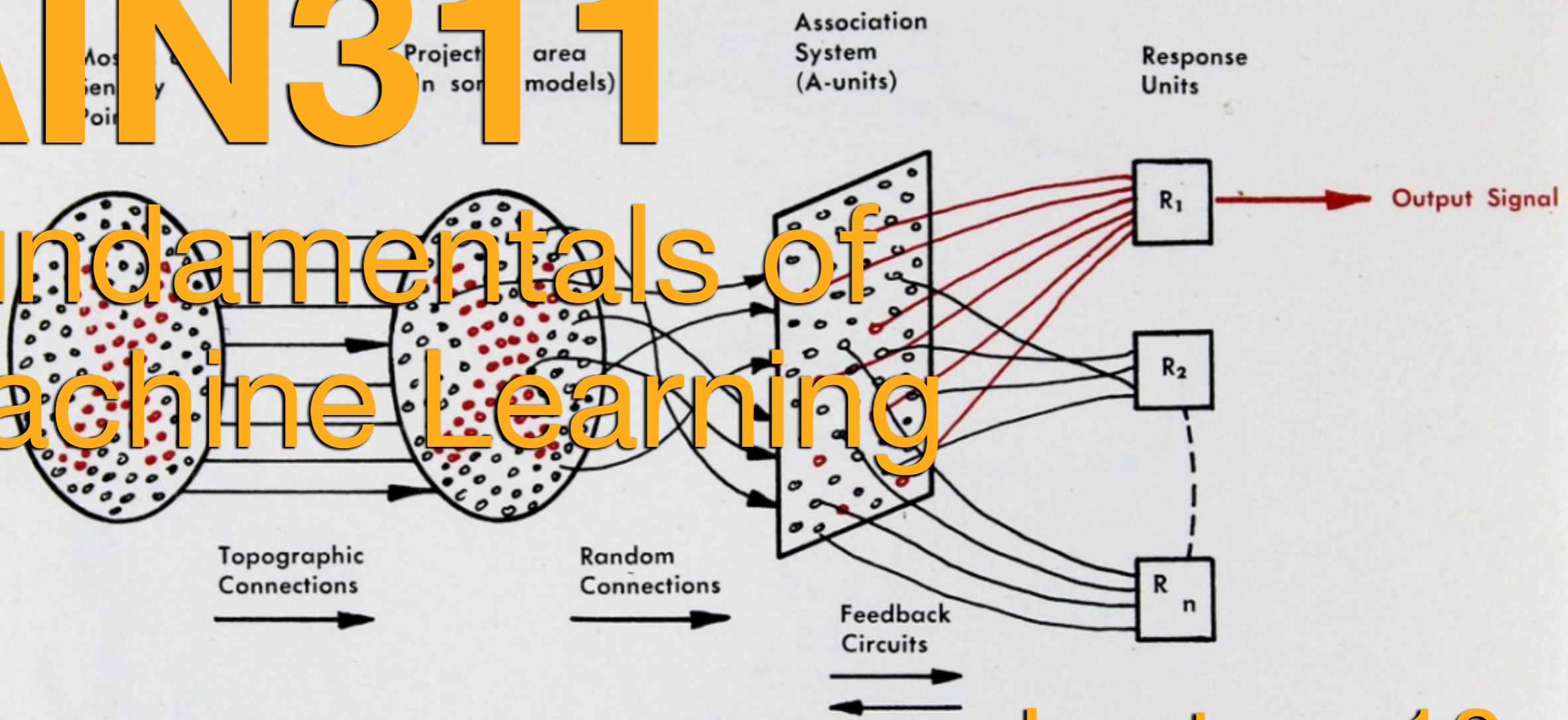


FIG. 2 — Organization of a perceptron.

Lecture 10: Linear Discriminant Functions Perceptron

Last time... Logistic Regression

Assumes the following functional form for $P(Y|X)$:

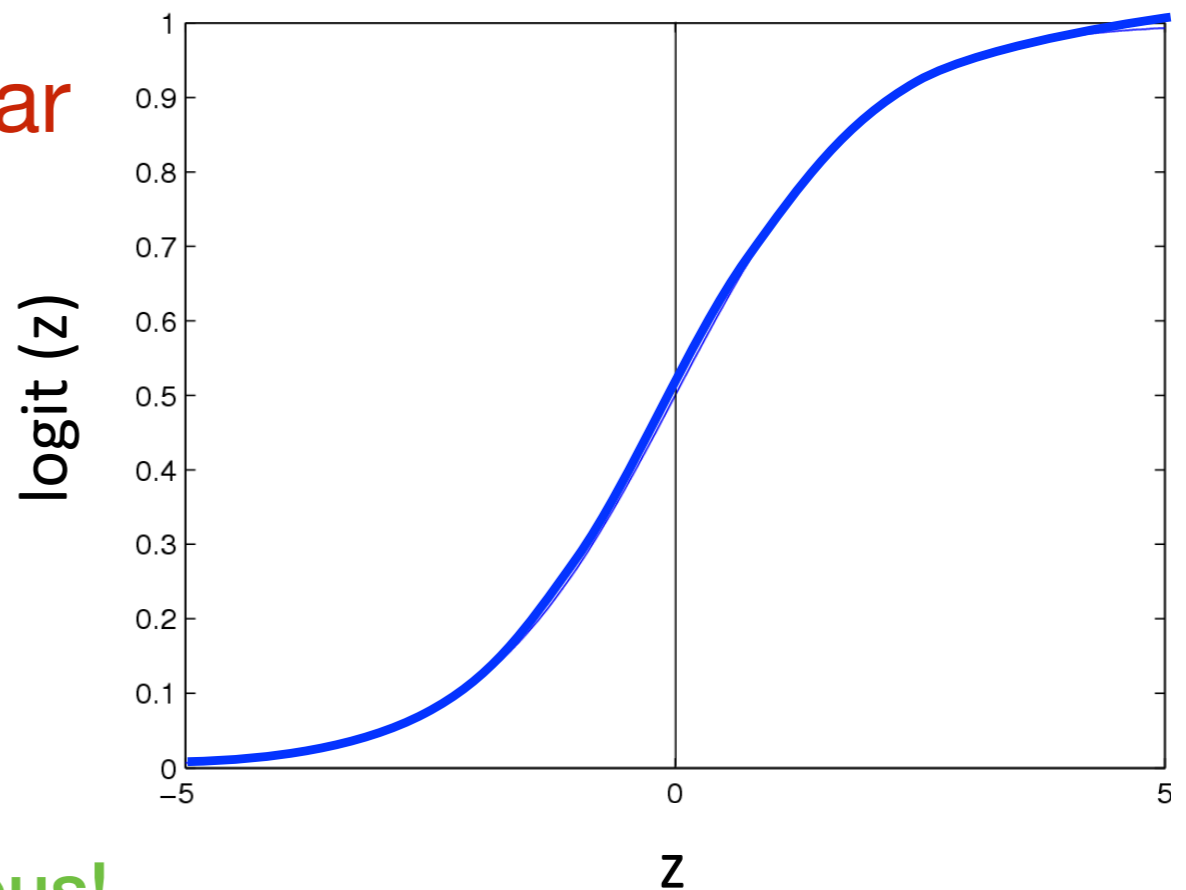
$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

Logistic function applied to linear function of the data

Logistic
function

(or Sigmoid):

$$\frac{1}{1 + \exp(-z)}$$



Features can be discrete or continuous!

Last time.. **Logistic Regression vs. Gaussian Naïve Bayes**

- LR is a linear classifier
 - decision rule is a hyperplane
- LR optimized by maximizing conditional likelihood
 - no closed-form solution
 - concave ! global optimum with gradient ascent
- Gaussian Naïve Bayes with class-independent variances representationally equivalent to LR
 - Solution differs because of objective (loss) function
- In general, NB and LR make different assumptions
 - NB: Features independent given class! assumption on $P(\mathbf{X}|Y)$
 - LR: Functional form of $P(Y|\mathbf{X})$, no assumption on $P(\mathbf{X}|Y)$
- Convergence rates
 - GNB (usually) needs less data
 - LR (usually) gets to better solutions in the limit

Linear Discriminant Functions

Linear Discriminant Function

- Linear discriminant function for a vector \mathbf{x}

$$y(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0$$

where \mathbf{w} is called weight vector, and w_0 is a bias.

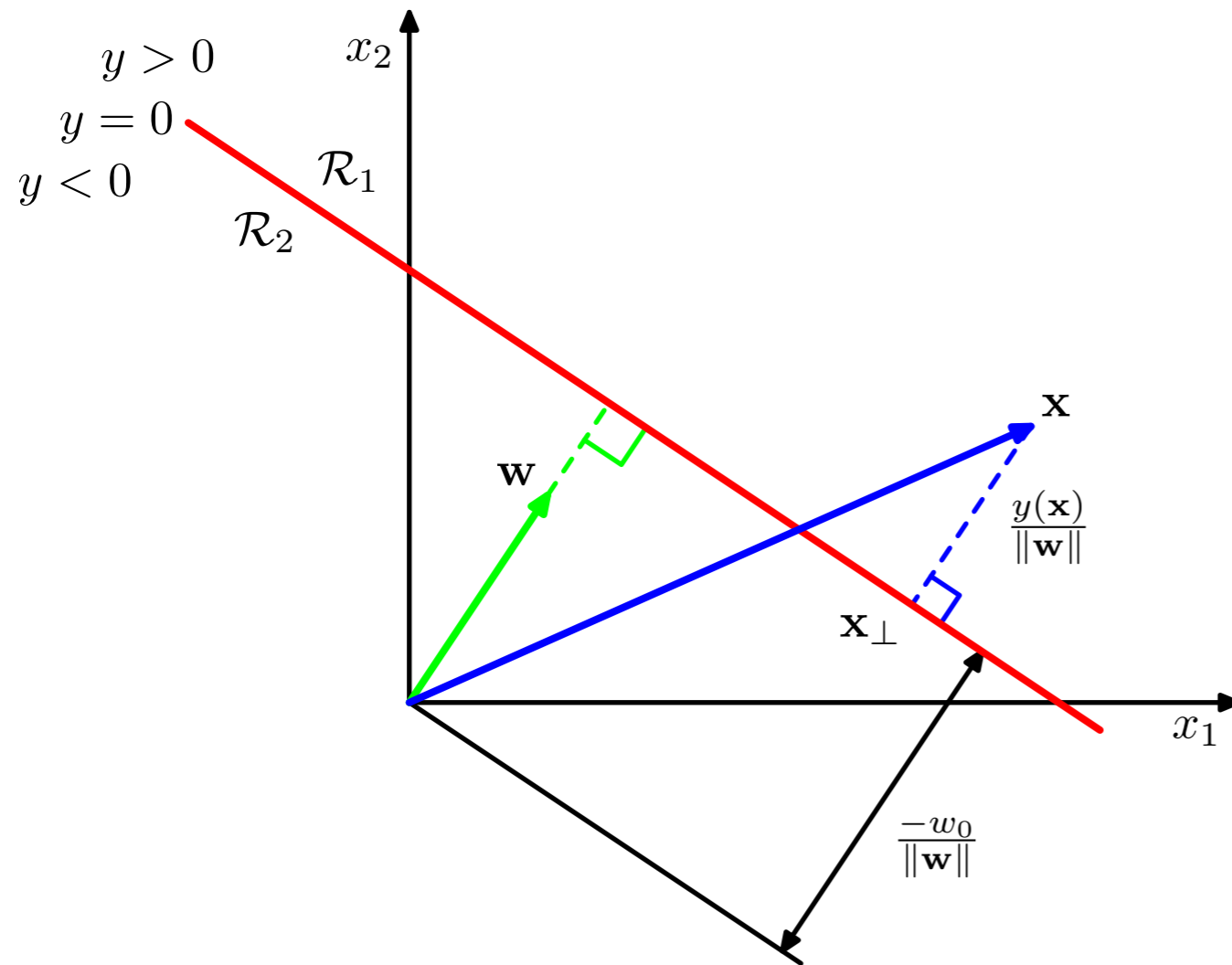
- The classification function is

$$C(\mathbf{x}) = \text{sign}(\mathbf{w}^T \mathbf{x} + w_0)$$

where step function $\text{sign}(\cdot)$ is defined as

$$\text{sign}(a) = \begin{cases} +1, & a \geq 0 \\ -1, & a < 0 \end{cases}$$

Properties of Linear Discriminant Functions



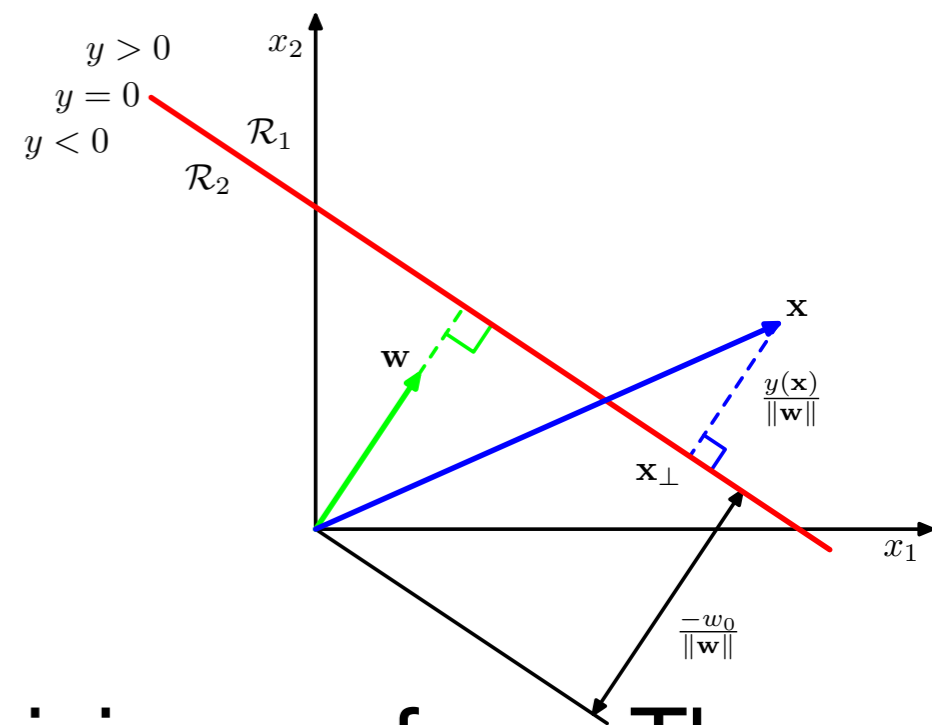
- The decision surface, shown in red, is perpendicular to \mathbf{w} , and its displacement from the origin is controlled by the bias parameter w_0 .
- The signed orthogonal distance of a general point \mathbf{x} from the decision surface is given by $y(\mathbf{x})/\|\mathbf{w}\|$
- $y(\mathbf{x})$ gives a signed measure of the perpendicular distance r of the point \mathbf{x} from the decision surface

- $y(\mathbf{x}) = 0$ for \mathbf{x} on the decision surface. The normal distance from the origin to the decision surface is

$$\frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\|} = -\frac{w_0}{\|\mathbf{w}\|}$$

- So w_0 determines the location of the decision surface.

Properties of Linear Discriminant Functions



- Let

$$\mathbf{x} = \mathbf{x}_{\perp} + r \frac{\mathbf{w}}{\|\mathbf{w}\|}$$

where \mathbf{x}_{\perp} is the projection \mathbf{x} on the decision surface. Then

$$\mathbf{w}^T \mathbf{x} = \mathbf{w}^T \mathbf{x}_{\perp} + r \frac{\mathbf{w}^T \mathbf{w}}{\|\mathbf{w}\|}$$

$$\mathbf{w}^T \mathbf{x} + w_0 = \mathbf{w}^T \mathbf{x}_{\perp} + w_0 + r \|\mathbf{w}\|$$

$$y(\mathbf{x}) = r \|\mathbf{w}\|$$

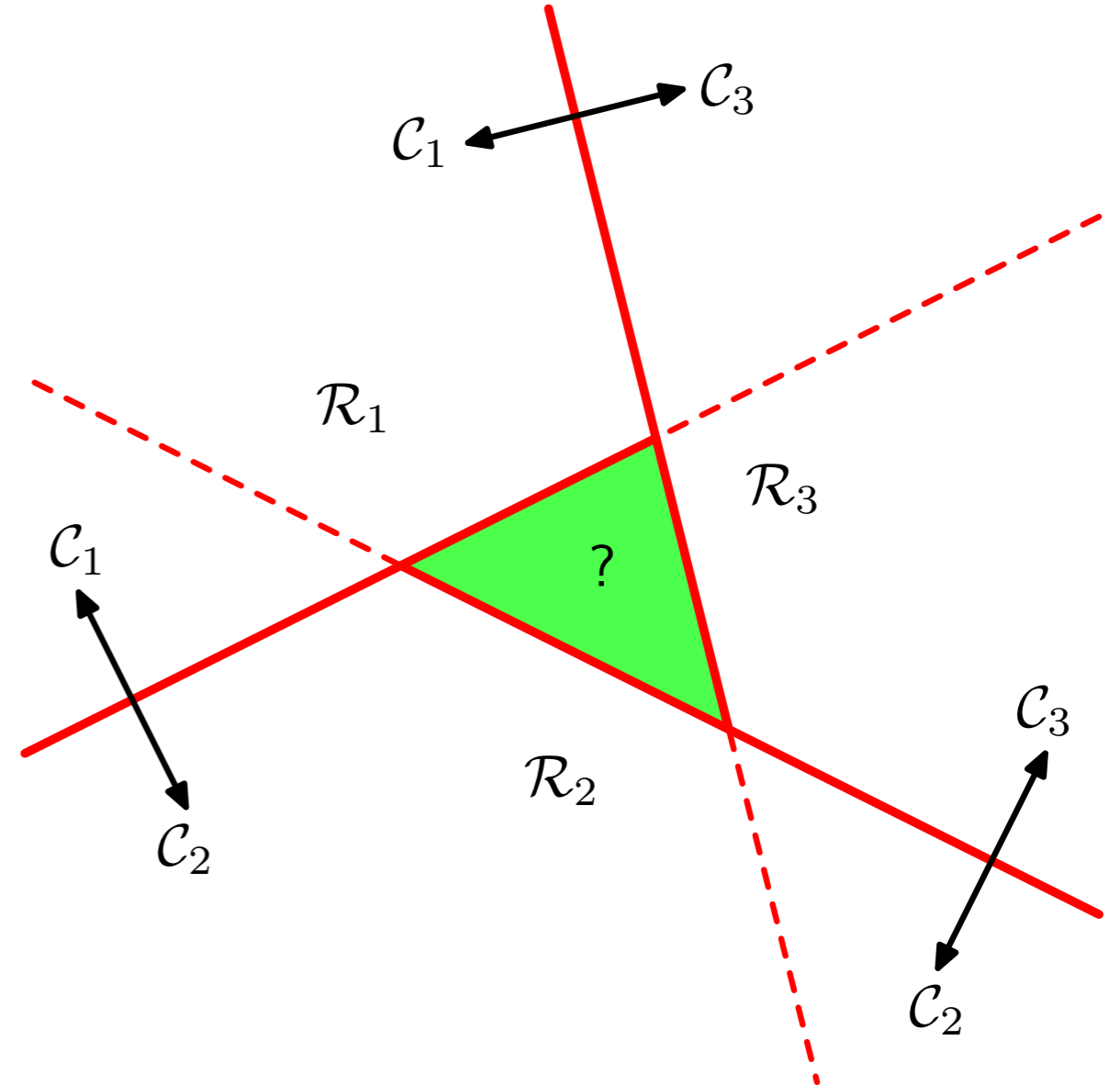
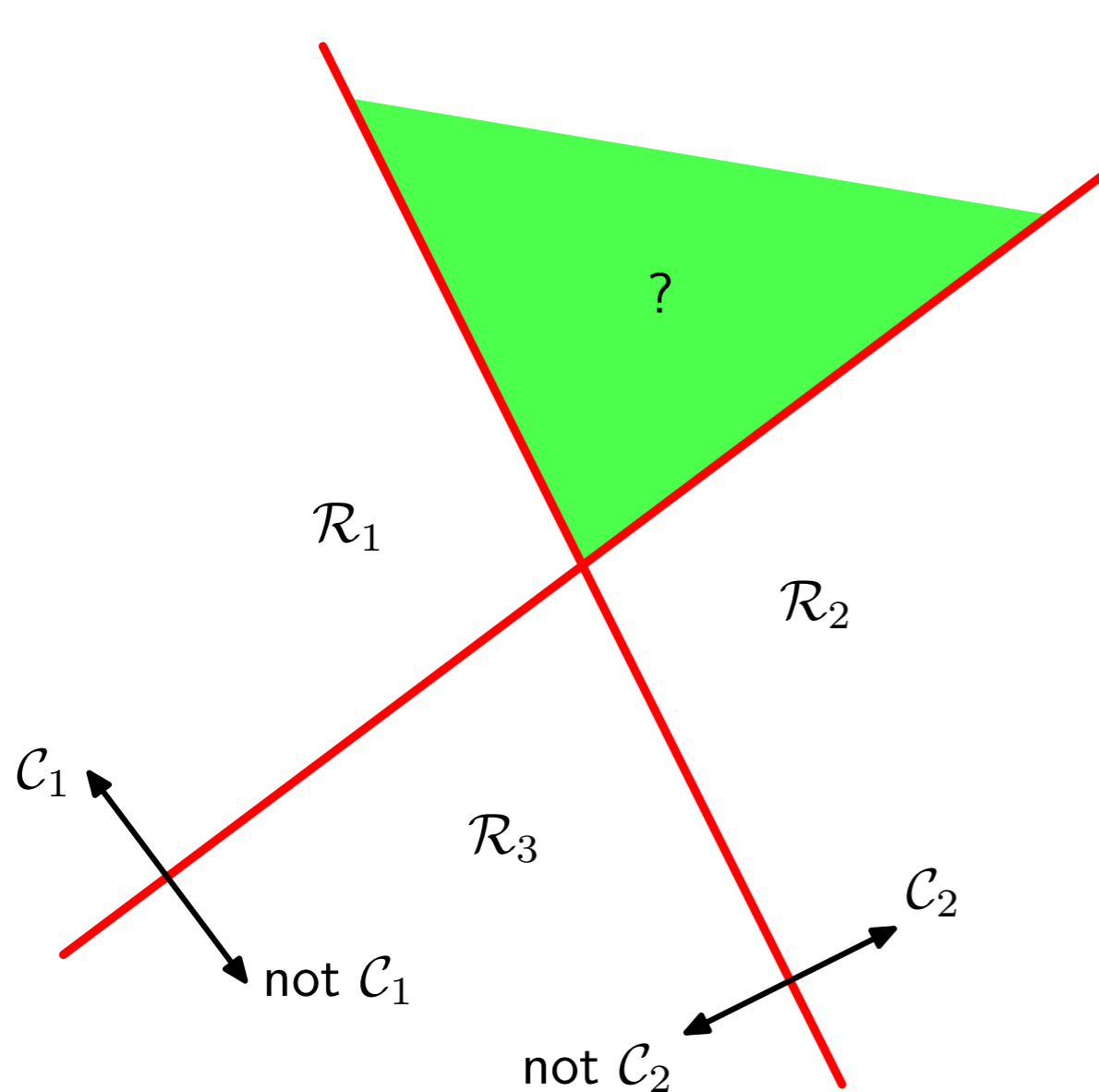
$$r = \frac{y(\mathbf{x})}{\|\mathbf{w}\|}$$

- Simpler notion: define $\tilde{\mathbf{w}} = (w_0, \mathbf{w})$ and $\tilde{\mathbf{x}} = (1, \mathbf{x})$ so that

$$y(\mathbf{x}) = \tilde{\mathbf{w}}^T \tilde{\mathbf{x}}$$

Multiple Classes: Simple Extension

- **One-versus-the-rest** classifier: classify C_k and samples not in C_k . ($K - 1$ classifiers)
- **One-versus-one** classifier: classify every pair of classes. ($K(K - 1)/2$ classifiers)



Multiple Classes: K-Class Discriminant

- A single K -class discriminant comprising K linear functions

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}$$

- Decision function

$$C(\mathbf{x}) = k, \text{ if } y_k(\mathbf{x}) > y_j(\mathbf{x}) \forall j \neq k$$

- The decision boundary between class C_k and C_j is given by $y_k(\mathbf{x}) = y_j(\mathbf{x})$

$$(\mathbf{w}_k - \mathbf{w}_j)^T \mathbf{x} + (w_{k0} - w_{j0}) = 0$$

Property of the Decision Regions

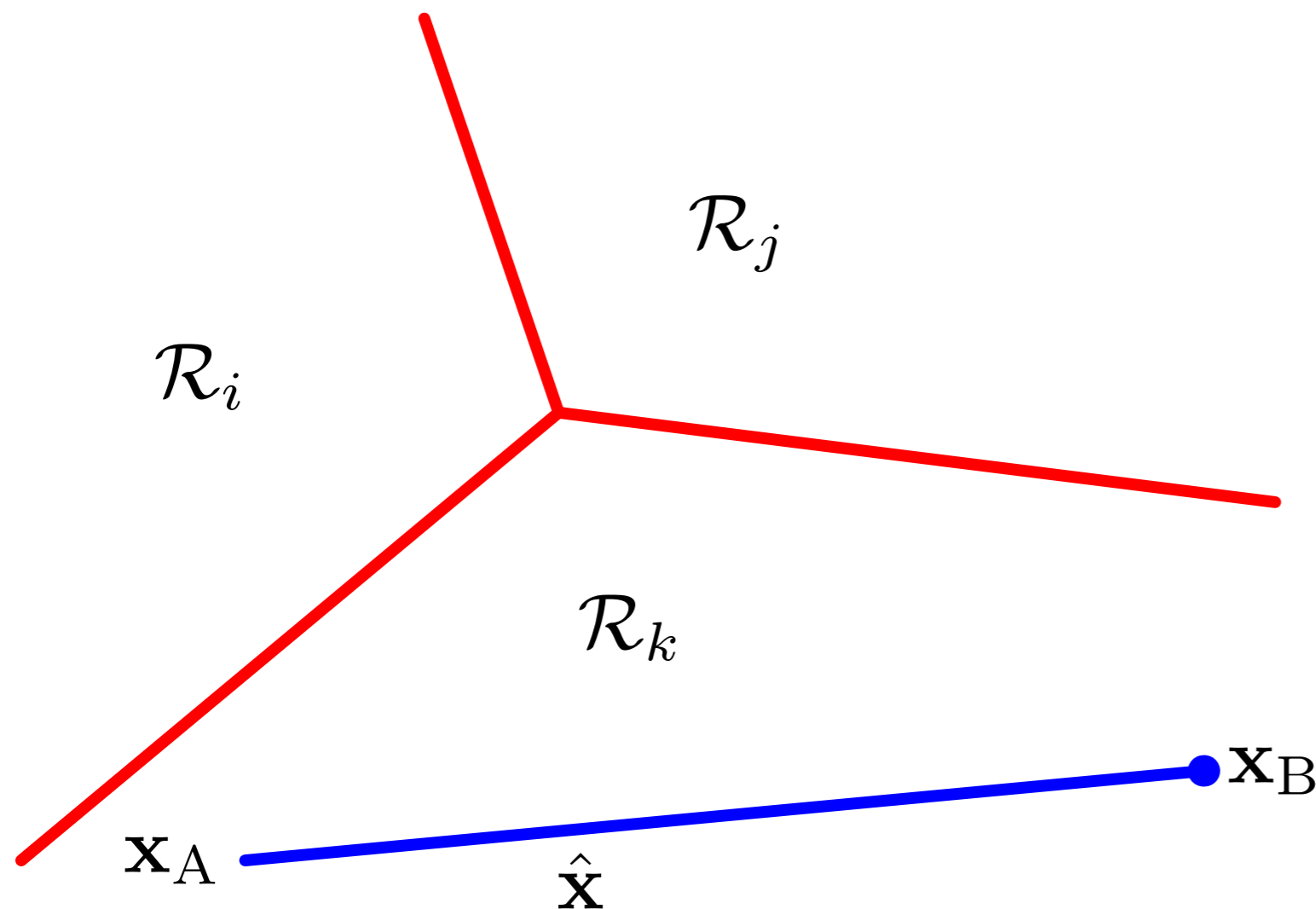
Theorem

The decision regions of the K -class discriminant $y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}$ are singly connected and convex.

Property of the Decision Regions

Theorem

The decision regions of the K -class discriminant $y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}$ are singly connected and convex.



If two points \mathbf{x}_A and \mathbf{x}_B both lie inside the same decision region \mathcal{R}_k , then any point \mathbf{x} that lies on the line connecting these two points must also lie in \mathcal{R}_k , and hence the decision region must be singly connected and convex.

Fisher's Linear Discriminant

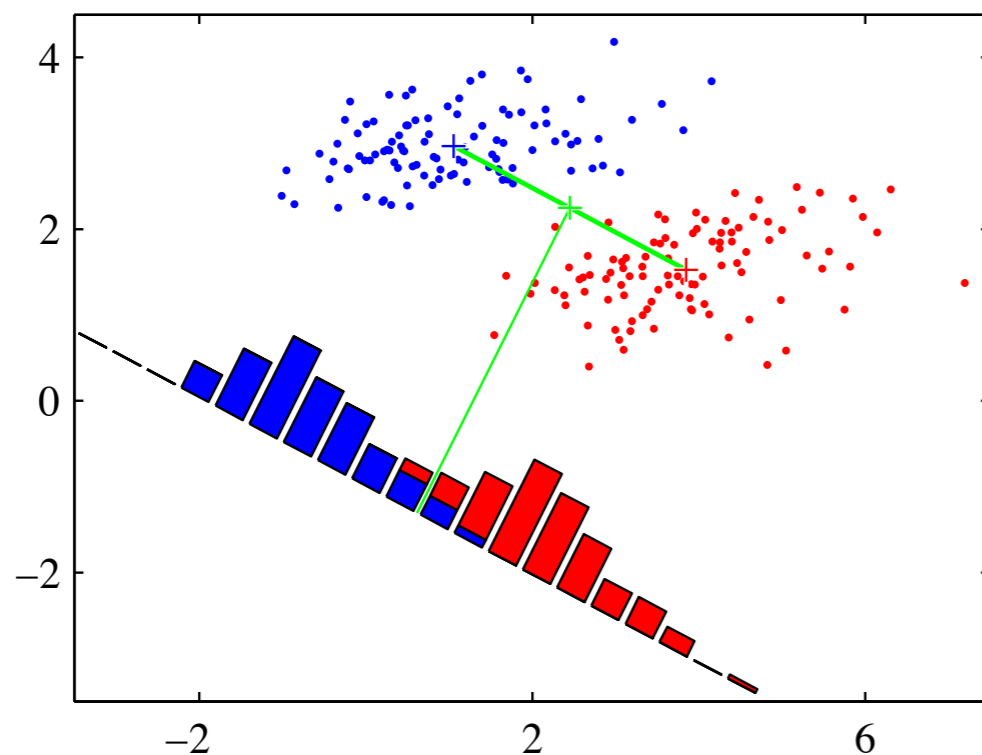
- Pursue the optimal linear projection on which the two classes can be maximally separated

$$y = \mathbf{w}^T \mathbf{x}$$

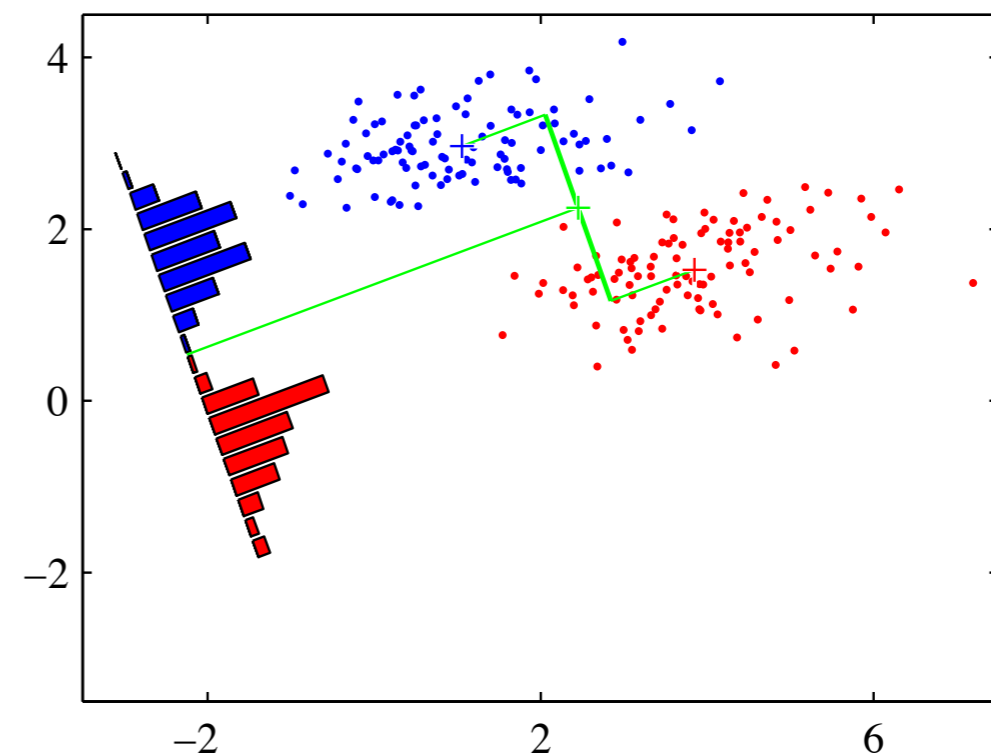
- The mean vectors of the two classes

$$\mathbf{m}_1 = \frac{1}{N_1} \sum_{n \in \mathcal{C}_1} \mathbf{x}_n, \quad \mathbf{m}_2 = \frac{1}{N_2} \sum_{n \in \mathcal{C}_2} \mathbf{x}_n$$

A way to view a linear classification model is in terms of dimensionality reduction.



Difference of means



Fisher's Linear Discriminant

What's a Good Projection?

- After projection, the two classes are separated as much as possible. Measured by the distance between projected center

$$\begin{aligned}\left(\mathbf{w}^T(\mathbf{m}_1 - \mathbf{m}_2)\right)^2 &= \mathbf{w}^T(\mathbf{m}_1 - \mathbf{m}_2)(\mathbf{m}_1 - \mathbf{m}_2)^T\mathbf{w} \\ &= \mathbf{w}^T\mathbf{S}_B\mathbf{w}\end{aligned}$$

where $\mathbf{S}_B = (\mathbf{m}_1 - \mathbf{m}_2)(\mathbf{m}_1 - \mathbf{m}_2)^T$ is called **between-class** covariance matrix.

- After projection, the variances of the two classes are as small as possible. Measured by the within-class covariance

where

$$\mathbf{w}^T\mathbf{S}_W\mathbf{w}$$

$$\mathbf{S}_W = \sum_{n \in \mathcal{C}_1} (\mathbf{x}_n - \mathbf{m}_1)(\mathbf{x}_n - \mathbf{m}_1)^T + \sum_{n \in \mathcal{C}_2} (\mathbf{x}_n - \mathbf{m}_2)(\mathbf{x}_n - \mathbf{m}_2)^T$$

Fisher's Linear Discriminant

- Fisher criterion: maximize the ratio w.r.t. \mathbf{w}

$$J(\mathbf{w}) = \frac{\text{Between-class variance}}{\text{Within-class variance}} = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}$$

- Recall the quotient rule: for $f(x) = \frac{g(x)}{h(x)}$

$$f'(x) = \frac{g'(x)h(x) - g(x)h'(x)}{h^2(x)}$$

- Setting $\nabla J(\mathbf{w}) = 0$, we obtain

$$(\mathbf{w}^T \mathbf{S}_B \mathbf{w}) \mathbf{S}_W \mathbf{w} = (\mathbf{w}^T \mathbf{S}_W \mathbf{w}) \mathbf{S}_B \mathbf{w}$$

$$(\mathbf{w}^T \mathbf{S}_B \mathbf{w}) \mathbf{S}_W \mathbf{w} = (\mathbf{w}^T \mathbf{S}_W \mathbf{w}) (\mathbf{m}_2 - \mathbf{m}_1) \left((\mathbf{m}_2 - \mathbf{m}_1)^T \mathbf{w} \right)$$

- Terms $\mathbf{w}^T \mathbf{S}_B \mathbf{w}$, $\mathbf{w}^T \mathbf{S}_W \mathbf{w}$ and $(\mathbf{m}_2 - \mathbf{m}_1)^T \mathbf{w}$ are scalars, and we only care about directions. So the scalars are dropped. Therefore

$$\mathbf{w} \propto \mathbf{S}_W^{-1} (\mathbf{m}_2 - \mathbf{m}_1)$$

From Fisher's Linear Discriminant to Classifiers

- Fisher's Linear Discriminant is not a classifier; it only decides on an optimal projection to convert high-dimensional classification problem to 1D.
- A bias (threshold) is needed to form a linear classifier (multiple thresholds lead to nonlinear classifiers). The final classifier has the form

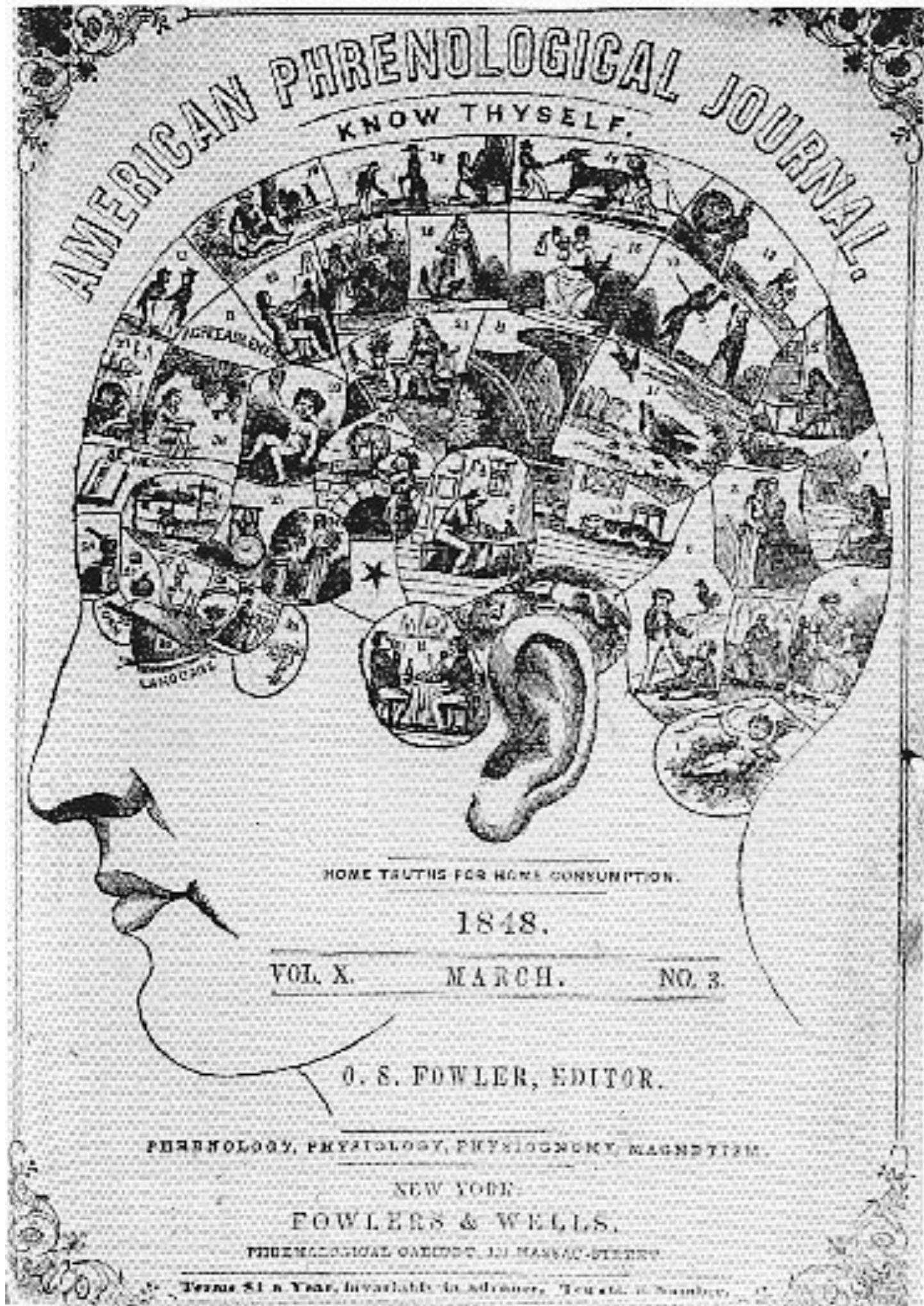
$$y(\mathbf{x}) = \text{sign}(\mathbf{w}^T \mathbf{x} + w_0)$$

where the nonlinear activation function $\text{sign}(\cdot)$ is a step function

$$\text{sign}(a) = \begin{cases} +1, & a \geq 0 \\ -1, & a < 0 \end{cases}$$

- How to decide the bias w_0 ?

Perceptron



early theories
of the brain

Biology and Learning

- Basic Idea

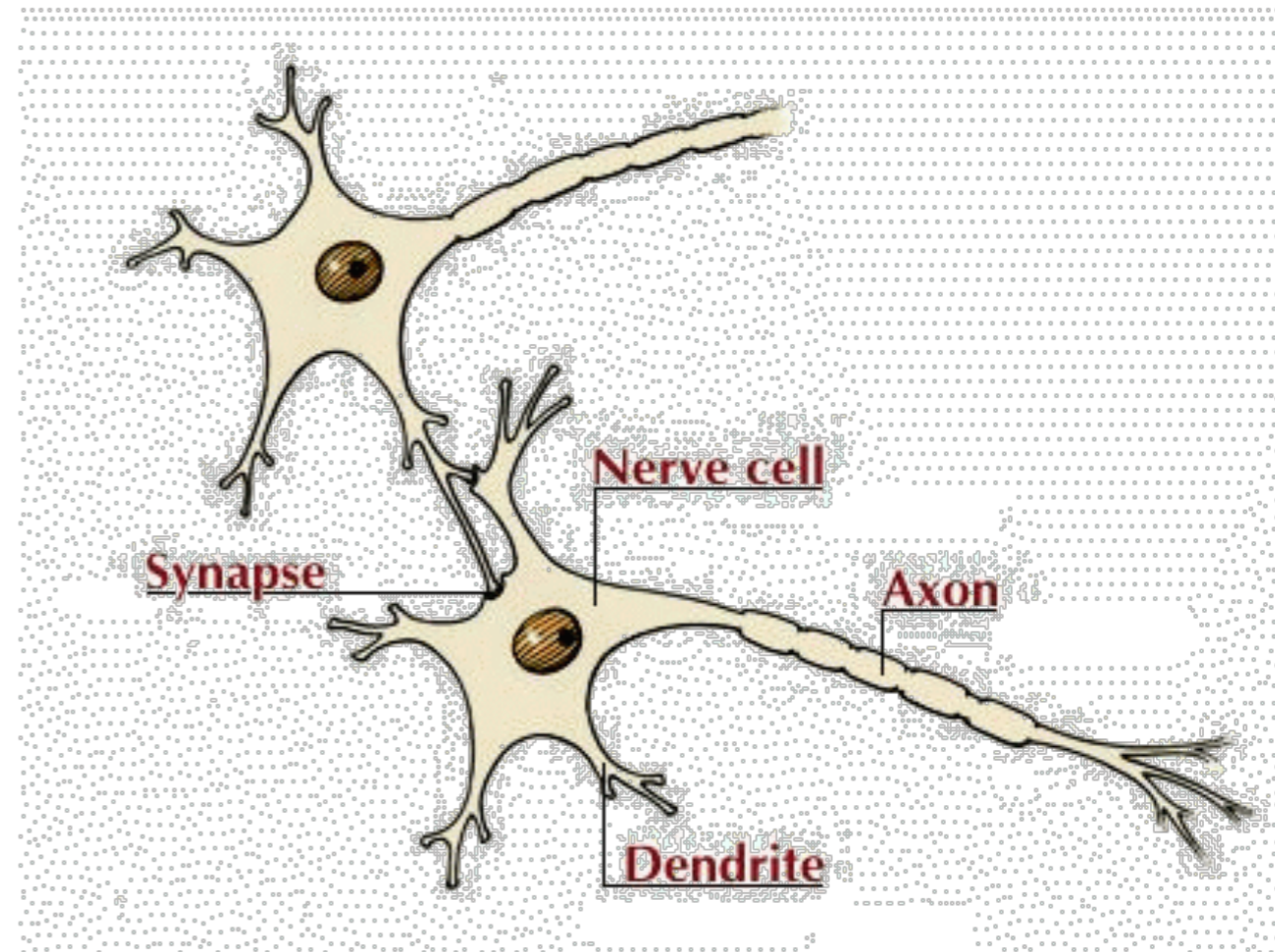
- Good behavior should be rewarded, bad behavior punished (or not rewarded). This improves system fitness.
- Killing a sabertooth tiger should be rewarded ...
- Correlated events should be combined.
- Pavlov's salivating dog.

- Training mechanisms

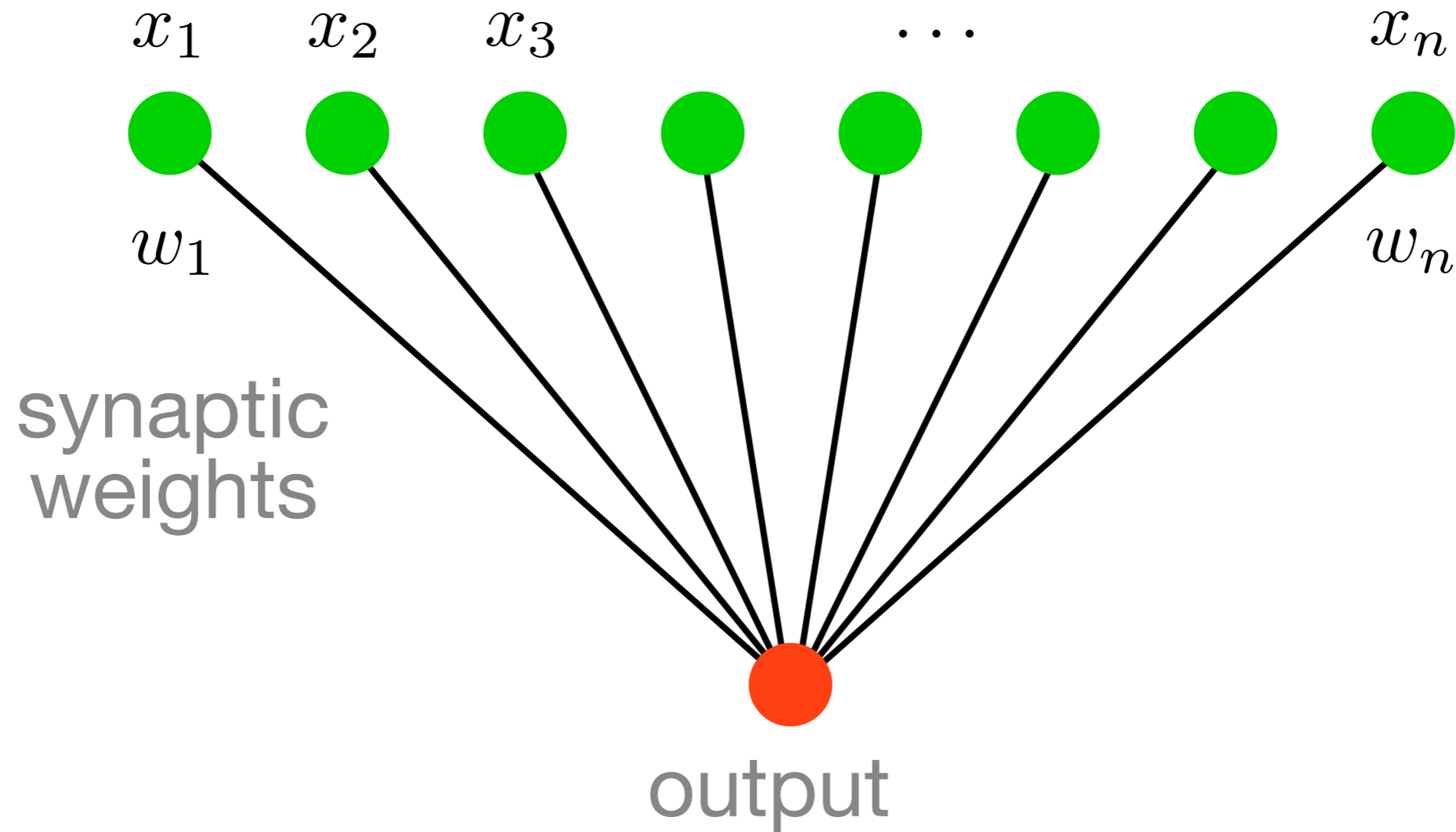
- Behavioral modification of individuals (learning)
Successful behavior is rewarded (e.g. food).
- Hard-coded behavior in the genes (instinct)
The wrongly coded animal does not reproduce.

Neurons

- Soma (CPU)
Cell body - combines signals
- Dendrite (input bus)
Combines the inputs from several other nerve cells
- Synapse (interface)
Interface and **parameter store** between neurons
- Axon (cable)
May be up to 1m long and will transport the activation signal to neurons at different locations



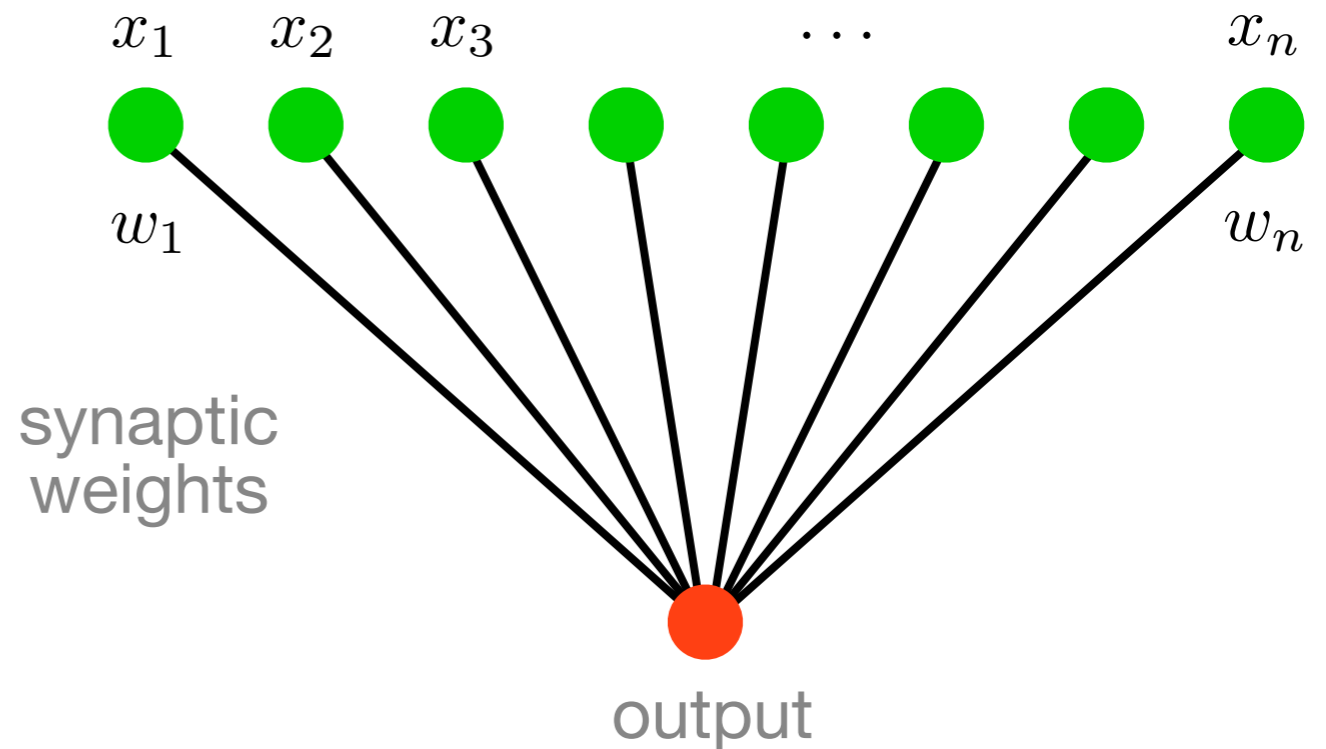
Neurons



$$f(x) = \sum_i w_i x_i = \langle w, x \rangle$$

Perceptron

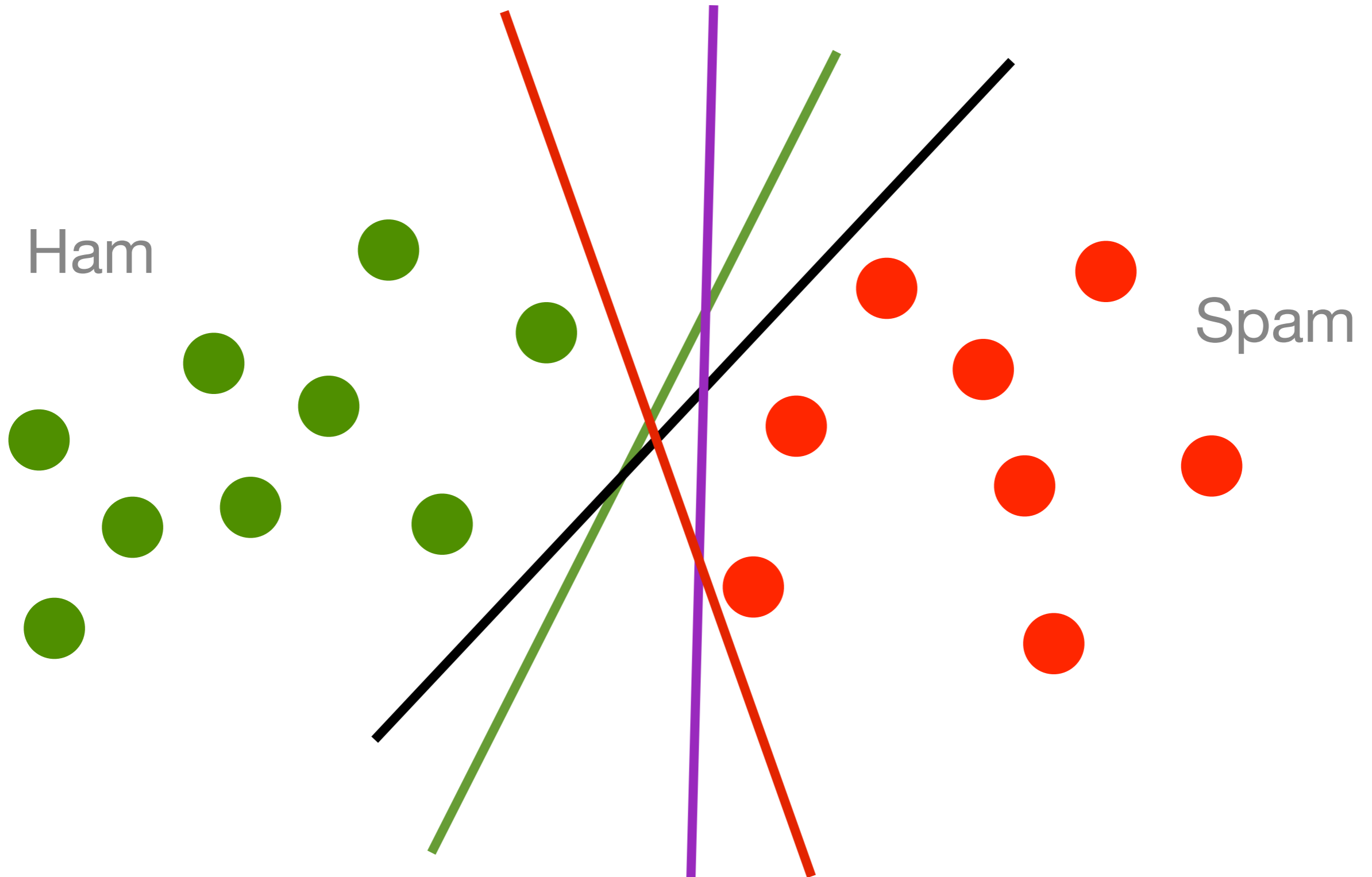
- Weighted linear combination
- Nonlinear decision function
- Linear offset (bias)

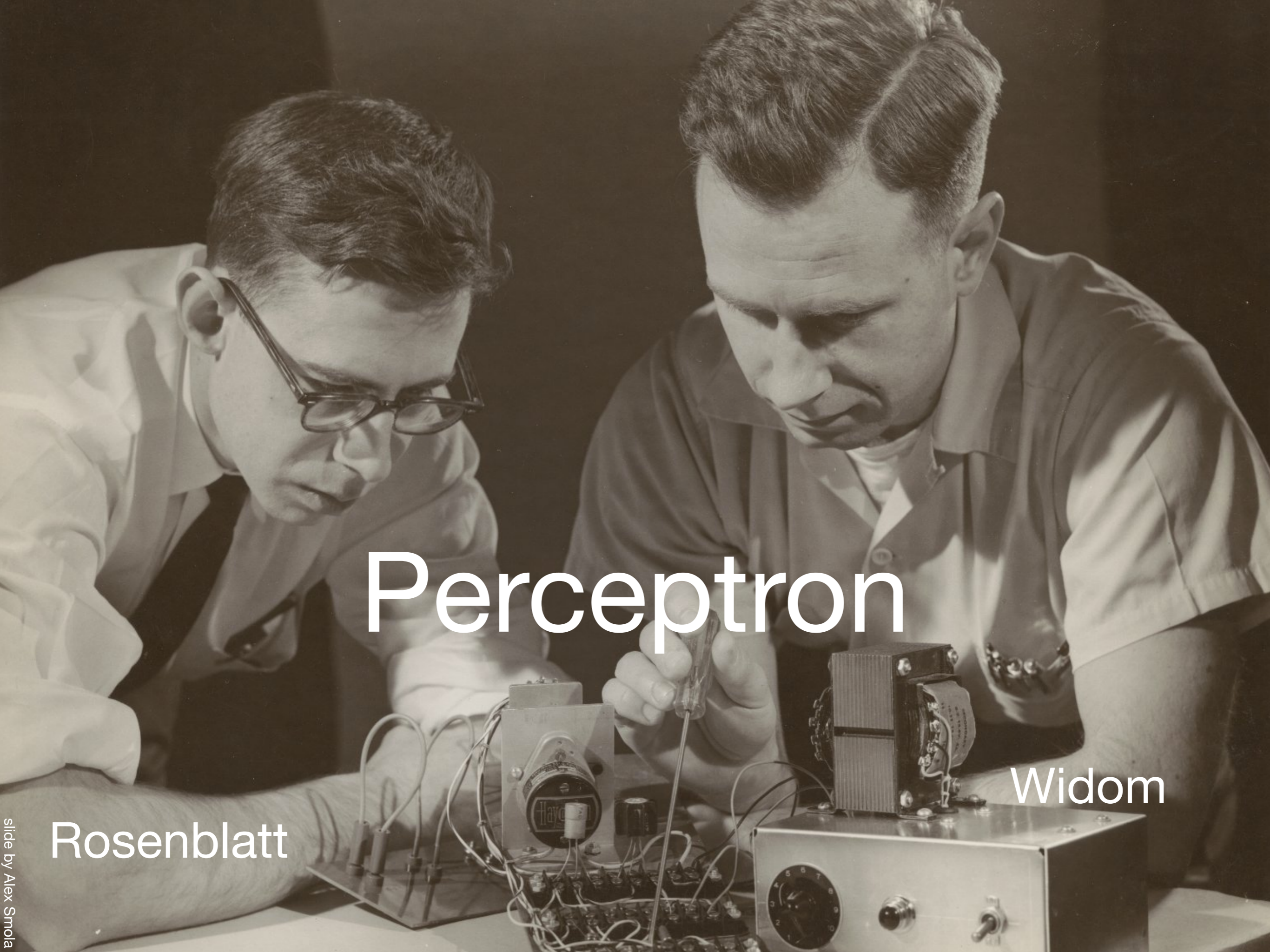


$$f(x) = \sigma(\langle w, x \rangle + b)$$

- Linear separating hyperplanes
(spam/ham, novel/typical, click/no click)
- **Learning**
Estimating the parameters w and b

Perceptron





Perceptron

Rosenblatt

Widom

The Perceptron

initialize $w = 0$ and $b = 0$

repeat

if $y_i [\langle w, x_i \rangle + b] \leq 0$ **then**

$w \leftarrow w + y_i x_i$ and $b \leftarrow b + y_i$

end if

until all classified correctly

- Nothing happens if classified correctly

- Weight vector is linear combination $w = \sum_{i \in I} y_i x_i$

- Classifier is linear combination of

inner products $f(x) = \sum_{i \in I} y_i \langle x_i, x \rangle + b$

Convergence Theorem

- If there exists some (w^*, b^*) with unit length and
$$y_i [\langle x_i, w^* \rangle + b^*] \geq \rho \text{ for all } i$$

then the perceptron converges to a linear separator after a number of steps bounded by

$$\left(b^{*2} + 1 \right) \left(r^2 + 1 \right) \rho^{-2} \text{ where } \|x_i\| \leq r$$

- Dimensionality independent
- Order independent (i.e. also worst case)
- Scales with ‘difficulty’ of problem

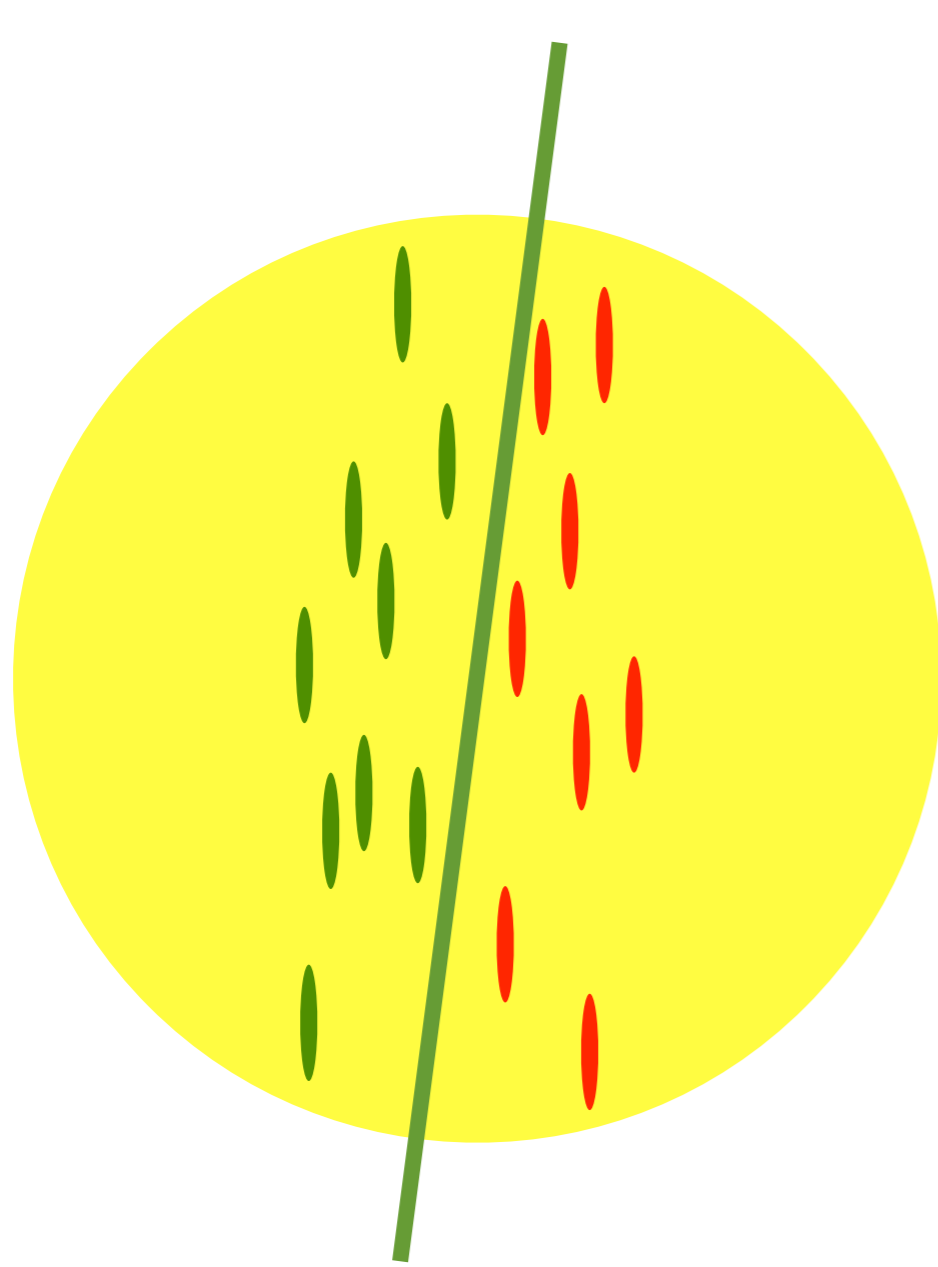
Consequences

- Only need to store errors.
This gives a compression bound for perceptron.
- Stochastic gradient descent on hinge loss
$$l(x_i, y_i, w, b) = \max(0, 1 - y_i [\langle w, x_i \rangle + b])$$
- **Fails with noisy data**

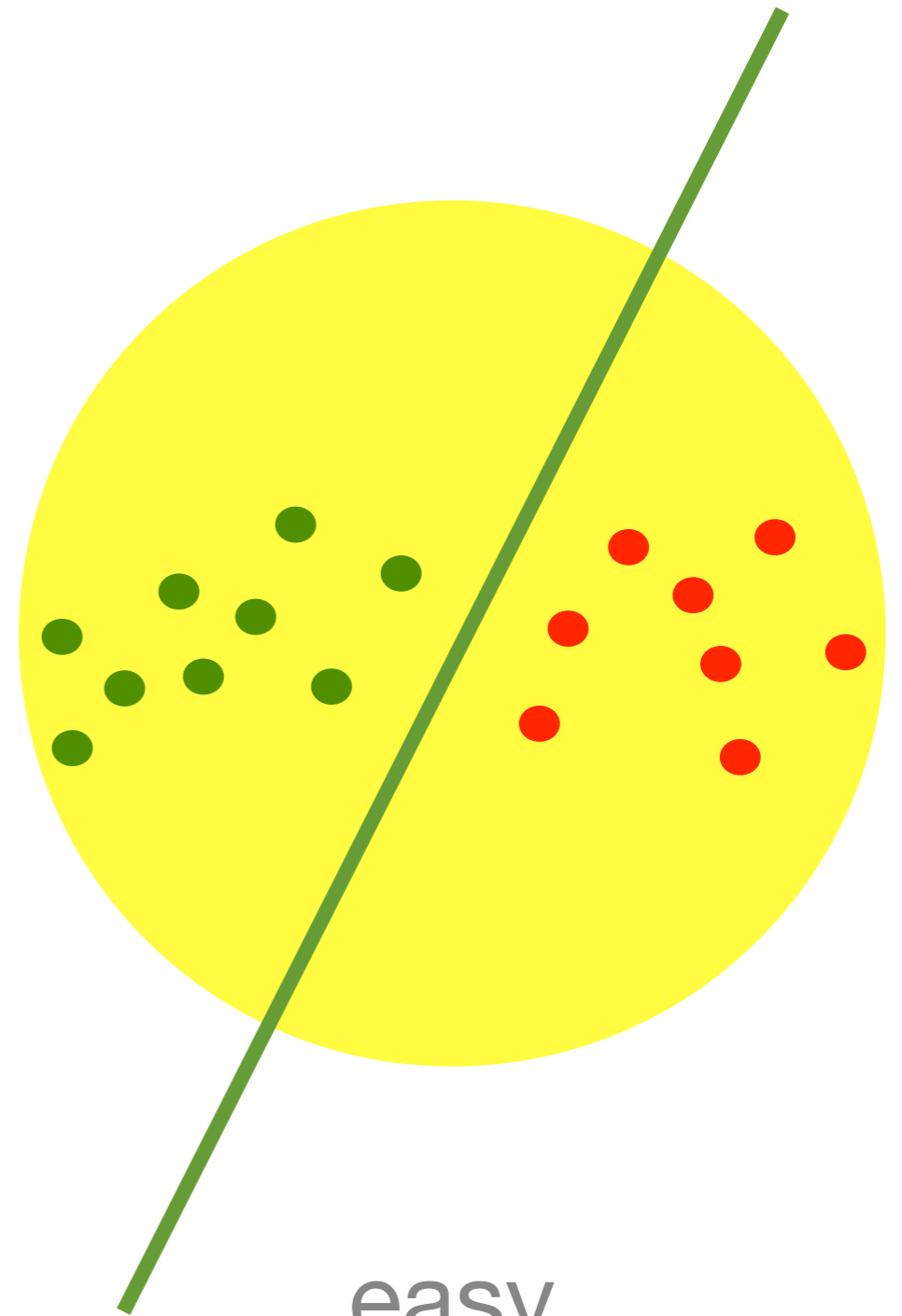
do NOT train your avatar with perceptrons



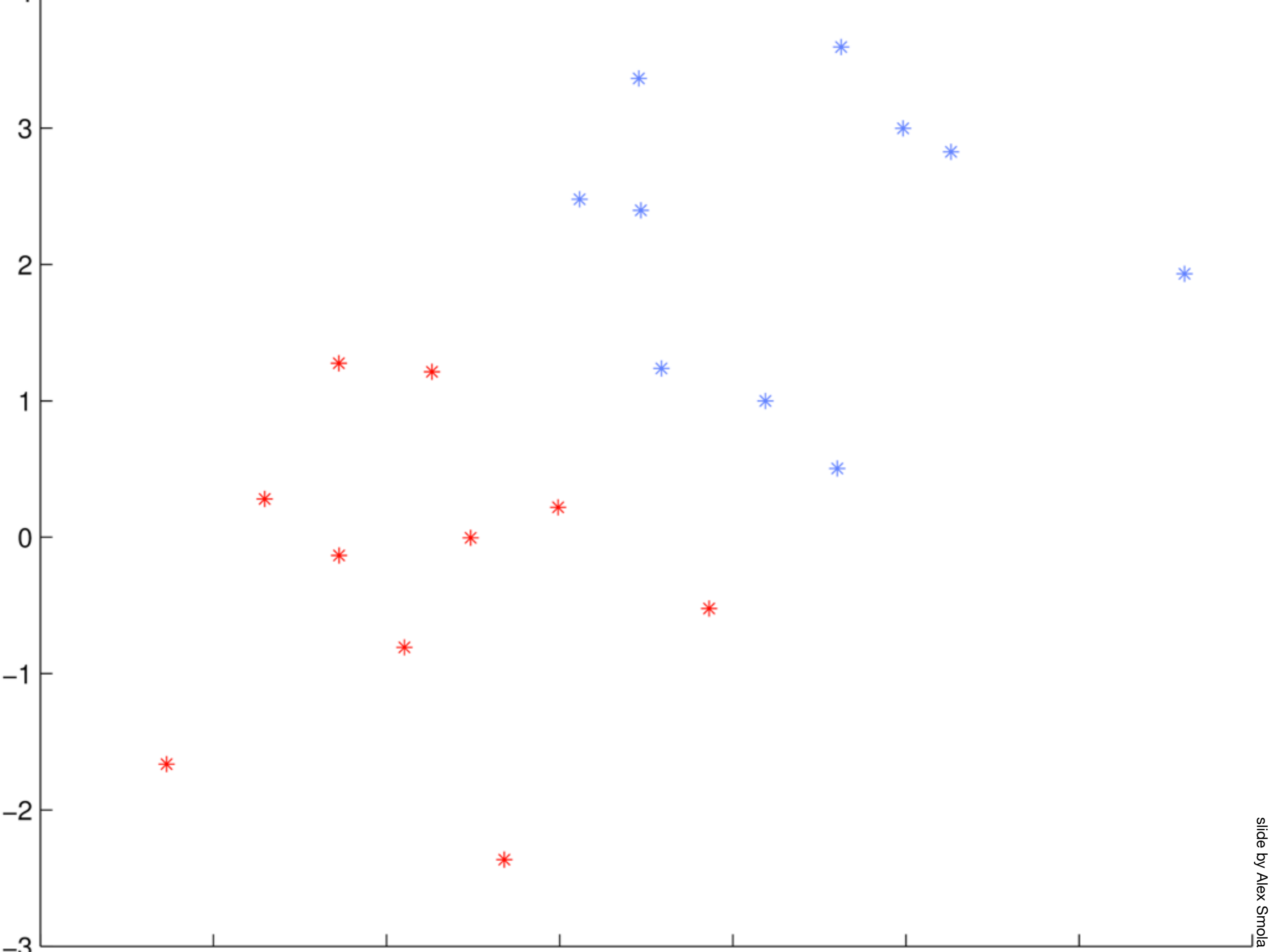
Hardness: margin vs. size

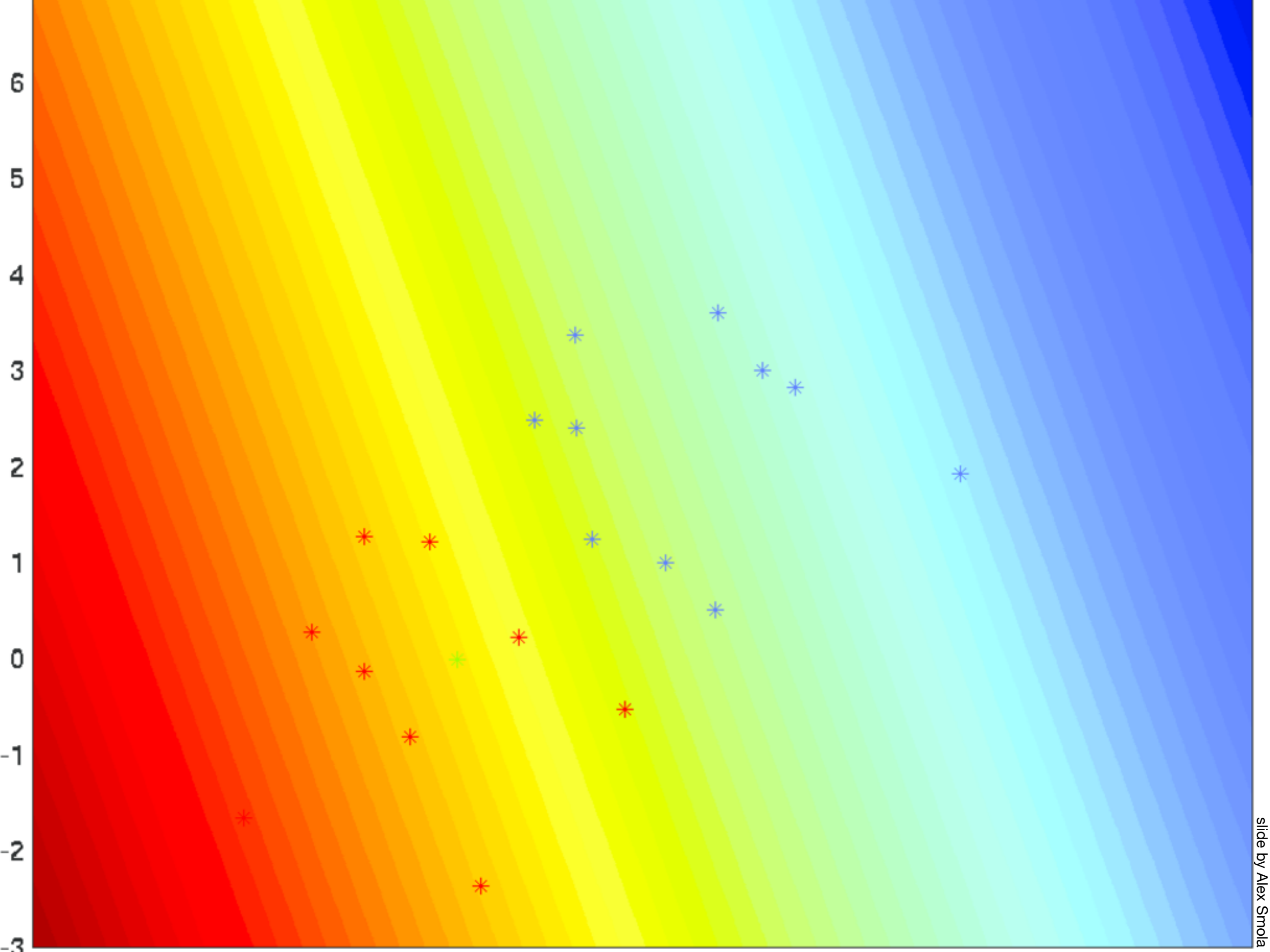


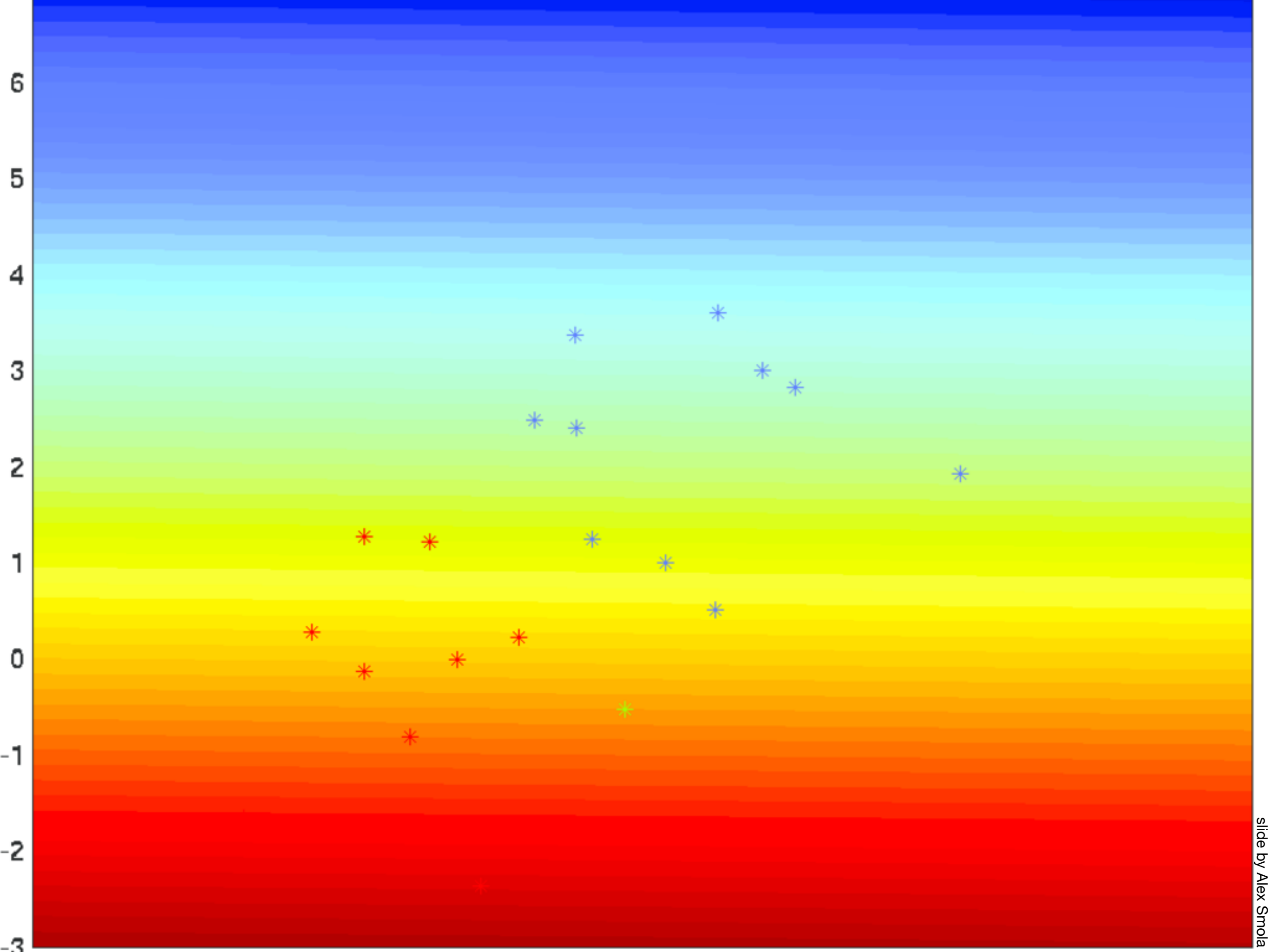
hard

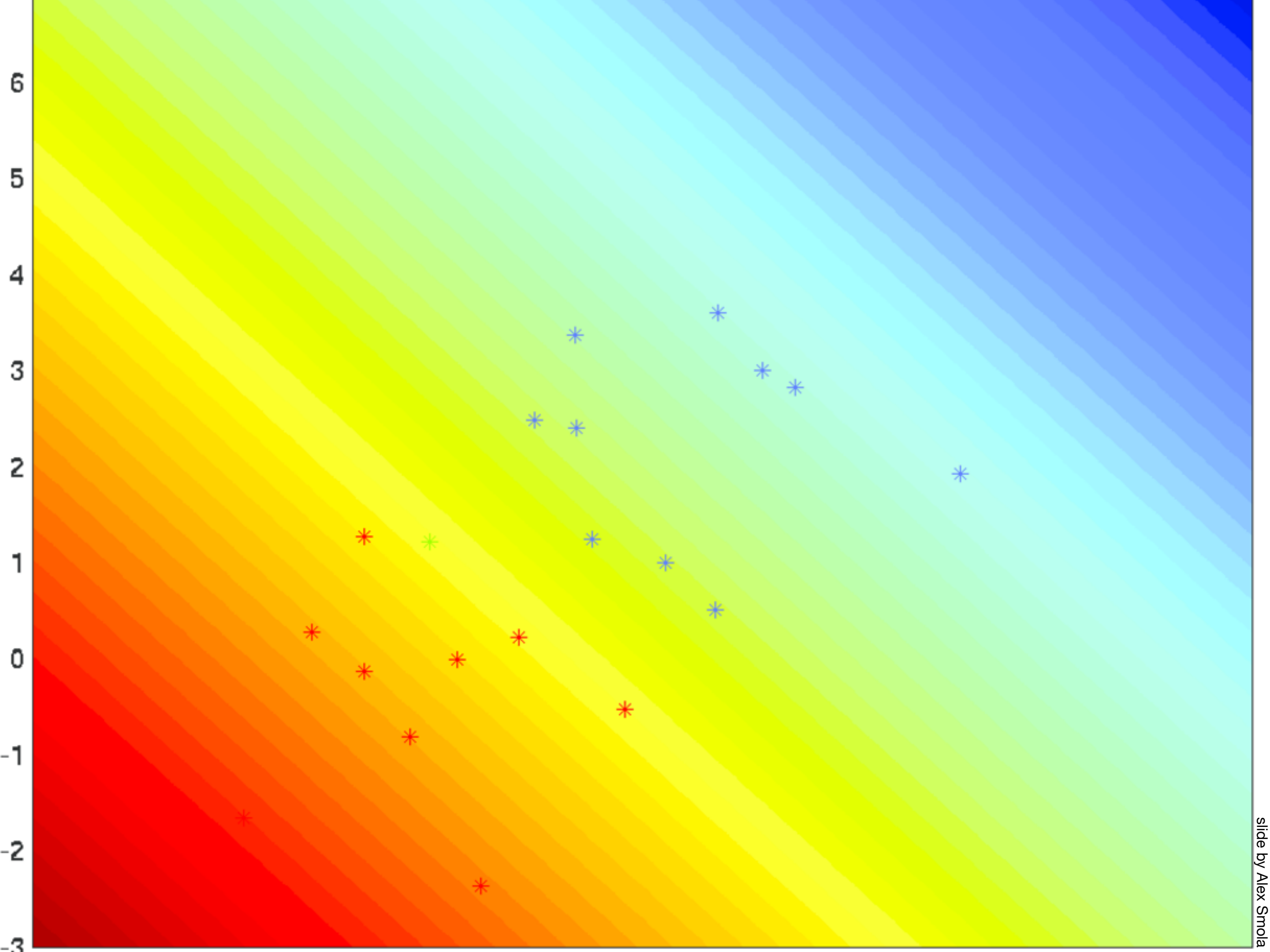


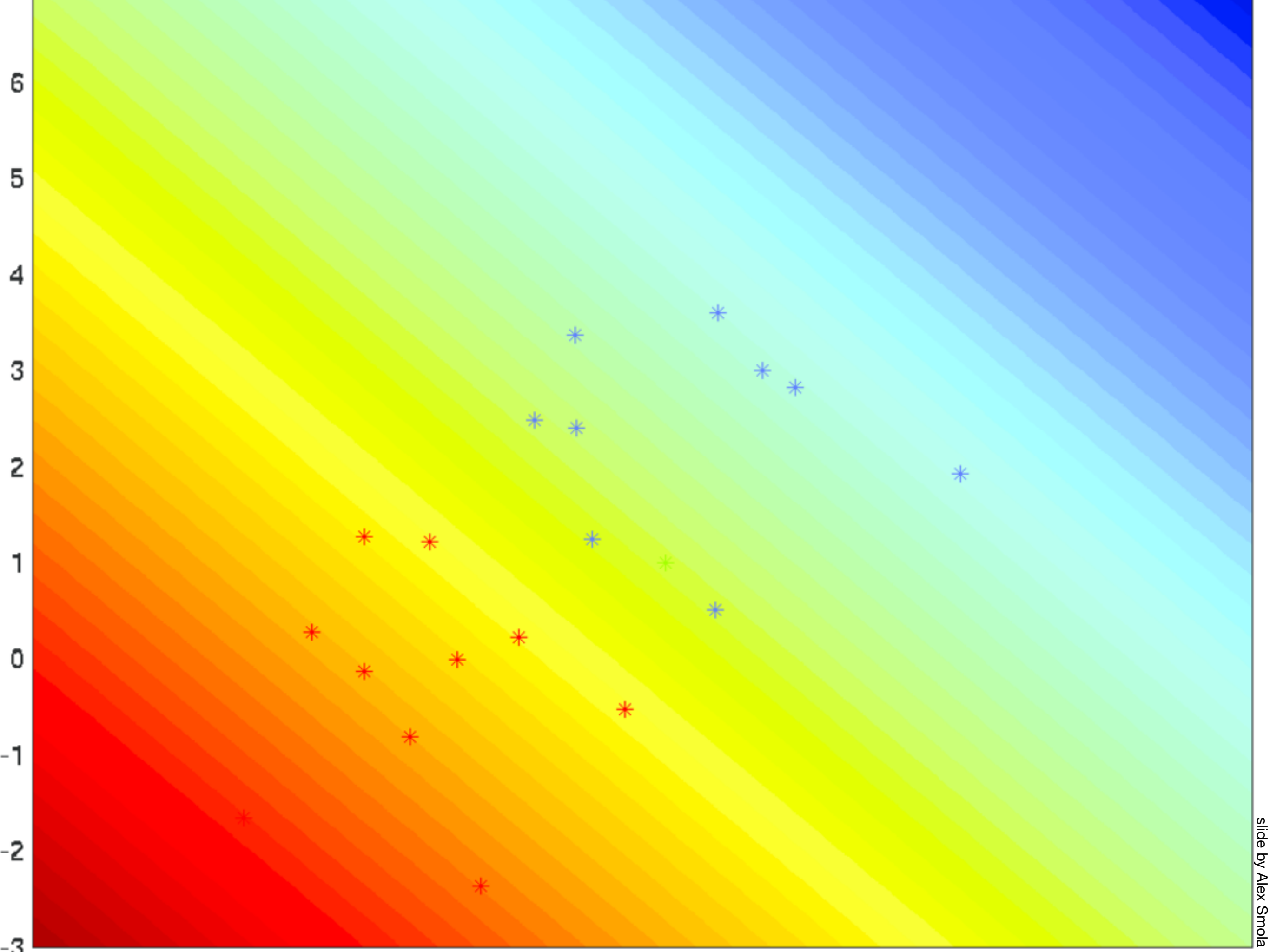
easy

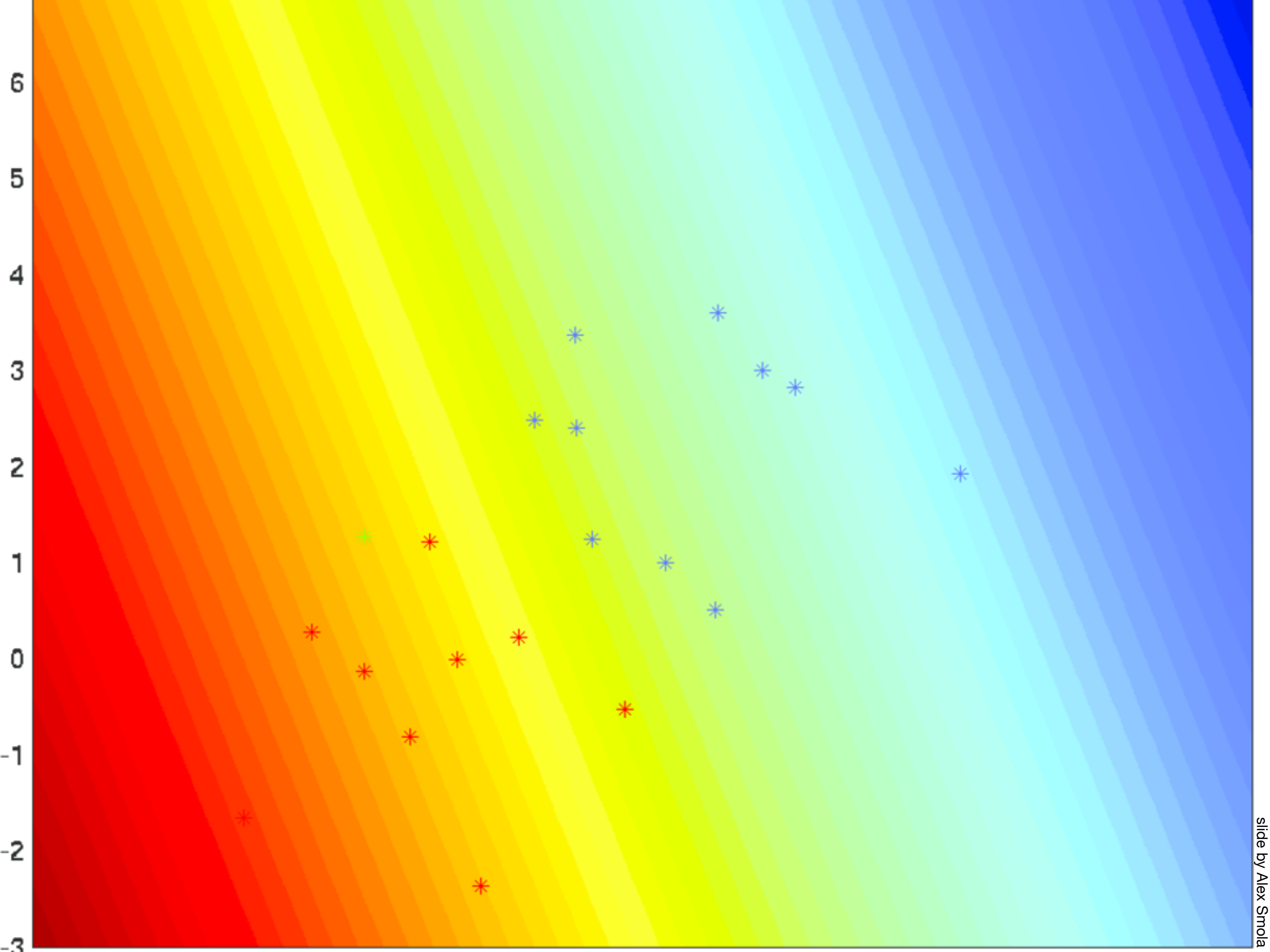


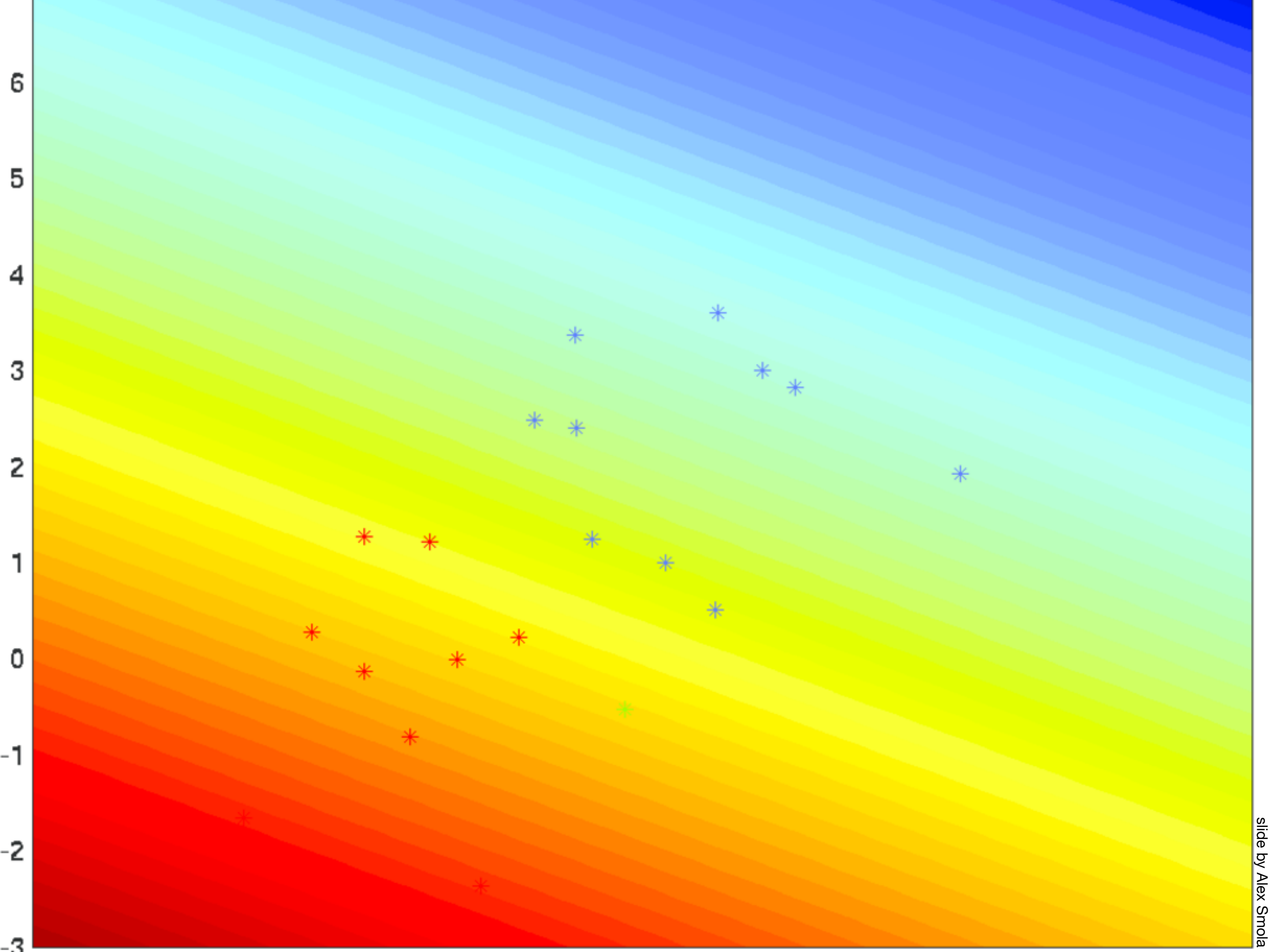


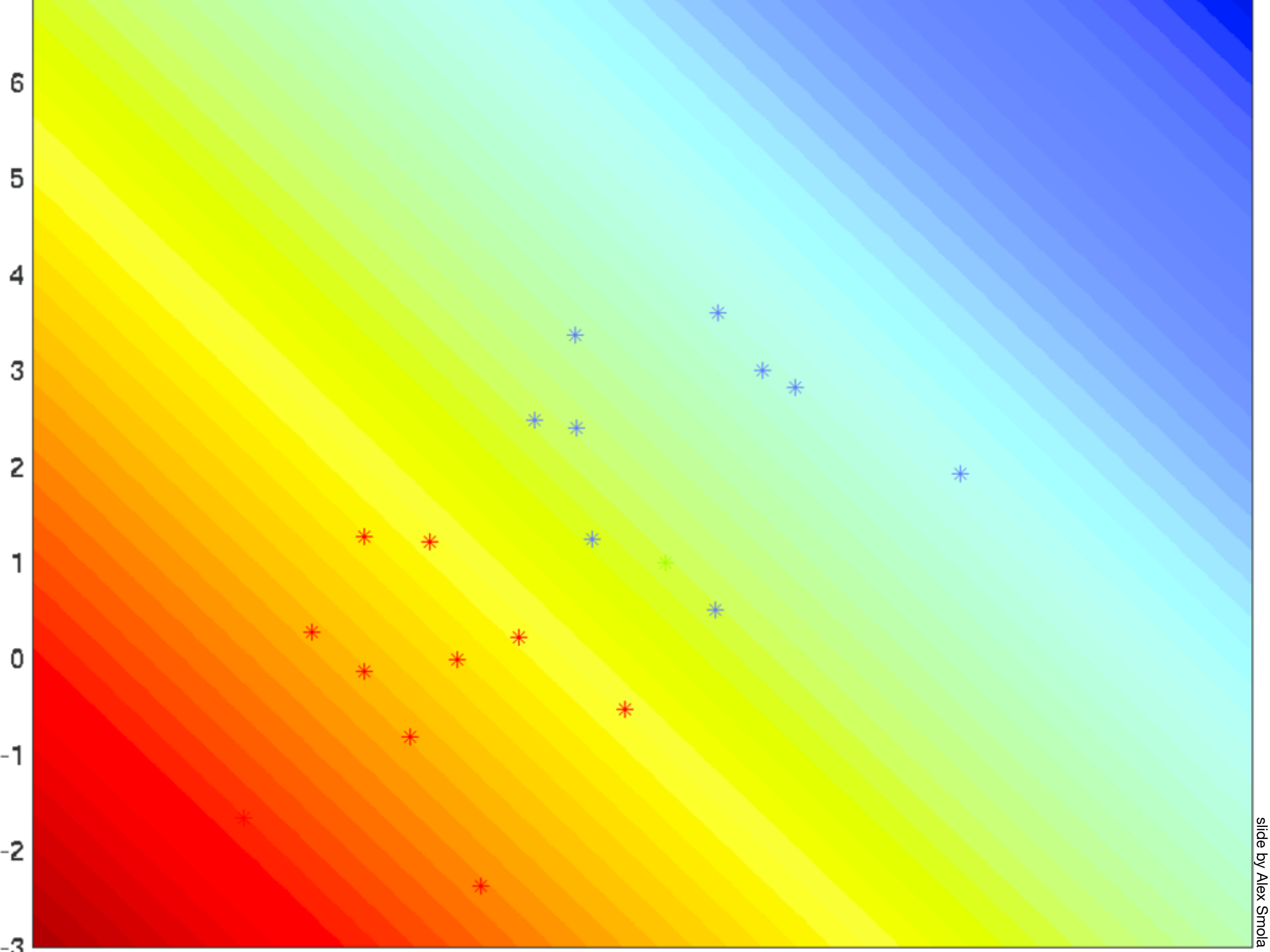


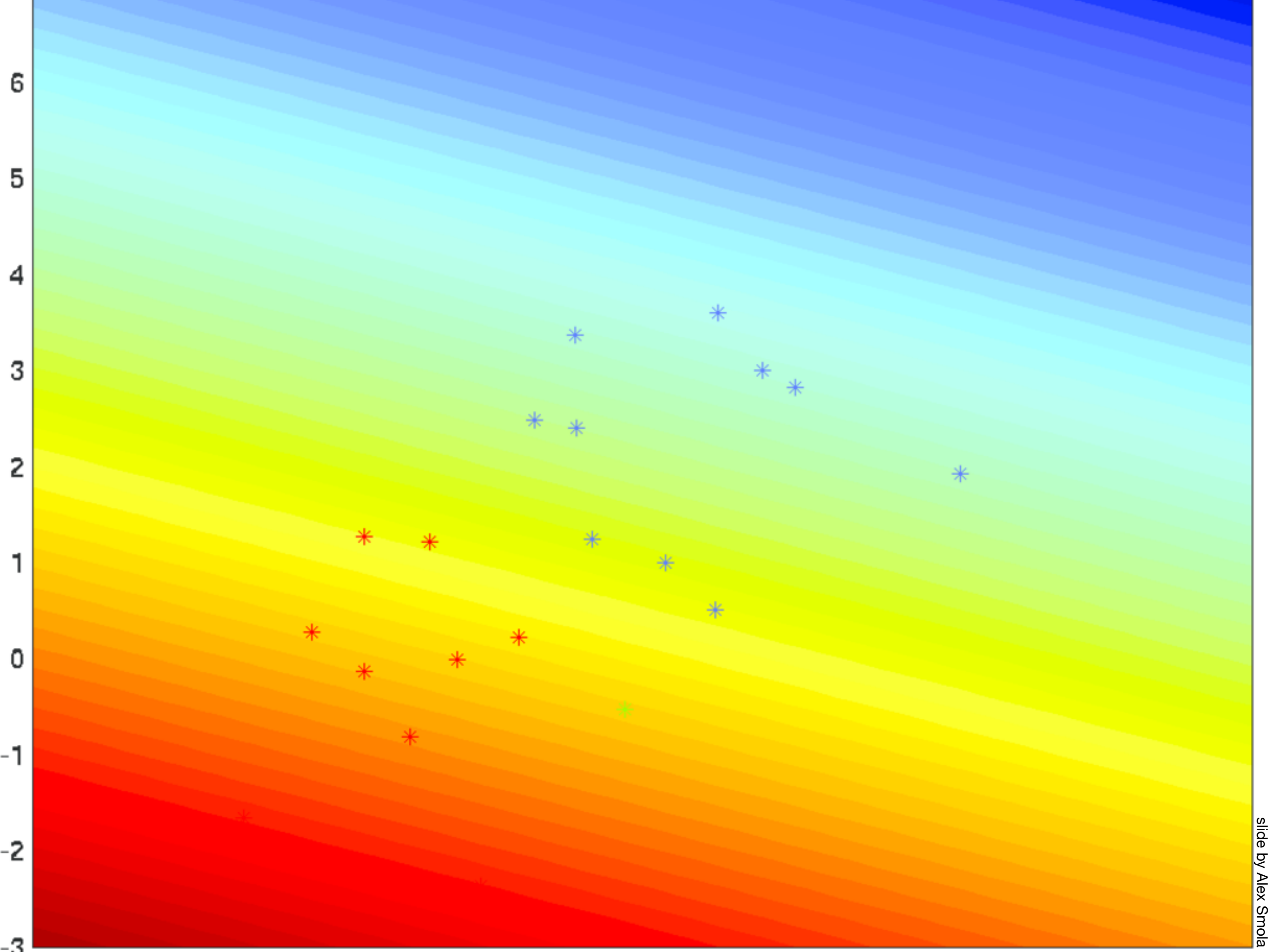


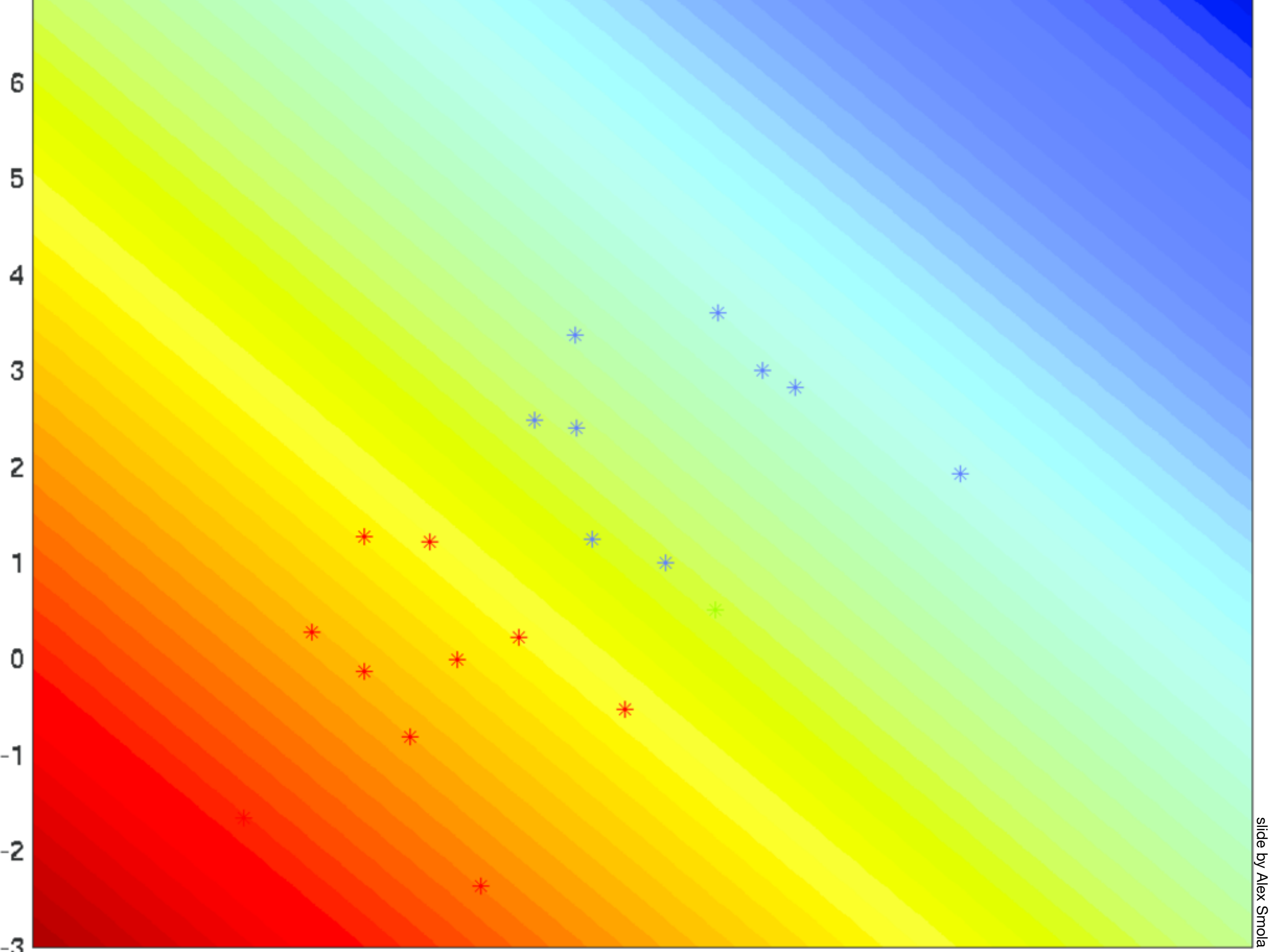


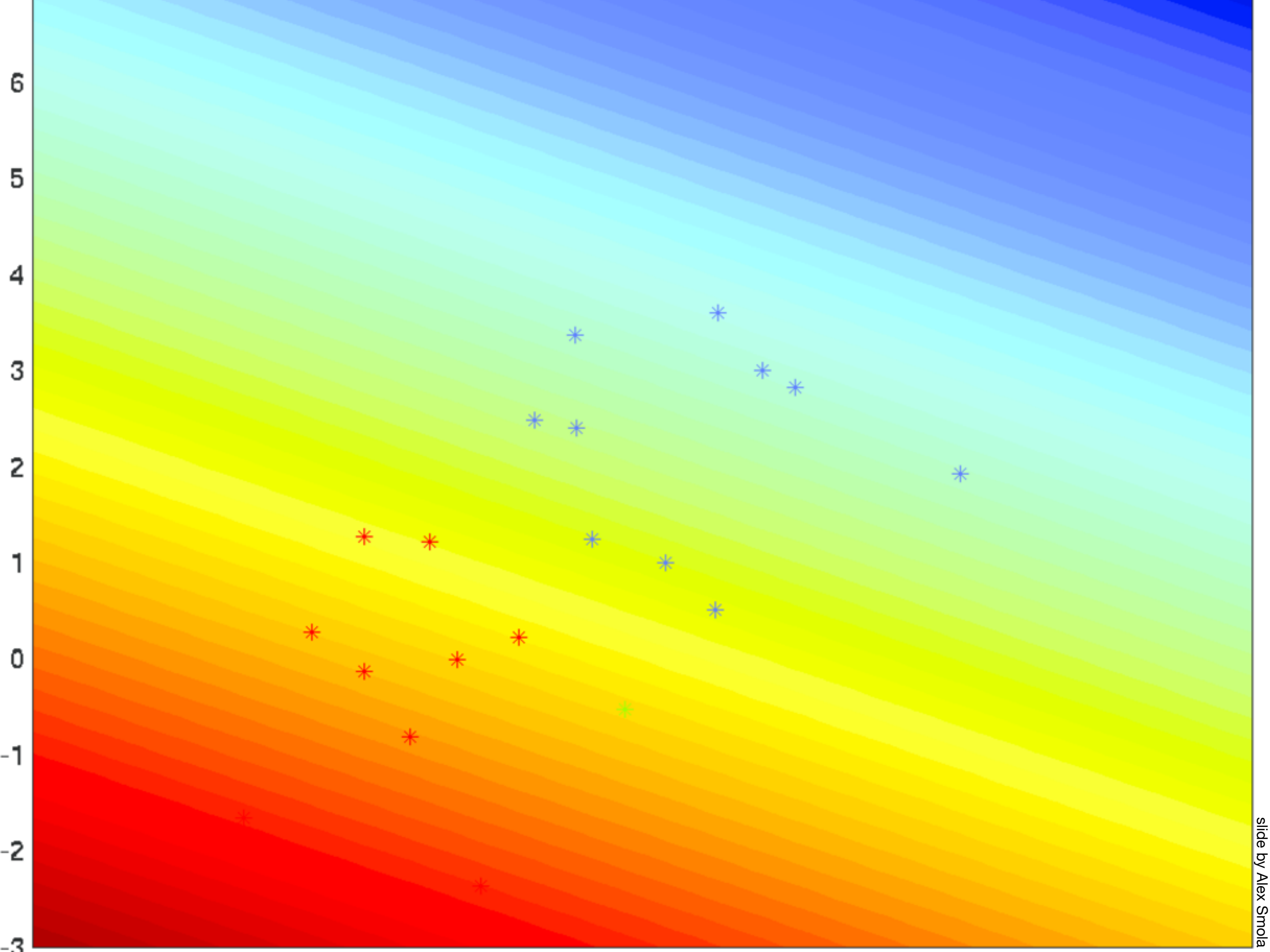


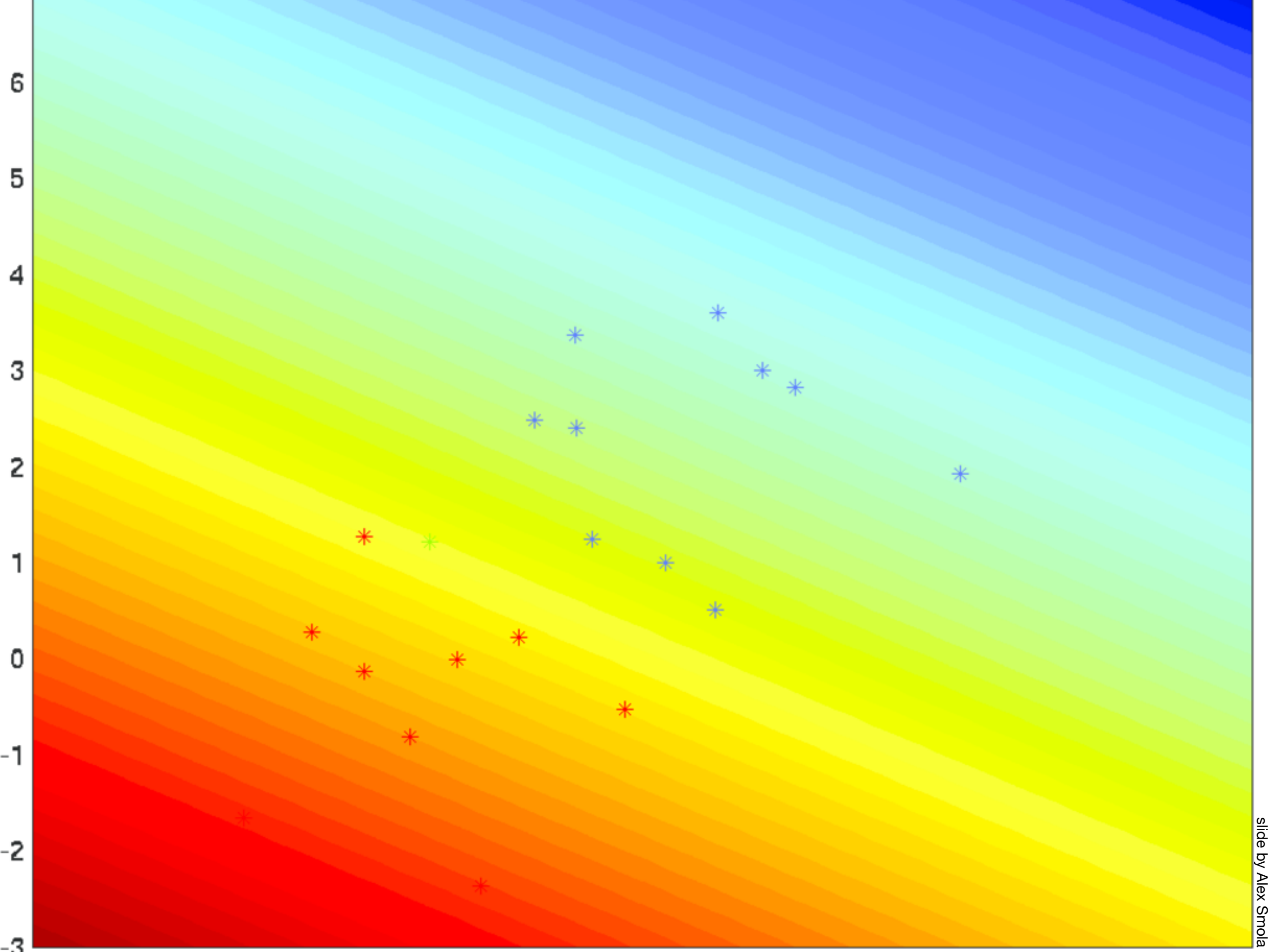






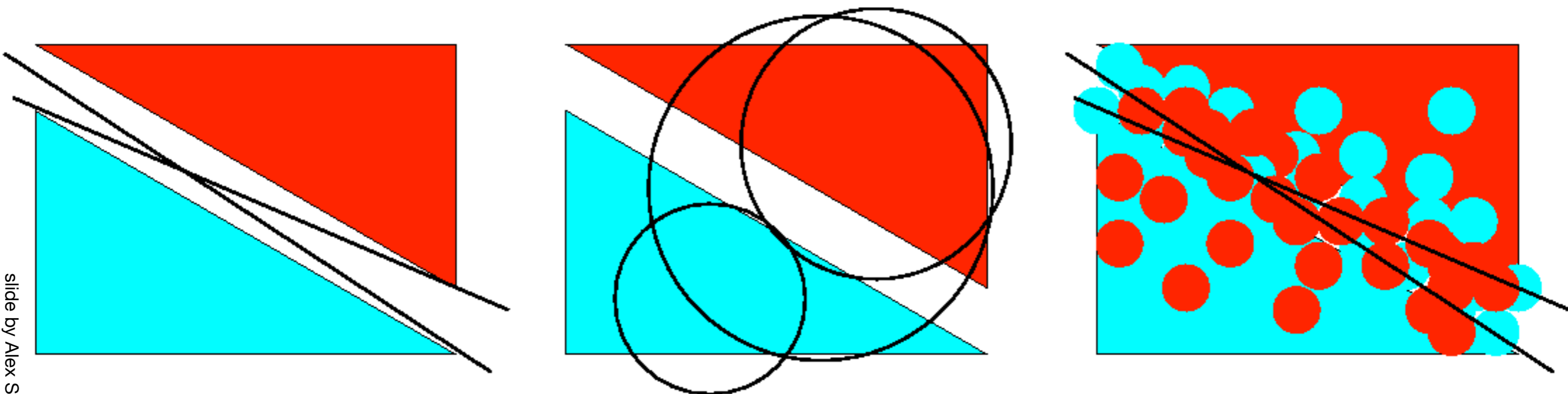




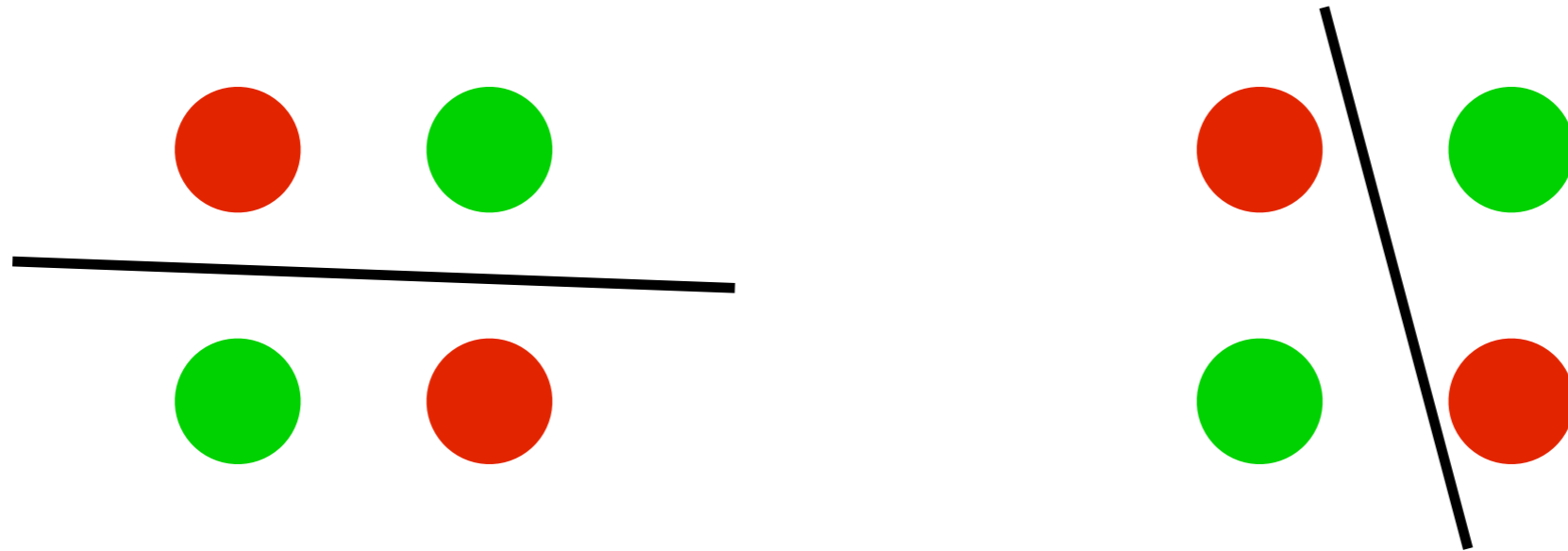


Concepts & version space

- Realizable concepts
 - Some function exists that can separate data and is included in the concept space
 - For perceptron - data is linearly separable
- Unrealizable concept
 - Data not separable
 - We don't have a suitable function class (often hard to distinguish)



Minimum error separation



- XOR - not linearly separable
- Nonlinear separation is trivial
- Caveat (Minsky & Papert)

Finding the minimum error linear separator
is NP hard (this killed Neural Networks in the 70s).

Nonlinear Features

- Regression

We got nonlinear functions by preprocessing

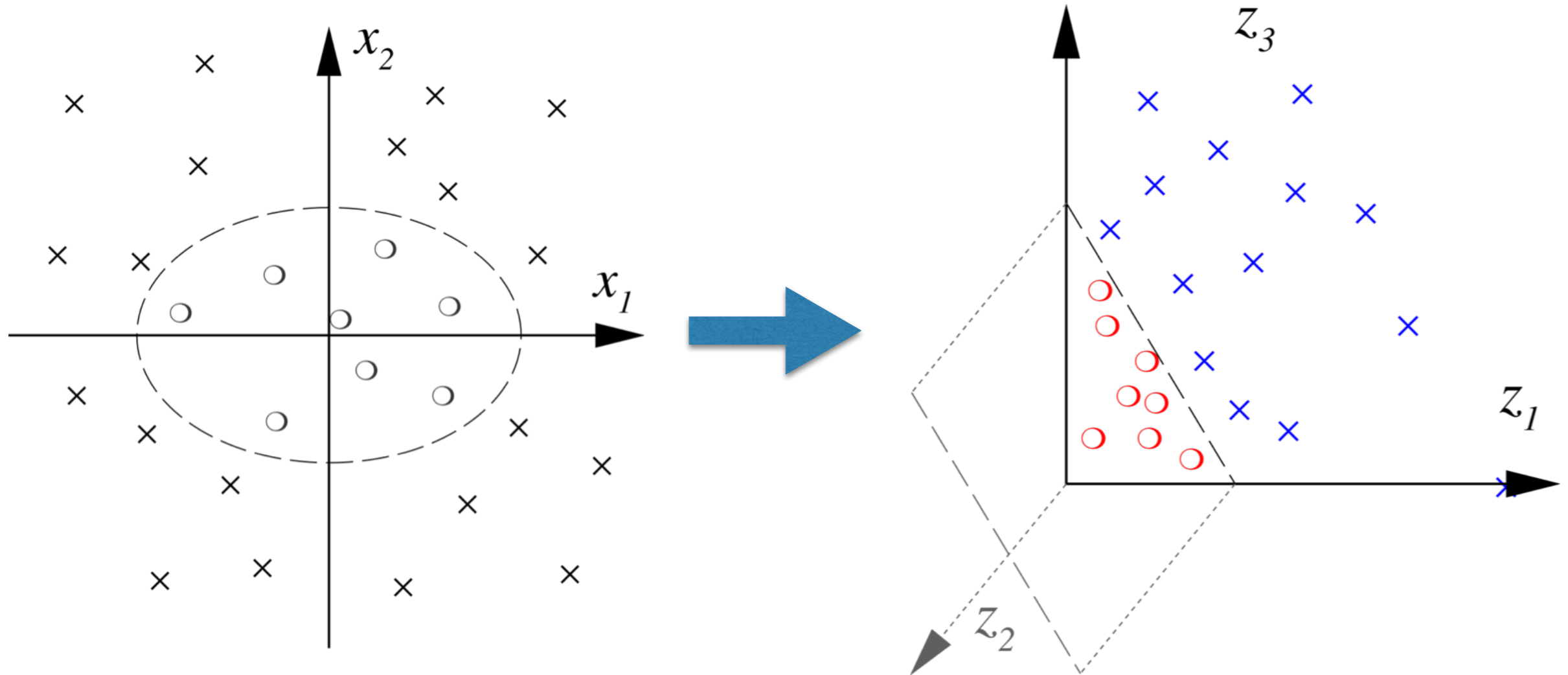
- Perceptron

- Map data into feature space $x \rightarrow \phi(x)$
- Solve problem in this space
- Query replace $\langle x, x' \rangle$ by $\langle \phi(x), \phi(x') \rangle$ for code

- Feature Perceptron

- Solution in span of $\phi(x_i)$

Quadratic Features



- Separating surfaces are
Circles, hyperbolae, parabolae

Constructing Features (very naive OCR system)

	1	2	3	4	5	6	7	8	9	0
Loops	0	0	0	1	0	1	0	2	1	1
3 Joints	0	0	0	0	0	1	0	0	1	0
4 Joints	0	0	0	1	0	0	0	1	0	0
Angles	0	1	1	1	1	0	1	0	0	0
Ink	1	2	2	2	2	2	1	3	2	2

Feature Engineering for Spam Filtering

- bag of words
- pairs of words
- date & time
- recipient path
- IP number
- sender
- encoding
- links
- ... secret sauce ...

Delivered-To: alex.smola@gmail.com
Received: by 10.216.47.73 with SMTP id s51cs361171web;
Tue, 3 Jan 2012 14:17:53 -0800 (PST)
Received: by 10.213.17.145 with SMTP id s17mr2519891eba.147.1325629071725;
Tue, 03 Jan 2012 14:17:51 -0800 (PST)
Return-Path: <alex+caf_alex.smola@gmail.com@smola.org>
Received: from mail-ey0-f175.google.com (mail-ey0-f175.google.com [209.85.215.175])
by mx.google.com with ESMTPS id n4si29264232eef.57.2012.01.03.14.17.51
(version=TLSv1/SSLv3 cipher=OTHER);
Tue, 03 Jan 2012 14:17:51 -0800 (PST)
Received-SPF: neutral (google.com: 209.85.215.175 is neither permitted nor denied by best
guess record for domain of alex+caf_alex.smola@gmail.com@smola.org) client-
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Authentication-Results: mx.google.com; spf=neutral (google.com: 209.85.215.175 is neither
permitted nor denied by best guess record for domain of
alex+caf_alex.smola@gmail.com@smola.org)
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for <alex.smola@gmail.com>; Tue, 03 Jan 2012 14:17:51 -0800 (PST)
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for <alex@smola.org>; Tue, 03 Jan 2012 14:17:48 -0800 (PST)
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Tue, 03 Jan 2012 14:17:47 -0800 (PST)
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Subject: CS 281B. Advanced Topics in Learning and Decision Making
From: Tim Althoff <althoff@eecs.berkeley.edu>
To: alex@smola.org
Content-Type: multipart/alternative; boundary=f46d043c7af4b07e8d04b5a7113a

--f46d043c7af4b07e8d04b5a7113a
Content-Type: text/plain; charset=ISO-8859-1

More feature engineering

- Two Interlocking Spirals

Transform the data into a radial and angular part

$$(x_1, x_2) = (r \sin \phi, r \cos \phi)$$

- Handwritten Japanese Character Recognition

- Break down the images into strokes and recognize it
- Lookup based on stroke order

- Medical Diagnosis

- Physician's comments
- Blood status / ECG / height / weight / temperature ...
- Medical knowledge

- Preprocessing

- Zero mean, unit variance to fix scale issue (e.g. weight vs. income)
- Probability integral transform (inverse CDF) as alternative

The Perceptron on features

initialize $w, b = 0$

repeat

Pick (x_i, y_i) from data

if $y_i(w \cdot \Phi(x_i) + b) \leq 0$ then

$$w' = w + y_i \Phi(x_i)$$

$$b' = b + y_i$$

until $y_i(w \cdot \Phi(x_i) + b) > 0$ for all i

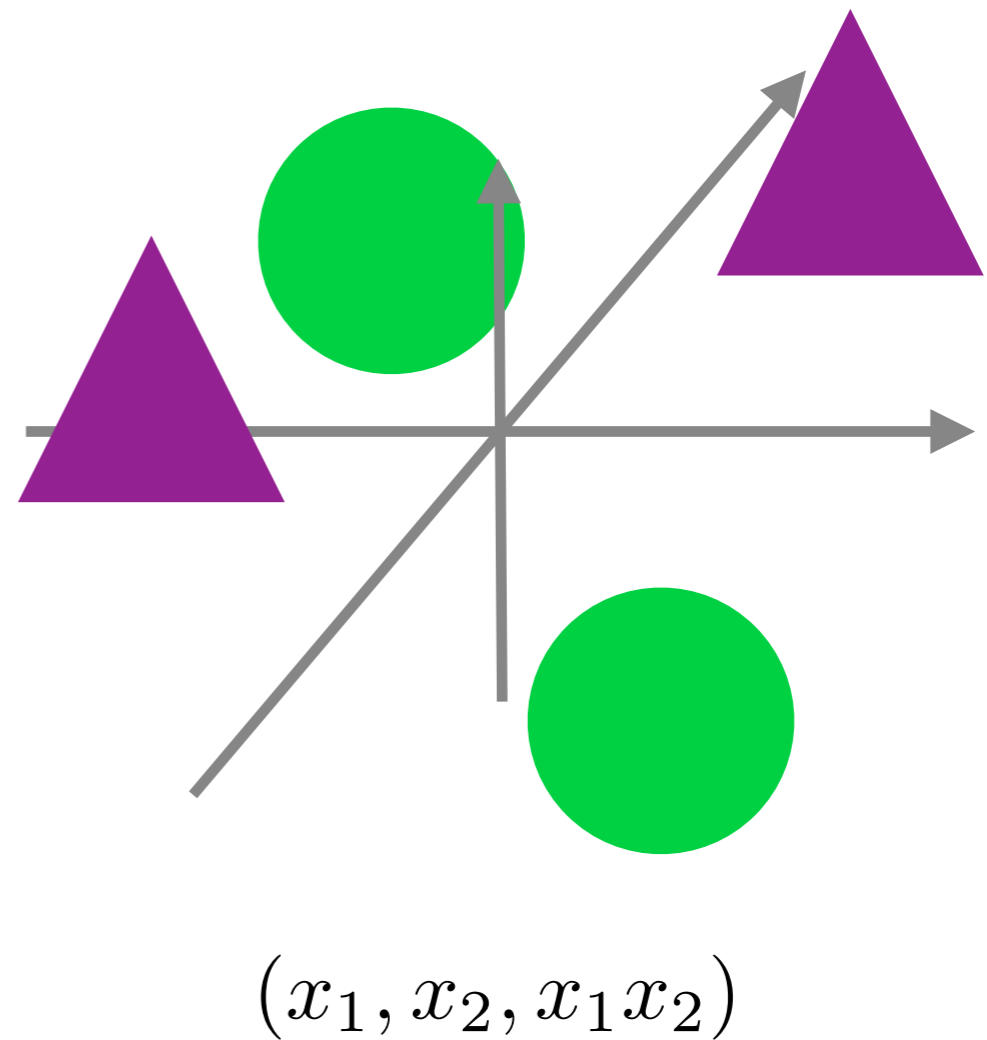
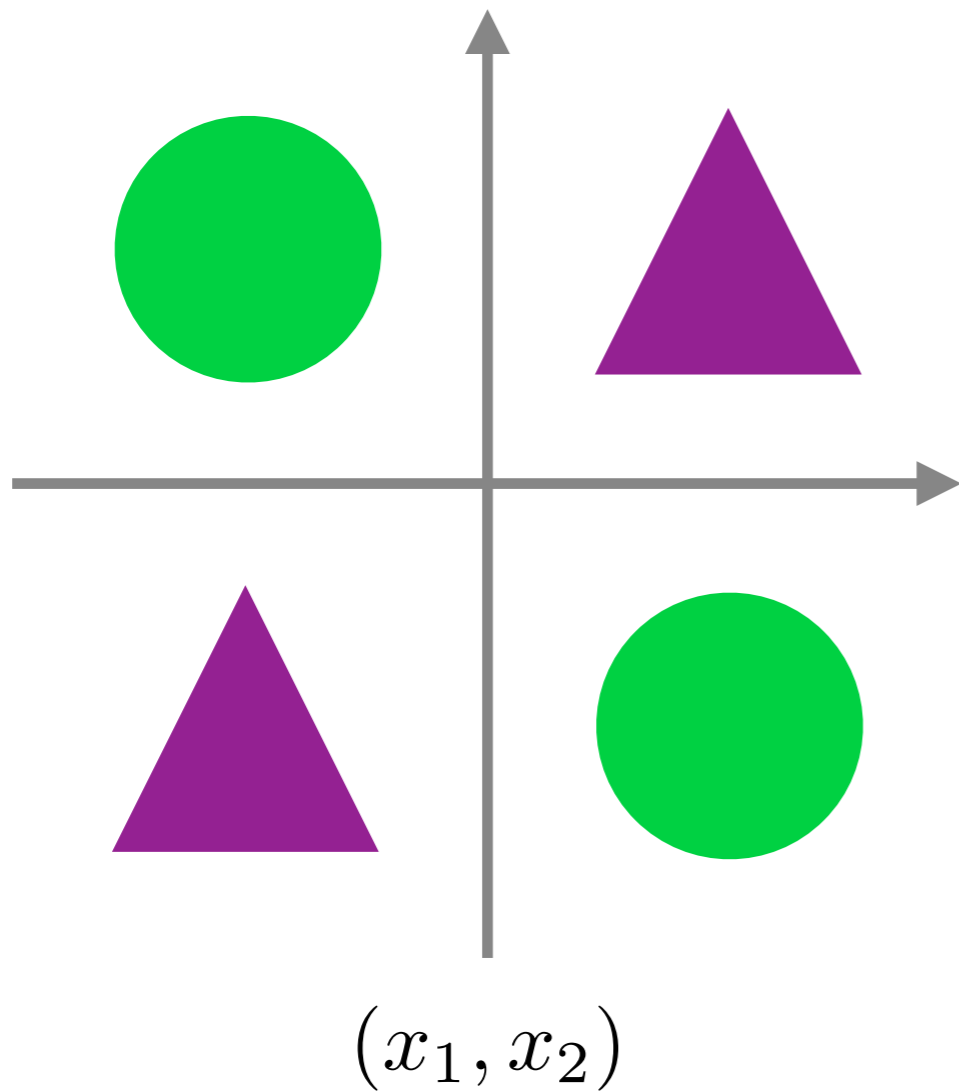
- Nothing happens if classified correctly
- Weight vector is linear combination $w = \sum_{i \in I} y_i \phi(x_i)$
- Classifier is linear combination of

inner products $f(x) = \sum_{i \in I} y_i \langle \phi(x_i), \phi(x) \rangle + b$

Problems

- Problems
 - Need domain expert (e.g. Chinese OCR)
 - Often expensive to compute
 - Difficult to transfer engineering knowledge
- Shotgun Solution
 - Compute many features
 - Hope that this contains good ones
 - Do this efficiently

Solving XOR



- XOR not linearly separable
- Mapping into 3 dimensions makes it easily solvable

Next Lecture: Multi-layer Perceptron