

# BBM444

## FUNDAMENTALS OF COMPUTATIONAL PHOTOGRAPHY

Lecture #11 – Visual Quality Assessment



HACETTEPE  
UNIVERSITY  
COMPUTER  
VISION LAB

Erkut Erdem // Hacettepe University // Spring 2026

# Today's Lecture

- Introduction about image quality assessment (IQA)
- Full-reference IQA models
- No-reference IQA models
- The Perception-Distortion Tradeoff
- What makes a great picture?

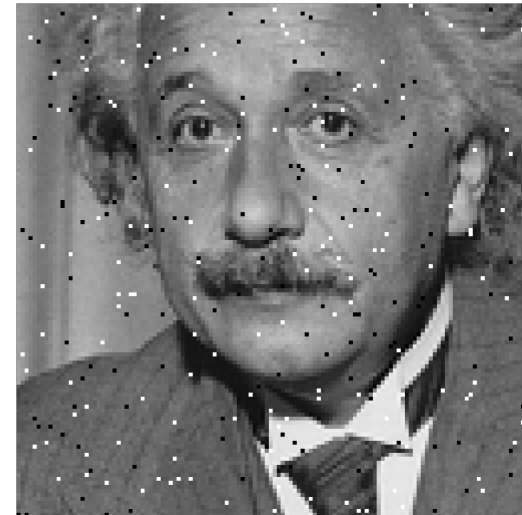
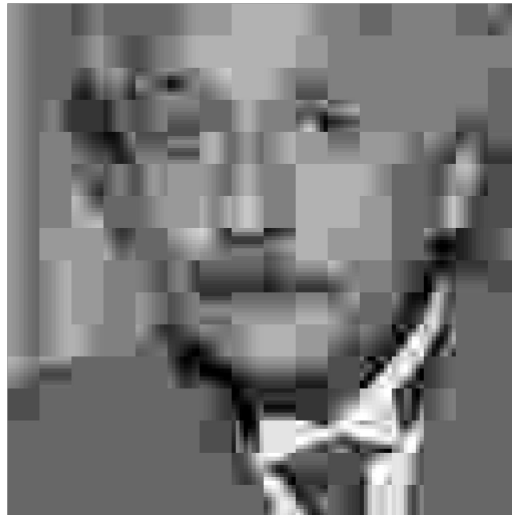
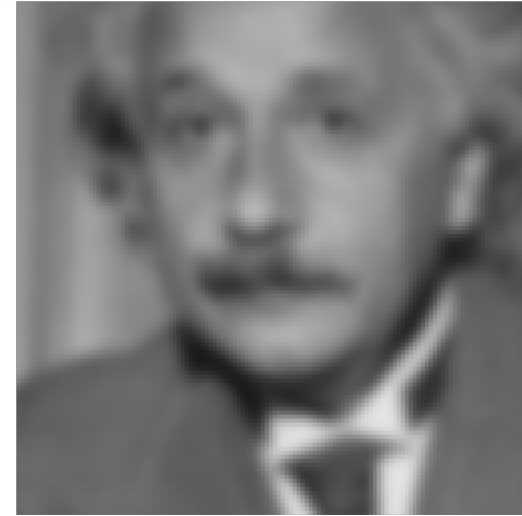
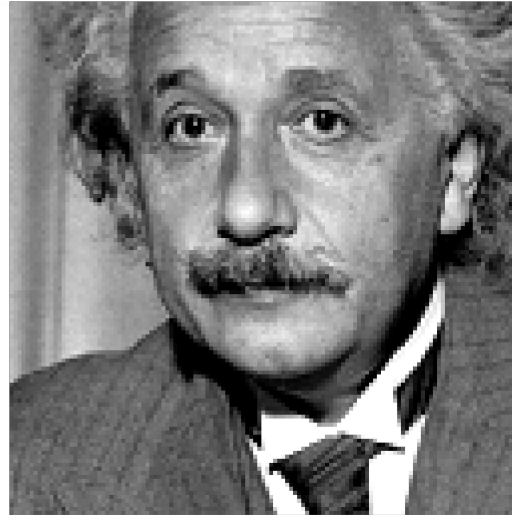
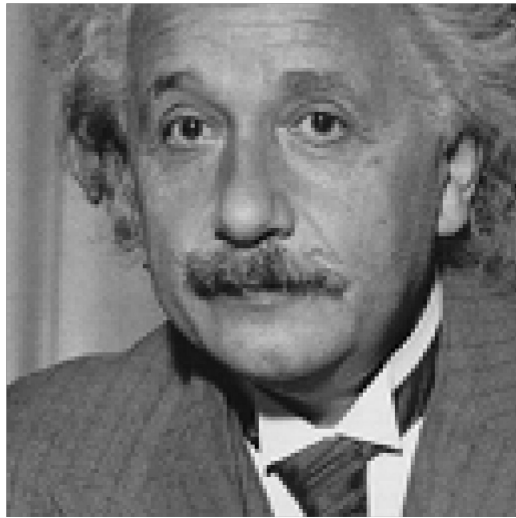
**Disclaimer:** The material and slides for this lecture were borrowed from

—Alexei Efros's CS194-26/294-26 "Intro to Computer Vision and Computational Photography" class

—Kede Ma and Yuming Fang's "Image Quality Assessment in the Modern Age" tutorial at ACM MM 2021

# Introduction about image quality assessment

# What is Image Quality Assessment?



# Image Restoration (IR) and Image Quality Assessment (IQA)

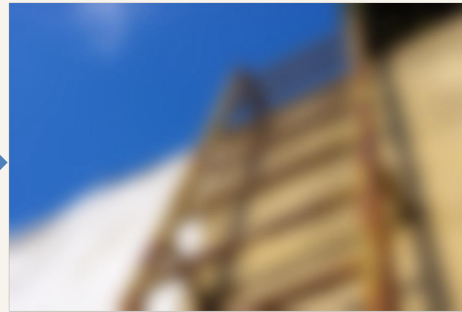
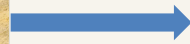
- **Image Restoration (IR)** aims at recovering a high-quality image from its degraded observation.
- **Image Quality Assessment (IQA)** methods were developed to measure the distortion/perceptual-quality of images.
- **IQA methods** are widely used to evaluate IR algorithms, e.g., PSNR, SSIM and Perceptual Index (PI).

# Synthetic and Authentic Distortions

Synthetic Distortions: Simulated by Pristine Image



Pristine image



BLUR: level 4



JPEG: level 4

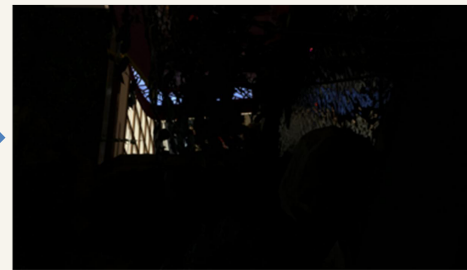
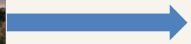


JP2K: level 4

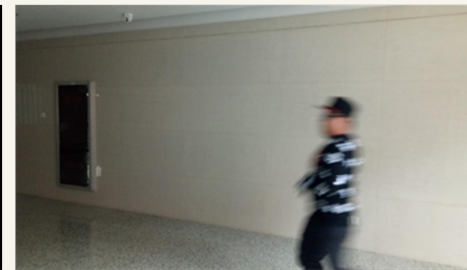
Realistic Distortions: Captured from Mobile Devices



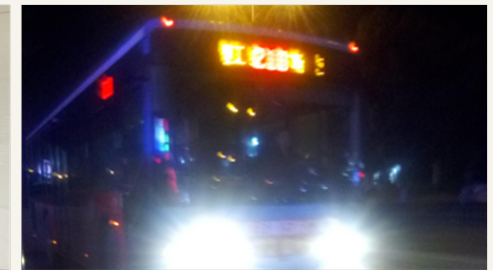
Smartphone Photography



Under-expoure



Motion blurring



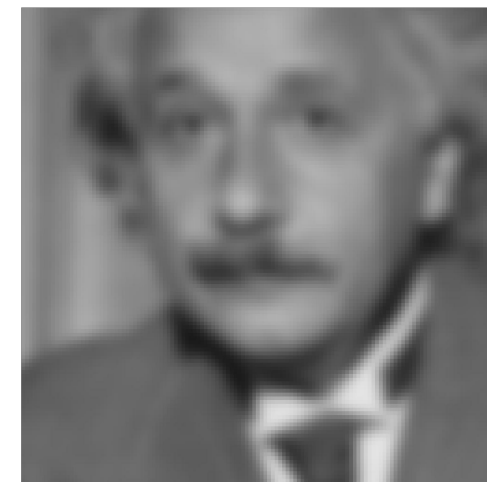
Mixture distortions

# Visual Quality Assessment

- Subjective quality assessment
  - Reliable and accurate quality prediction of visual content
  - Time-consuming, laborious and expensive
  - Not applicable in practical applications
- Objective quality assessment
  - Predict perceived visual quality automatically
  - Applicable in practical applications

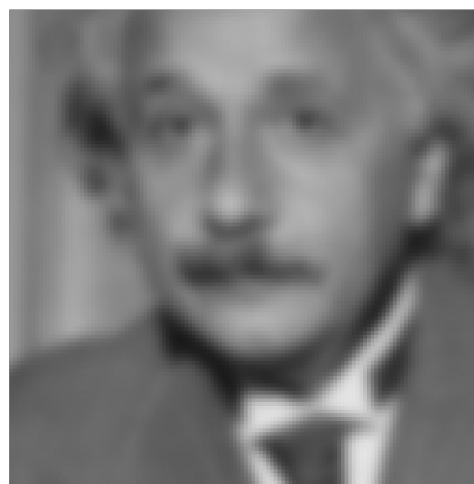
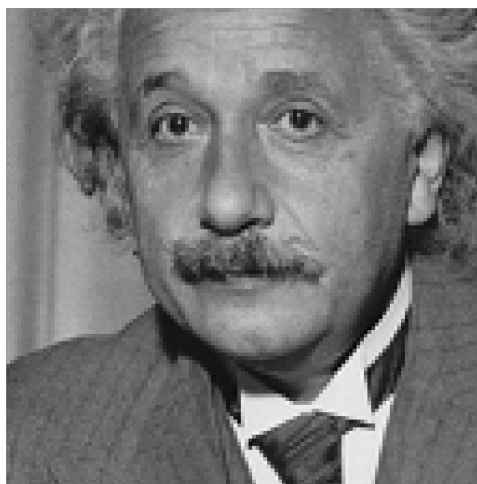
# Subjective Image Quality Assessment

- Absolute category rating (ACR)
  - Single stimulus method
  - Test images are presented one at a time without reference information
  - Voting time: less or equal to 10 seconds depending on the voting method
  - Presentation time: 10 seconds depending on the test image content
  - Five-level or nine-level scale overall rating
- Absolute category rating with hidden reference (ACR-HR)
  - The only difference from the ACR method: a reference version of each test image must be included as the test stimulus, which is termed as a hidden reference condition



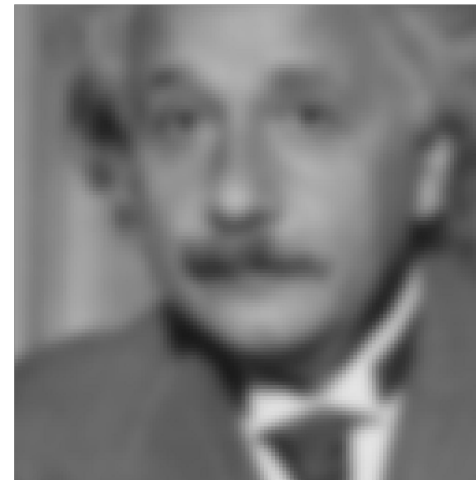
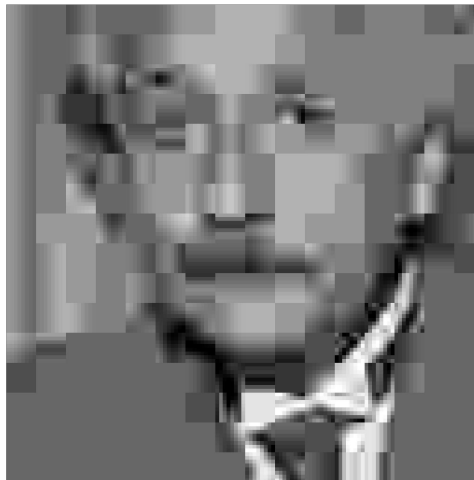
# Subjective Image Quality Assessment

- Degradation category rating (DCR)
  - Double stimulus method
  - Test images are presented in pairs: one is reference image, while the other is distorted image
  - Voting time: less or equal 10 seconds depending on voting method
  - Presentation time: 10 seconds depending on the image content
  - Five-level scale overall rating



# Subjective Image Quality Assessment

- Pair comparison (PC)
  - Double stimulus method
  - Two test images from two different systems are presented in pair from the same reference image
  - Participants are asked to provide the judgment on which one is preferred in the test pair
  - All possible pairs are compared ( $N$  stimuli  $\rightarrow N(n-1)/2$  pairs)
  - (optional) Convert paired comparison data to scale values



A

B

- Which one do you prefer?

# LIVE Dataset

- Reference images: 29. Distorted images: 779.
- Distortion types: 5 (fast fading, Gaussian blur, JP2K, JPEG, white noise)



# CSIQ Dataset

- Reference images: 30. Distorted images: 866.
- Distortion types: 6 (JPEG, JP2K, Gaussian blur, white noise, contrast change, pink noise)



# TID2013 Dataset

- Reference images: 25. Distorted images: 3000.
- Distortion types: 24 (fast fading, Gaussian blur, JP2K, JPEG, white noise, etc.)



# KADID-10K Dataset

- Reference images: 81. Distorted images: 10125.
- Distortion types: 25 (Gaussian blur, JP2K, JPEG, white noise, motion blur,



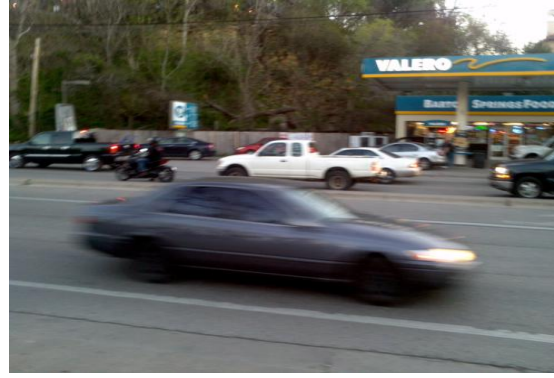
# Waterloo Exploration Dataset

- Reference images: 4744. Distorted images: 94880.
- Distortion types: 4 (Gaussian blur, JP2K, JPEG, White noise.)



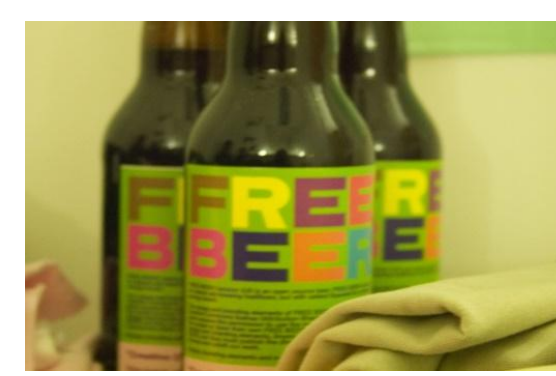
# LIVE Challenge Dataset – Authentic Distortion

- Distorted images: 1162.
- Distortion types: Complex.



# KonIQ-10K Dataset – Authentic Distortion

- Distorted images: 10073.
- Distortion types: Complex.



# SPAQ Dataset – Authentic Distortion

- Distorted images: 11125 (taken by 66 smartphones with 11 manufacturers).
- Distortion types: Complex.



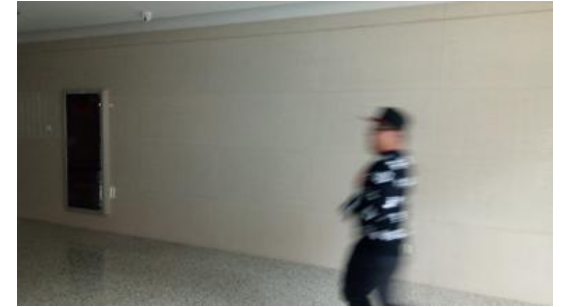
Under-exposure.



Over-exposure



Contrast reduction



Moving object blurring



Sensor noise



Out-of-focus



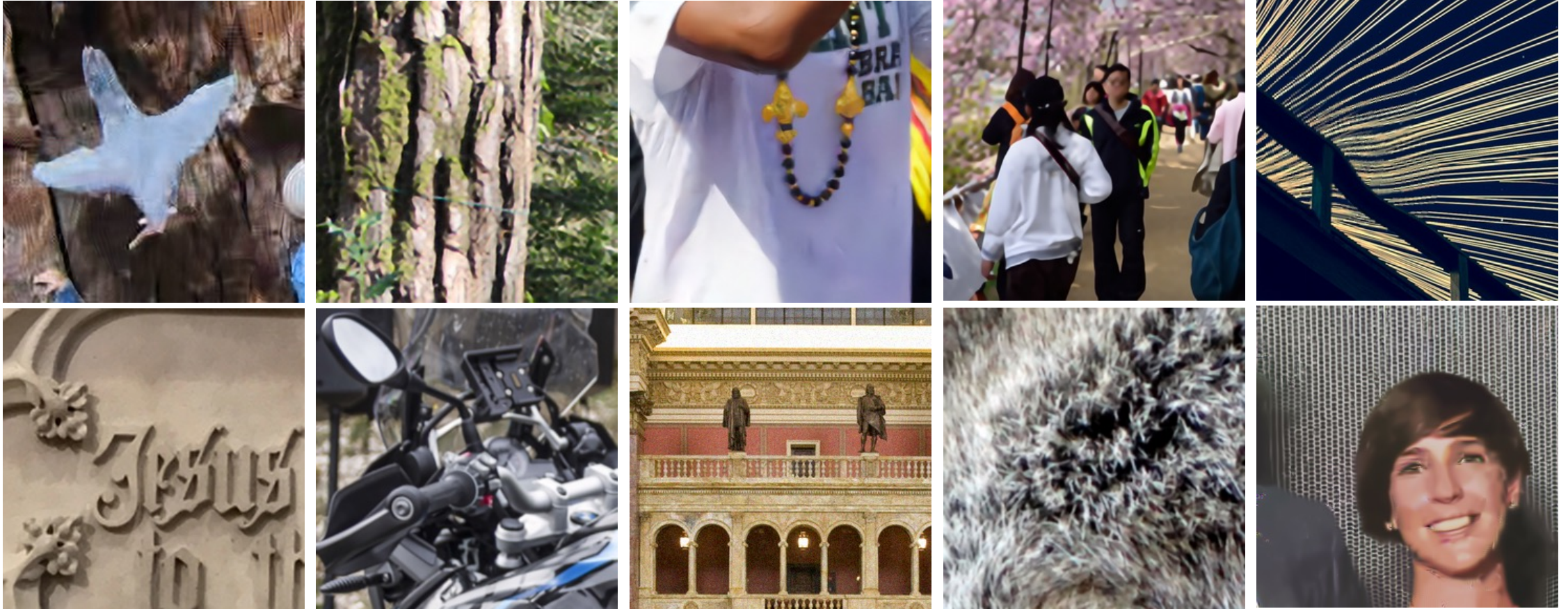
Camera motion blurring



Mixture distortions

# PIPAL Dataset

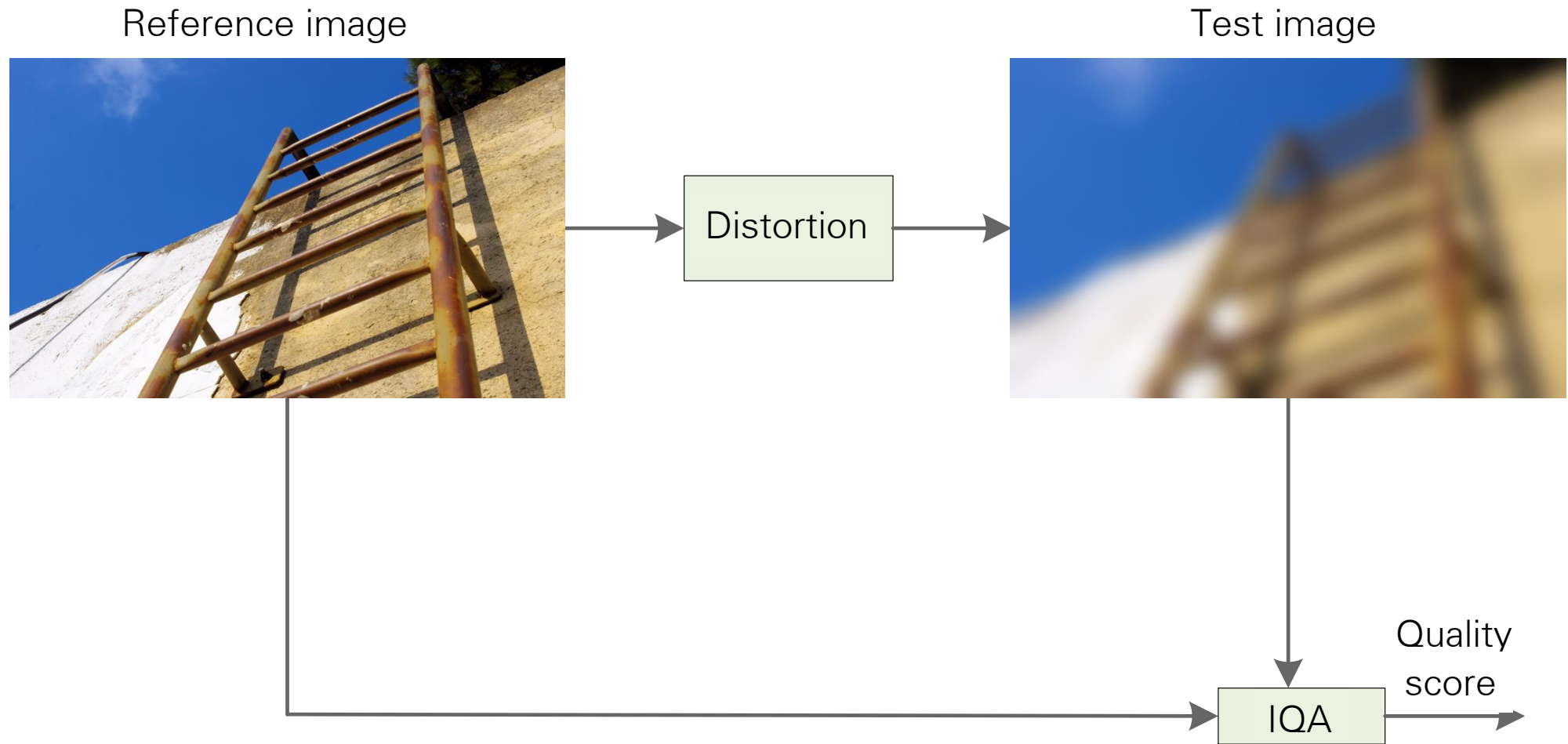
- Reference images: 250. Distorted images: 29000.
- Distortion types: 40 (GAN-based image restoration methods).



# Objective Image Quality Assessment

- **Goal:** Build computational models that accurately predict human perception of image quality
- Two categories:
  1. Full-reference IQA
  2. No-reference IQA

# Full-Reference IQA



# No-Reference IQA (Blind IQA - BIQA)

Reference image



Distortion

Test image



Quality score

IQA

# Full-reference IQA: From Mean Squared Error to Structural Similarity (and More)

# What is Wrong with MSE?

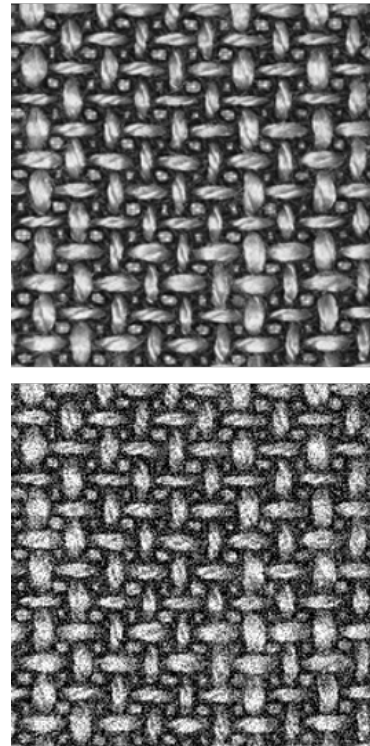


Image Credit: Berardino

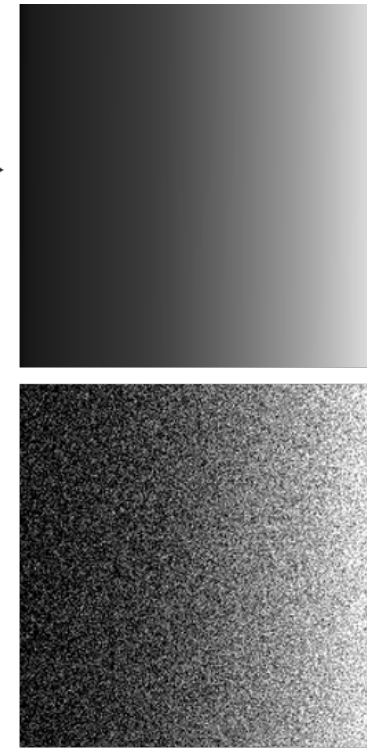
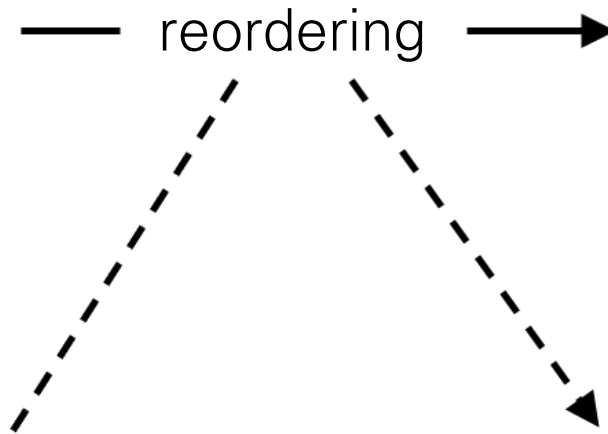
# What is Wrong with MSE?

$$\text{MSE}(x, y) = \frac{1}{N} \sum_{i=1}^N (x_i - y_i)^2$$

Don't care about pixel ordering



MSE= 1600, SSIM=0.637

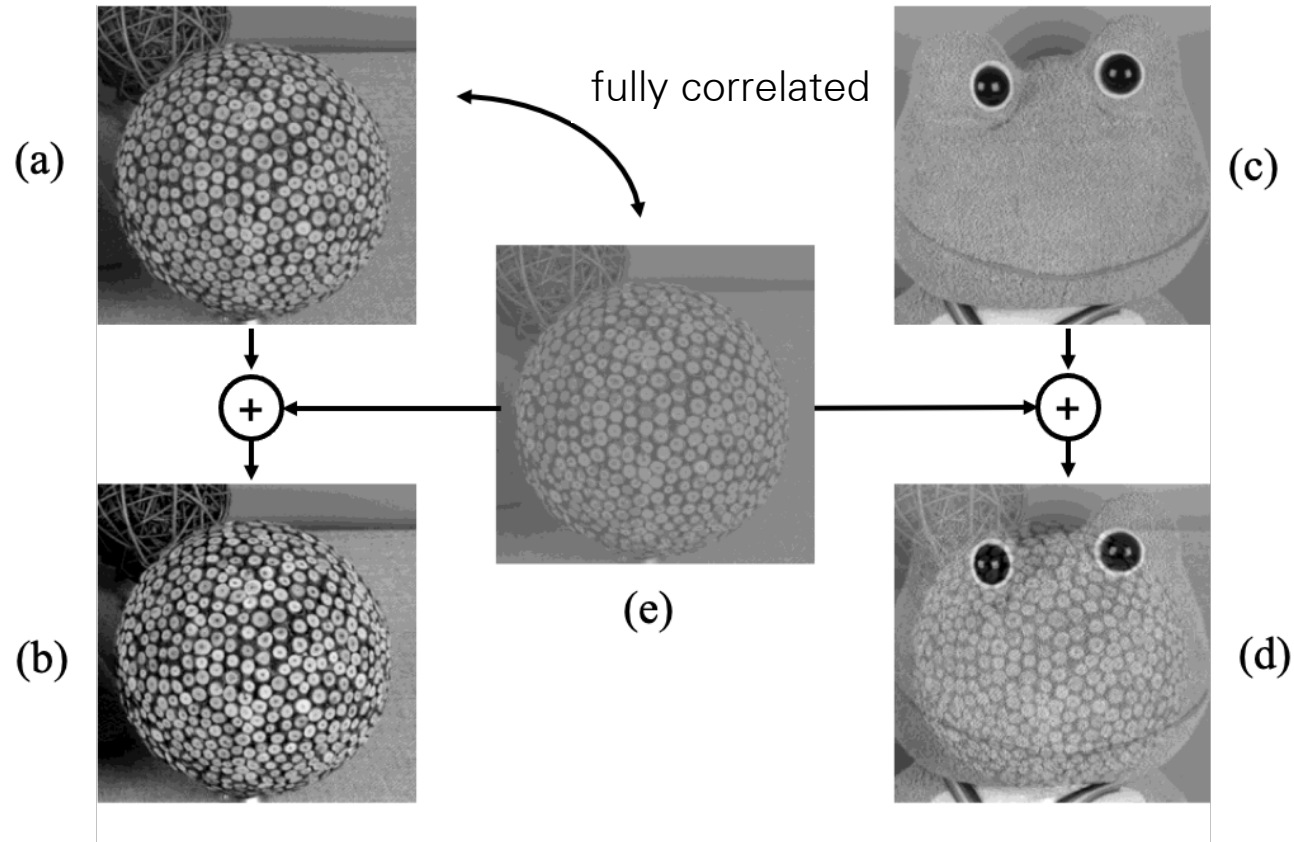


MSE= 1600, SSIM=0.042

# What is Wrong with MSE?

$$\text{MSE}(x, y) = \frac{1}{N} \sum_{i=1}^N (x_i - y_i)^2$$

Care about pixel difference, not the underlying signals



# What is Wrong with MSE?

$$\text{MSE}(x, y) = \frac{1}{N} \sum_{i=1}^N (x_i - y_i)^2$$

Don't care about the sign of pixel difference



+30



MSE= 900,  
SSIM=0.933

+(rand sign)\*30



MSE= 900,  
SSIM=0.247

# What is Wrong with MSE?

- MSE (or the more general Minkowski metric) implicitly assumes that errors are statistically independent
  - True, if spatial dependencies are eliminated prior to computation
  - No easy task as natural images are highly structured (i.e., spatially correlated)
- Possible solution?
  - Learn a “perceptual” transform  $f$ : 
$$D(x, y) = \frac{1}{N} \sum_{i=1}^N (f(x)_i - f(y)_i)^2$$
- Question: What are the desirable properties of  $f$ ?

# Structural Similarity (SSIM)

- Assumption: The human visual system is highly adapted to extract structural information from the viewing field
- Methodology: A measure of structural information change provides a good approximation to perceived image distortion
- Questions:
  - How to define structural (and nonstructural) distortions?
  - How to separate structural and nonstructural distortions?

# The SSIM Index

[Wang et al., 2004]

$$\text{SSIM}(x, y) = \frac{(2\mu_x\mu_y + C_1)(2\sigma_{xy} + C_2)}{(\mu_x^2 + \mu_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

Original image



Distorted image



Similarity measure  
within sliding window



Pooling

Quality score

# Quality Map

Gaussian noise  
corrupted image



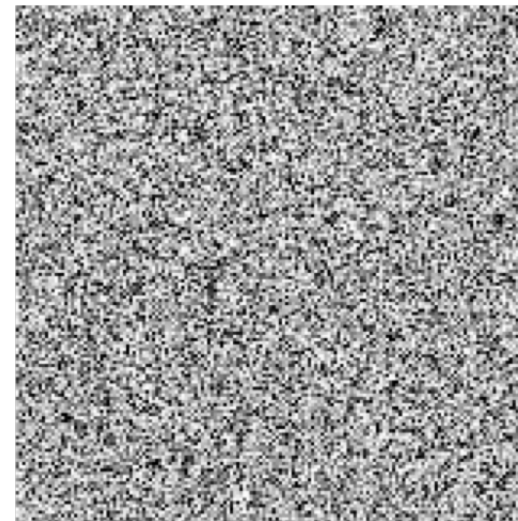
Original image



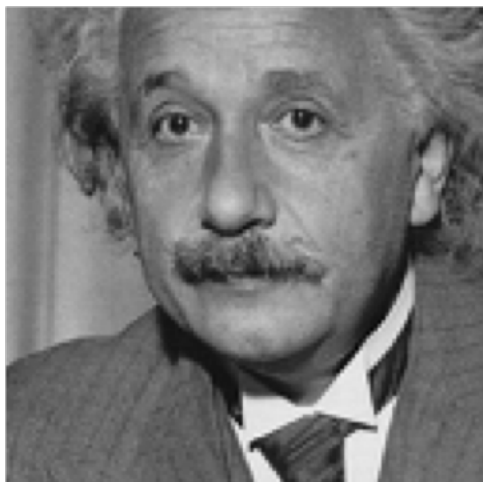
SSIM map



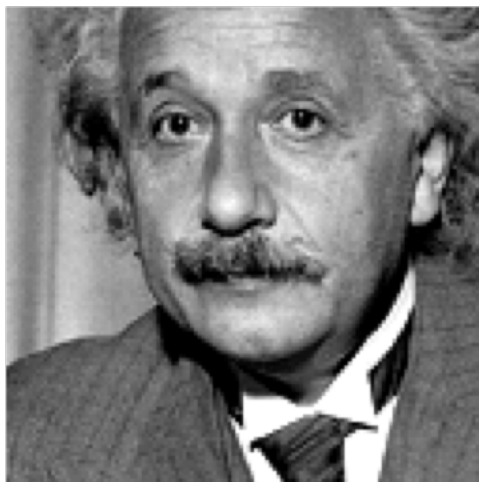
Absolute error map



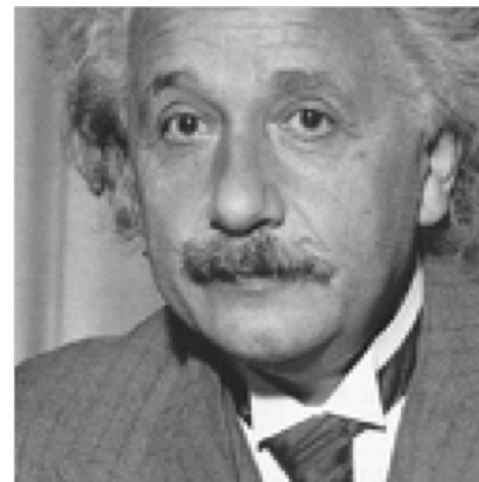
# SSIM vs MSE



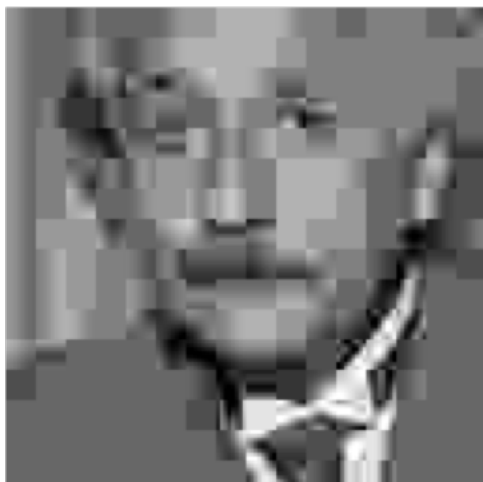
MSE=0, SSIM=1



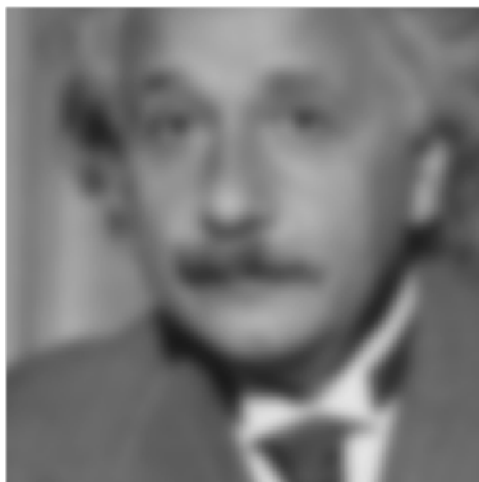
MSE=309, SSIM=0.93



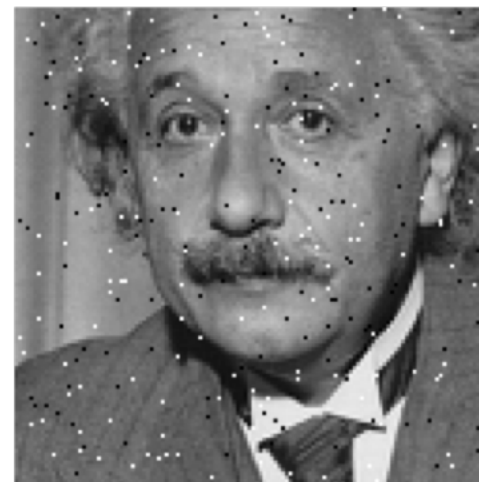
MSE=309, SSIM=0.99



MSE=309, SSIM=0.58



MSE=308, SSIM=0.64



MSE=309, SSIM=0.73

# What is Wrong with SSIM?

$$\text{SSIM}(x, y) = \frac{(2\mu_x\mu_y + C_1)(2\sigma_{xy} + C_2)}{(\mu_x^2 + \mu_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

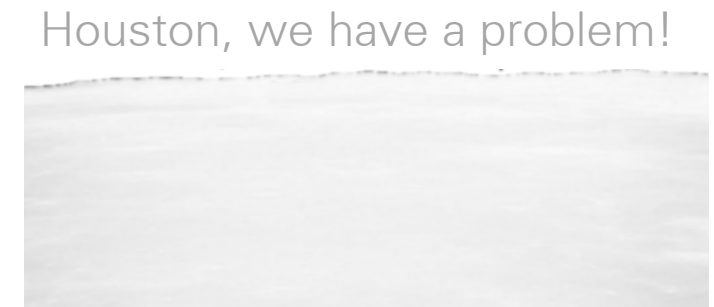
Normalization is sensitive to low intensities



Original image



Distorted image



SSIM map

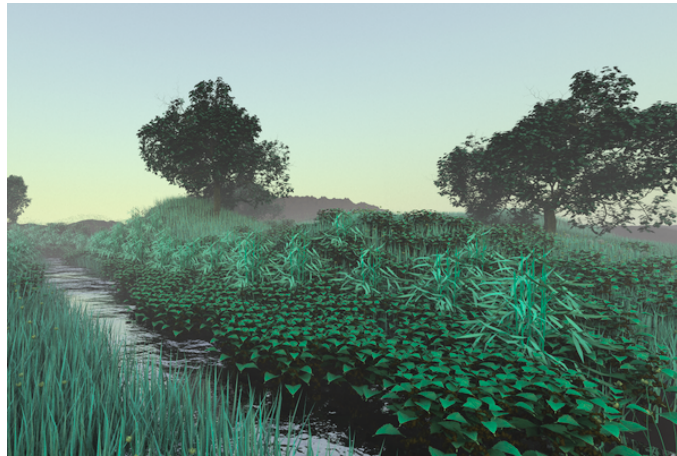
# What is Wrong with SSIM?

$$\text{SSIM}(\text{c2g}(x), \text{c2g}(y)) = \frac{(2\mu_x\mu_y + C_1)(2\sigma_{xy} + C_2)}{(\mu_x^2 + \mu_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

Don't consider chrominance



Original image



Distorted image



SSIM map

# What is Wrong with SSIM?

$$\text{SSIM}(x, y) = \frac{(2\mu_x\mu_y + C_1)(2\sigma_{xy} + C_2)}{(\mu_x^2 + \mu_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

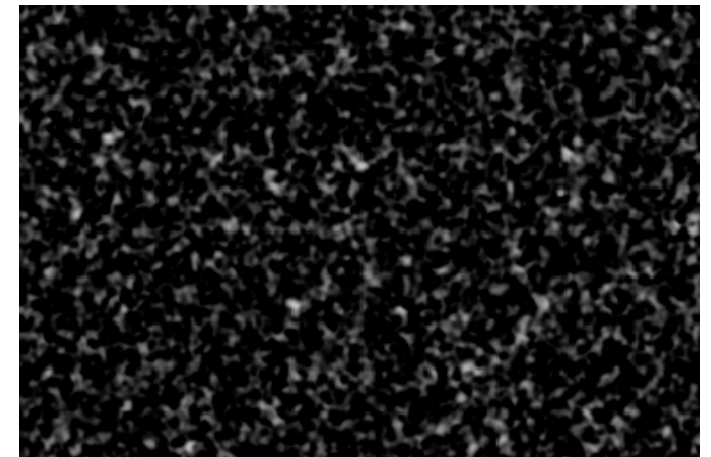
Rely on point-by-point comparison



Original image



Distorted image



SSIM map

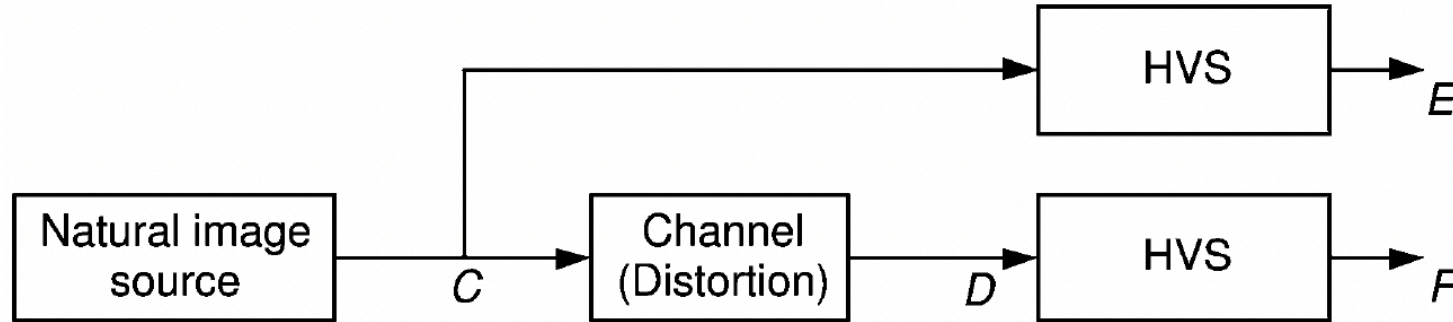
# More Generally

- Not accurate enough
  - MS-SSIM, IW-SSIM, VIF, MAD, FSIM, VSI, NLPD, LPIPS, DISTTS, ...
- Not computationally efficient enough
  - PAMSE, GMSD, ...
- Not misalignment-aware
  - Adaptive linear system, CW-SSIM, GTI-IQA
- Not color-aware
  - Adaptive linear system, FSIM\_c, LPIPS, PieAPP, DISTTS, ...
- Not texture-aware
  - STSIM, NPTSM, VGG Gram, LPIPS, DISTTS, A-DISTTS, ...

# Visual Information Fidelity (VIF)

[Sheikh and Bovik, 2006]

- An information-theoretical approach
- Quantifies the amount of information preserved in the distorted image
- Works when the “distorted” image is visually superior to the reference



$$\text{VIF} = \frac{MI(C; F)}{MI(C; E)}$$

# Most Apparent Distortion (MAD)

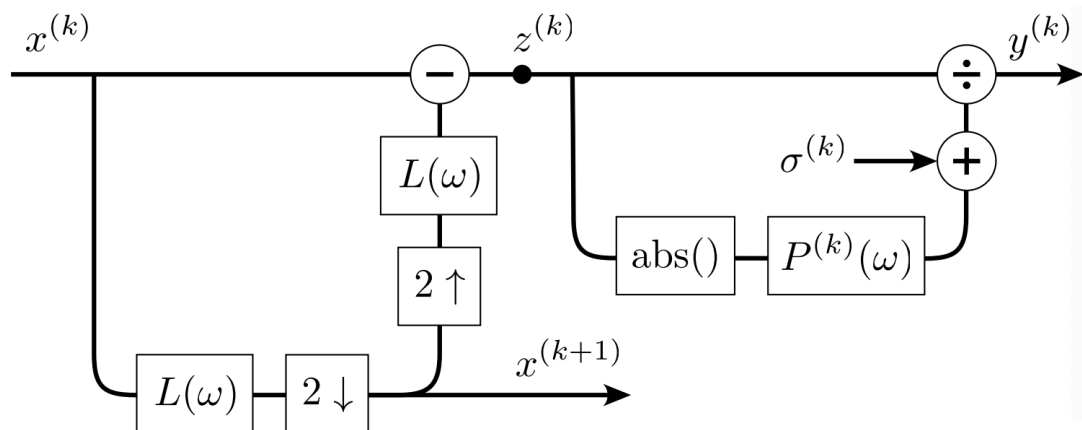
[Larson and Chandler, 2010]

- A multi-strategy approach
- A detection based strategy for near-threshold distortions
  - Look past the image and look for the distortions
- An appearance based strategy for clearly visible distortions
  - Look past the distortions and look for the image content

# Normalized Laplacian Pyramid Distance (NLPD)

[Laparra et al., 2016]

- An error visibility method that models the early visual system
- Local luminance subtraction and local gain control
- The SOTA method for high-dynamic-range image tone mapping

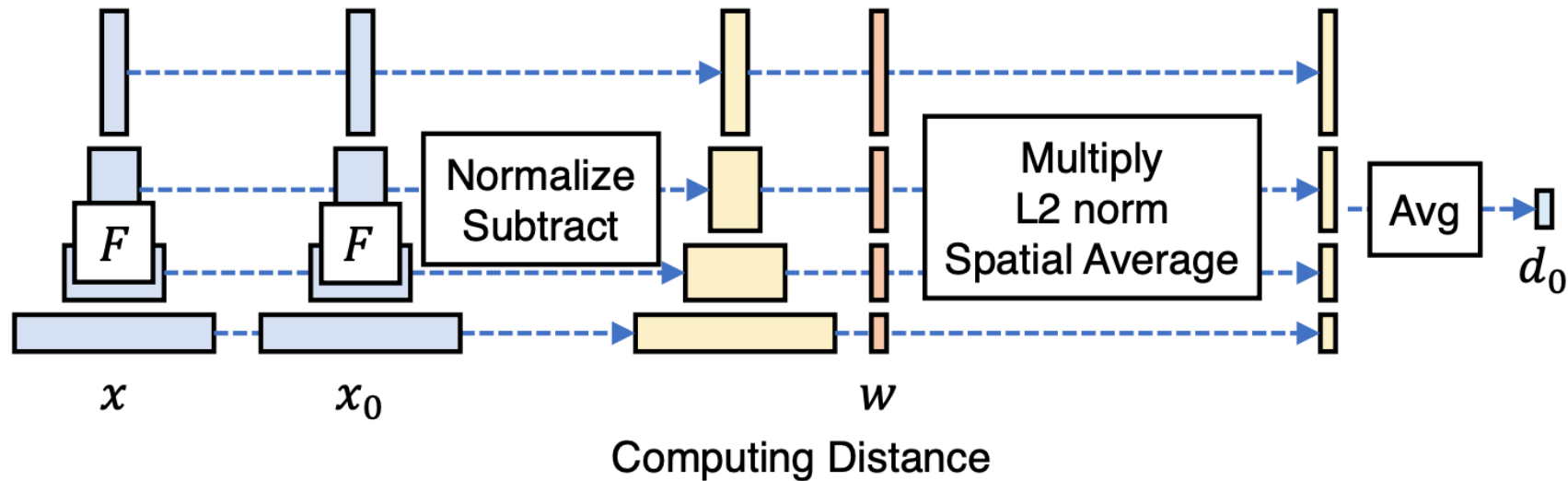


$$\text{NLPD}(x, \tilde{x}) = \frac{1}{N} \sum_{k=1}^N \frac{1}{\sqrt{N^{(k)}}} \|y^{(k)} - \tilde{y}^{(k)}\|_2$$

# Learned Perceptual Image Patch Similarity (LPIPS)

[Zhang et al., 2018]

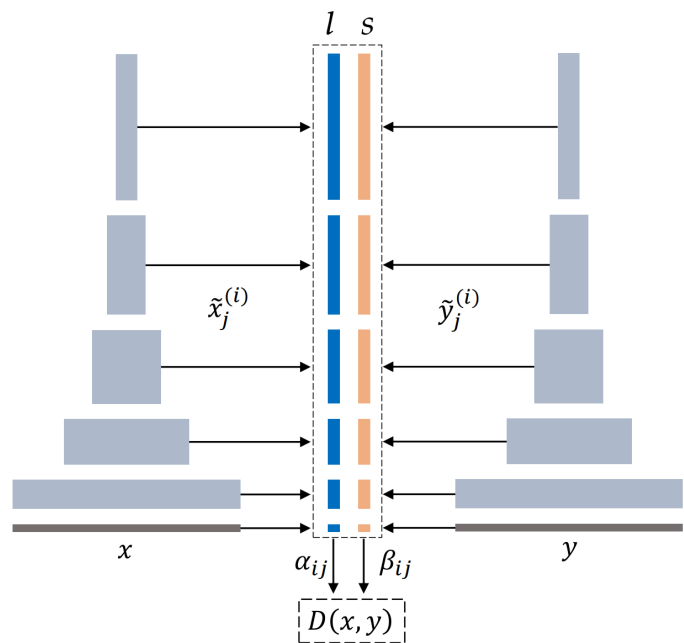
- Investigate a wide range of network architectures and vision tasks
- Demonstrate the effectiveness of deep features in designing IQA models



# Deep Image Structure and Texture Similarity (DISTS)

[Ding et al., 2020]

- Based on an injective mapping function built from a variant of VGG
- SSIM-like global structure and texture similarity measurements
- Robust to texture resampling and mild geometric transformations



$$\text{DISTS}(x, y) = 1 - \sum_{i=0}^m \sum_{j=1}^{n_i} \left( \alpha_{ij} l(\tilde{x}_j^{(i)}, \tilde{y}_j^{(i)}) + \beta_{ij} s(\tilde{x}_j^{(i)}, \tilde{y}_j^{(i)}) \right)$$

# Locally Adaptive DISTs

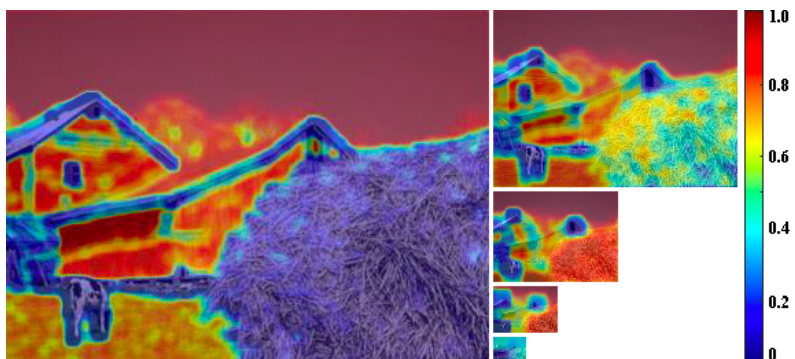
[Ding et al., 2021]

- Rely on the dispersion index to localize texture regions at different scales



$$\text{A-DISTS}(X, Y) = 1 - \frac{1}{N} \sum_{i=0}^M \sum_{j=1}^{N_i} S\left(\tilde{X}_j^{(i)}, \tilde{Y}_j^{(i)}\right)$$

$$S\left(\tilde{X}_j^{(i)}, \tilde{Y}_j^{(i)}\right) = \frac{1}{K_i} \sum_{k=1}^{K_i} \left( \tilde{p}_k^{(i)} l\left(\tilde{x}_{j,k}^{(i)}, \tilde{y}_{j,k}^{(i)}\right) + \tilde{q}_k^{(i)} s\left(\tilde{x}_{j,k}^{(i)}, \tilde{y}_{j,k}^{(i)}\right) \right)$$



# Full-Reference IQA: An Embarrassing Fact

## Reference Image Recovery



(a) Initialization

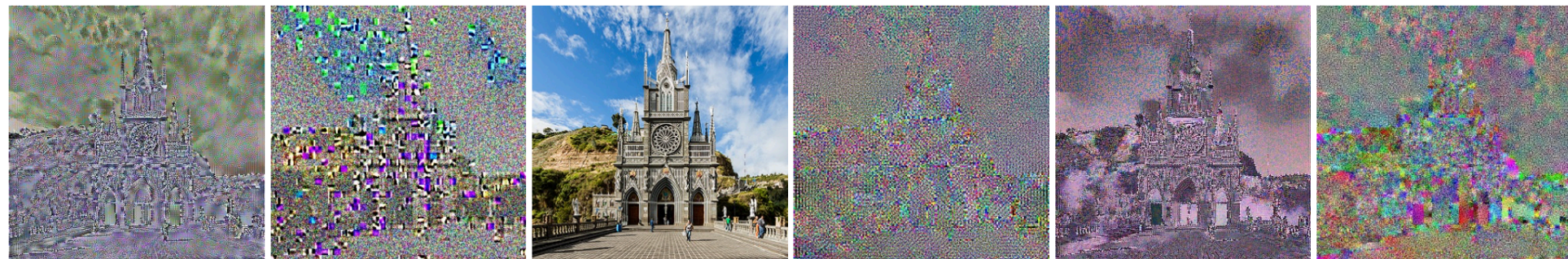
(b) MS-SSIM

(c) IFC

(d) VIF

(e) CW-SSIM

(f) MAD



(g) FSIM

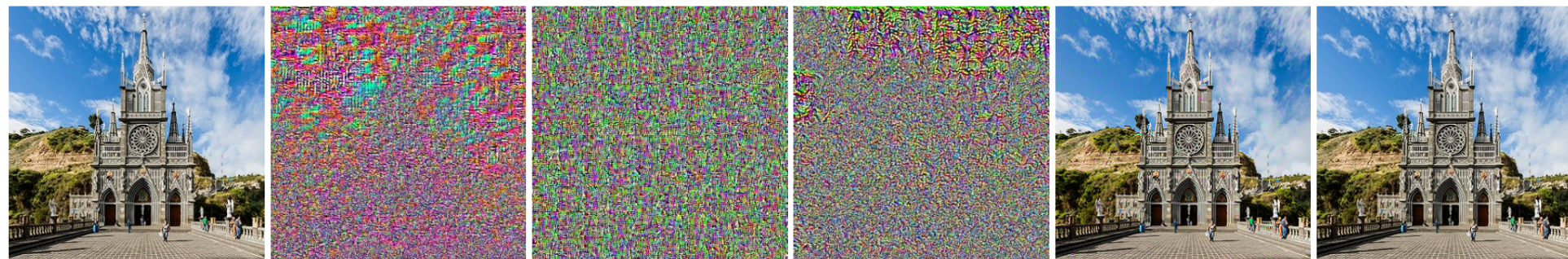
(h) SFF

(i) PAMSE

(j) GMSD

(k) VSI

(l) MCSD



(m) NLPD

(n) GTI-CNN

(o) DeepIQA

(p) PieAPP

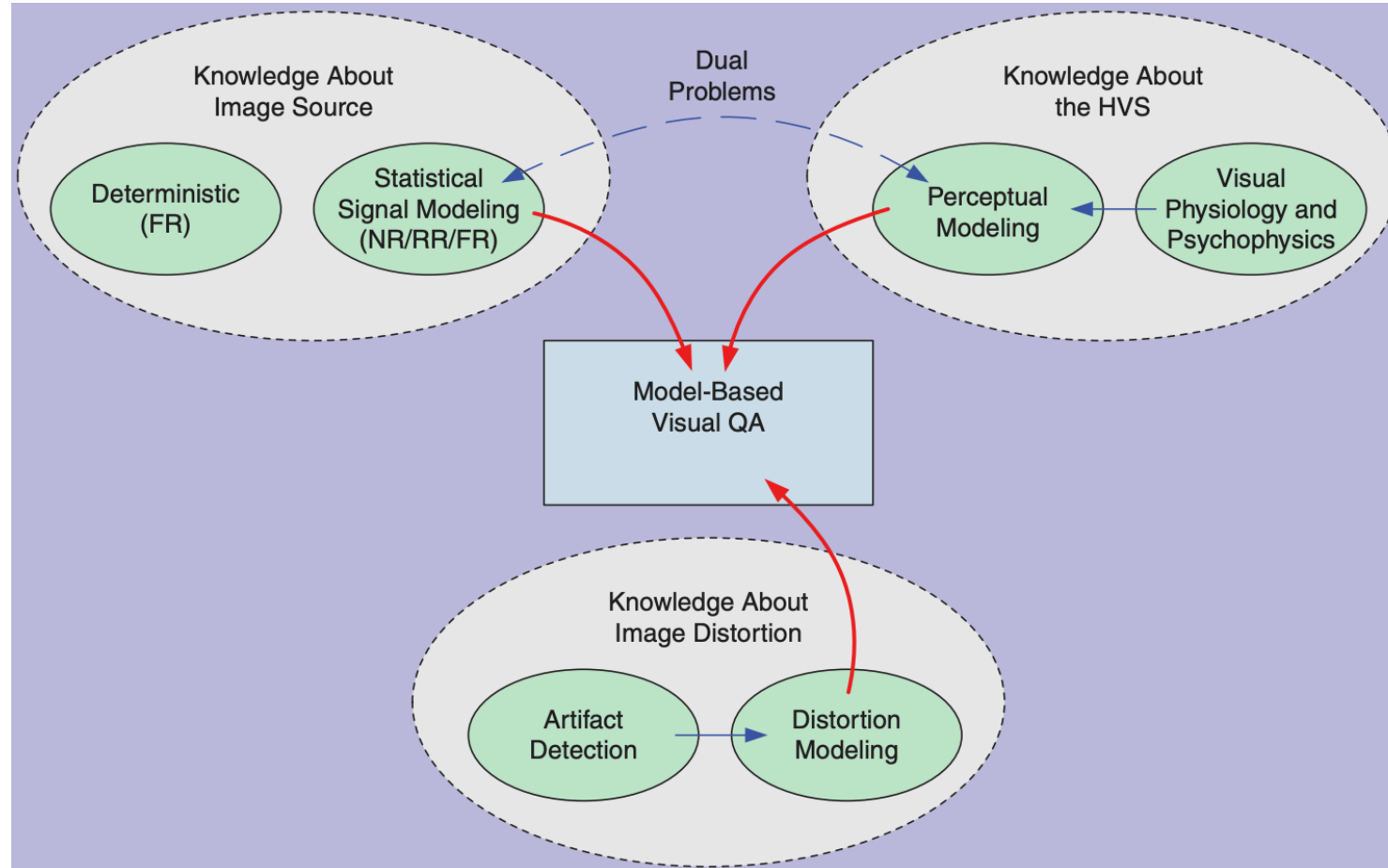
(q) LPIPS

(r) DISTs

$$y^{\star} = \arg \min_y D(x, y)$$

# No-Reference IQA: From Natural Scene Statistics to Learning based Approaches

# Knowledge Map



Question: Do we really wish to leverage knowledge about image distortions?

# Natural Scene Statistics (NSS) based Approaches

- Assumption: Natural images exhibit strong statistical regularities, and reside in a tiny portion of the whole image space
- Methodology: A measure of violation from such statistical regularities provides an approximation to the unnaturalness (i.e., quality) of the image
  1. Handcraft statistical features from the image
  2. Summarize the extracted features using probability distributions (e.g. generalized Gaussian)
  3. Input the fitted parameters to a regression method (e.g, SVM) or compare the fitted distribution to a “reference” distribution

# NSS based Approaches

- Edge intensity/spread, sample entropy, BRISQUE, NIQE, IL-NIQE, ...
  - Spatial domain
- Frequency domain
  - DFT (blur kernel, phase congruency), DCT (BLIINDS-II), ...
- Wavelet domain
  - Local phase coherence, DIIVINE, LBIQ, ...

# Natural Image Quality Evaluator (NIQE)

[Mittal et al., 2013]

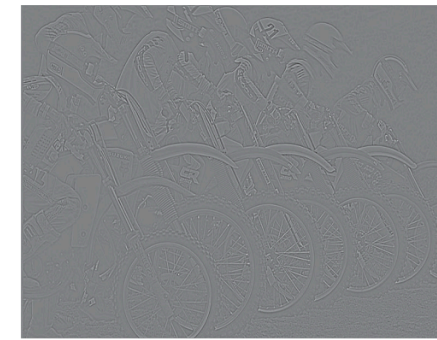
- Without reliance on human ratings
- Without exposure to distorted images
- Widely used in real-world image processing



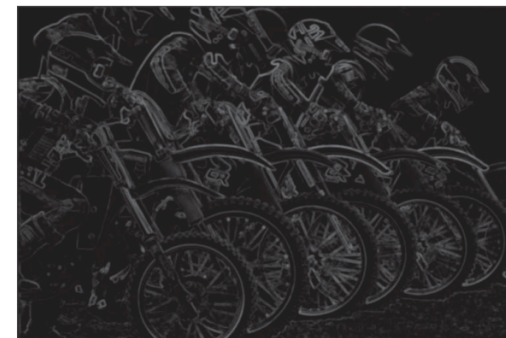
(a)



(b)



(c)



(d)



(e)

$$\text{NIQE} = \sqrt{(\mu_1 - \mu_2)^T \left( \frac{\Sigma_1 + \Sigma_2}{2} \right)^{-1} (\mu_1 - \mu_2)}$$

# (Deep) Learning based Approaches

- Methodology: Joint optimization of feature extraction and quality prediction
- Challenge: the large number of parameters to be optimized and the small number of human ratings as supervisory signals

# (Deep) Learning based Approaches

- Attempt 1: Fine-tune models from other vision tasks (e.g., object recognition)
  - [Bianco, 2018], DB-CNN, UNIQUE, HyperIQA, MetaIQA, ...
- Limitation:
  - Lose the opportunity to search for the optimal and (possibly simpler) network architecture

# (Deep) Learning based Approaches

- Attempt 2: Train no-reference models using image patches
  - CORNIA, [Kang et al., 2014], HOSA, DeepIQA, ...
- Limitation:
  - Local quality generally depends on global context
  - How to obtain a single global score for an image

# (Deep) Learning based Approaches

- Attempt 3: Quality-aware pretraining followed by fine-tuning
  - Leverage distortion information
  - MEON, RankIQA, DB-CNN, ...
- Leverage full-reference models
  - dipIQ, [Kim et al., 2018], [Ma et al., 2019]
- Limitation: Difficult to extend to authentic image distortions

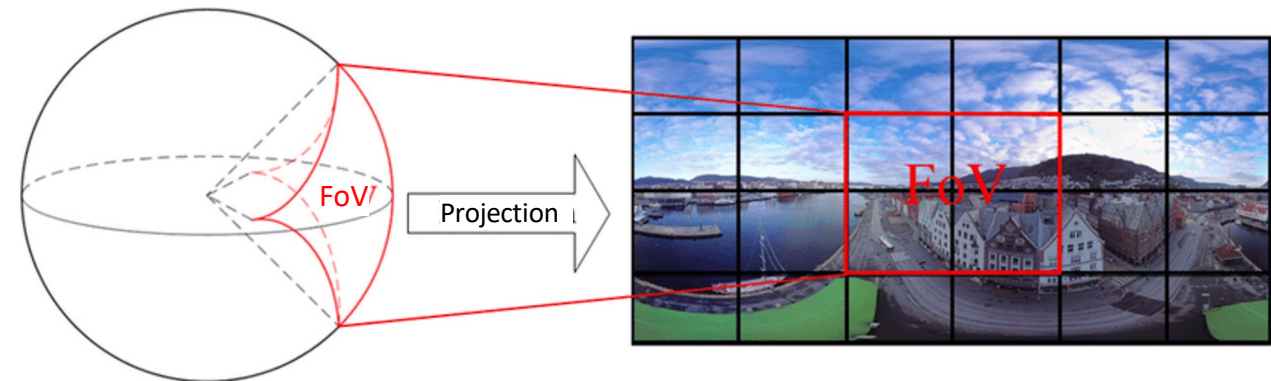
# A Case Study: Omnidirectional IQA

- Omnidirectional images (360° images) are becoming more and more popular
- Applications in virtual reality, robotics, and surveillance
- A new form of visual data



# Challenges in 360° Vision

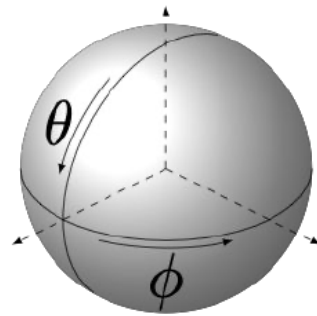
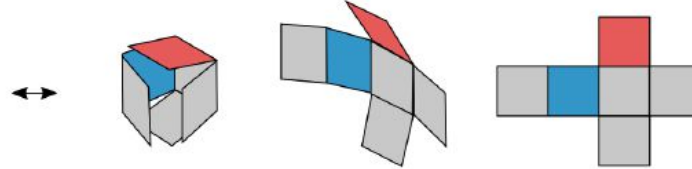
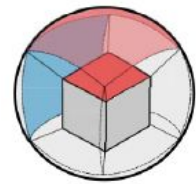
- Spherical distortion
- Limited training data
- Input size (+4K images/videos)
  
- There is a need for reliable quality assessment metrics for omnidirectional images



# Representing Omnidirectional Images

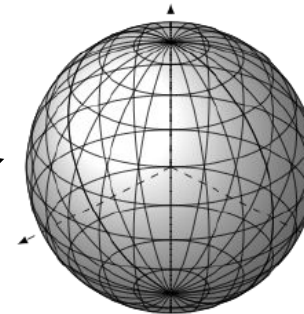
- Approach 1:  
Mapping onto 2D

- Cube-map Projection
- Equirectangular Projection

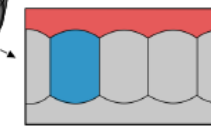


360° Images

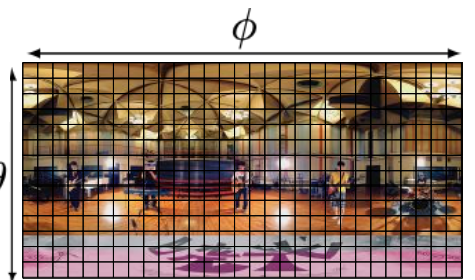
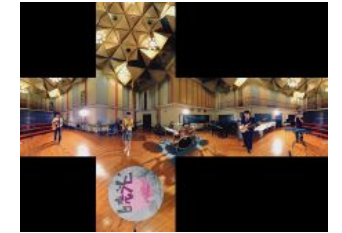
Approach 1:  
Projection



Alternative 2:  
Equirectangular  
Projection (ERP)

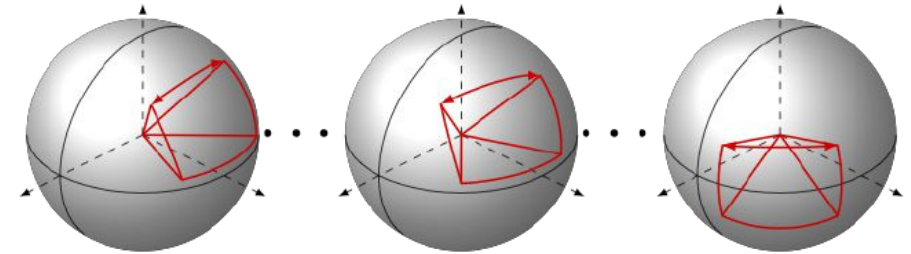


Alternative 2:  
Cube-map  
Projection



- Approach 2:  
Extracting  
multiple  
viewports

Approach 2:  
Extracting  
viewports



Viewport 1



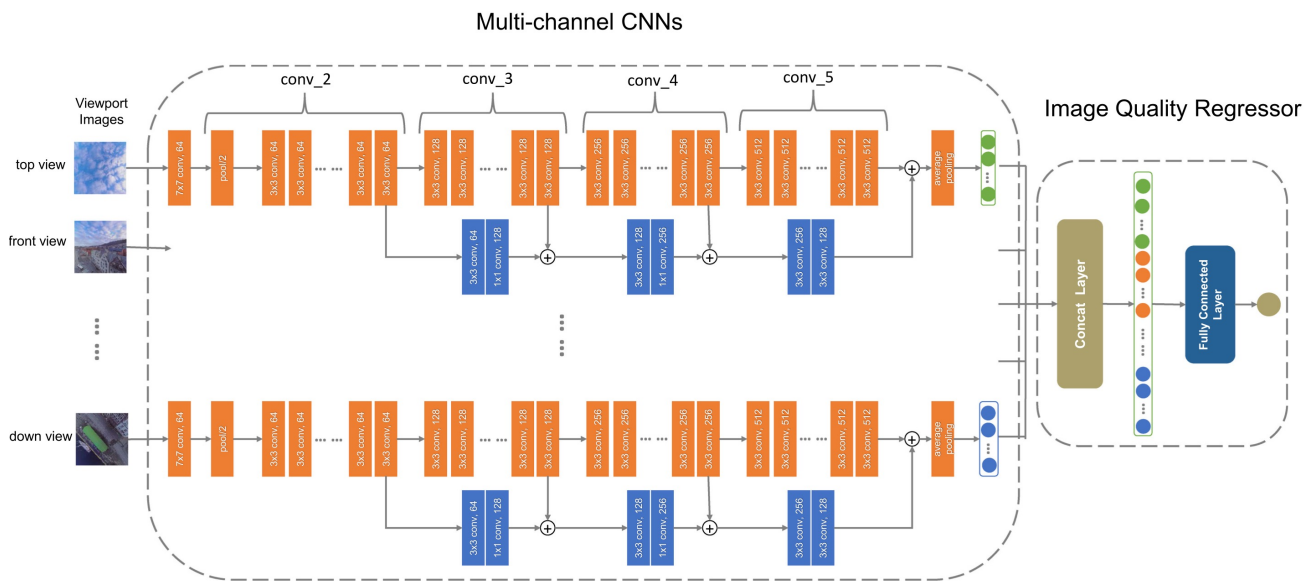
Viewport 2

...



Viewport n

# CNN-based OIQA methods

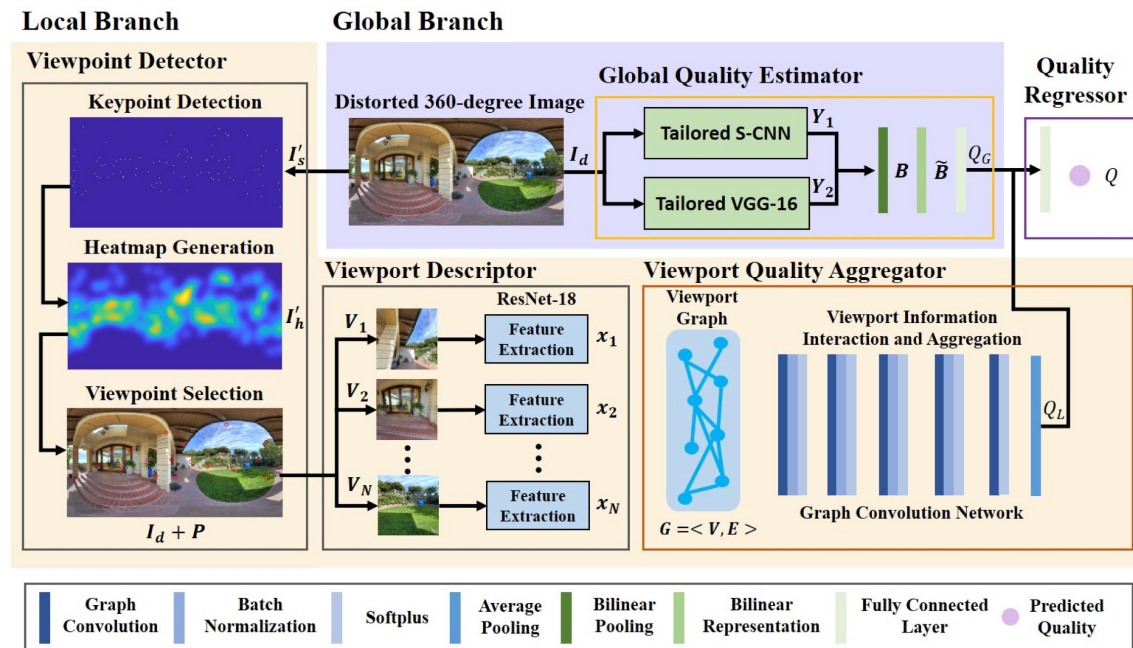


MC360IQA

Employs a multi-channel CNN to extract the features of viewport images projected by omnidirectional images and then regresses features to objective scores.

Sun et al. MC360IQA: A multi-channel CNN for blind 360-degree image quality assessment. IEEE J. Sel. Top. Signal Process., Vol. 14(1):64–77, 2020.

Xu et al. Blind omnidirectional image quality assessment with viewport oriented graph convolutional networks, IEEE Trans. Circuits Syst. Video Technol., Vol. 31(5), 2020

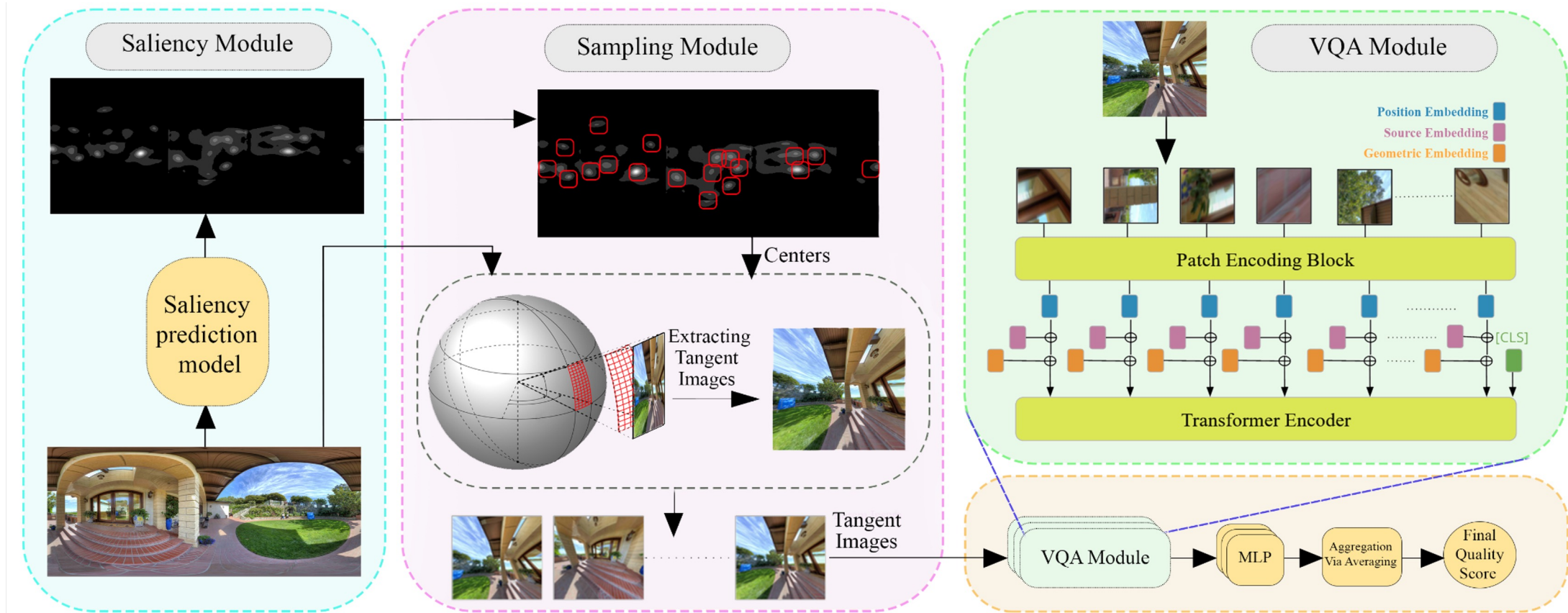


VGCN

A blind OIQA framework containing local and global branches that utilizes a graph convolutional network-based architecture

# Transformer-based OIQA methods

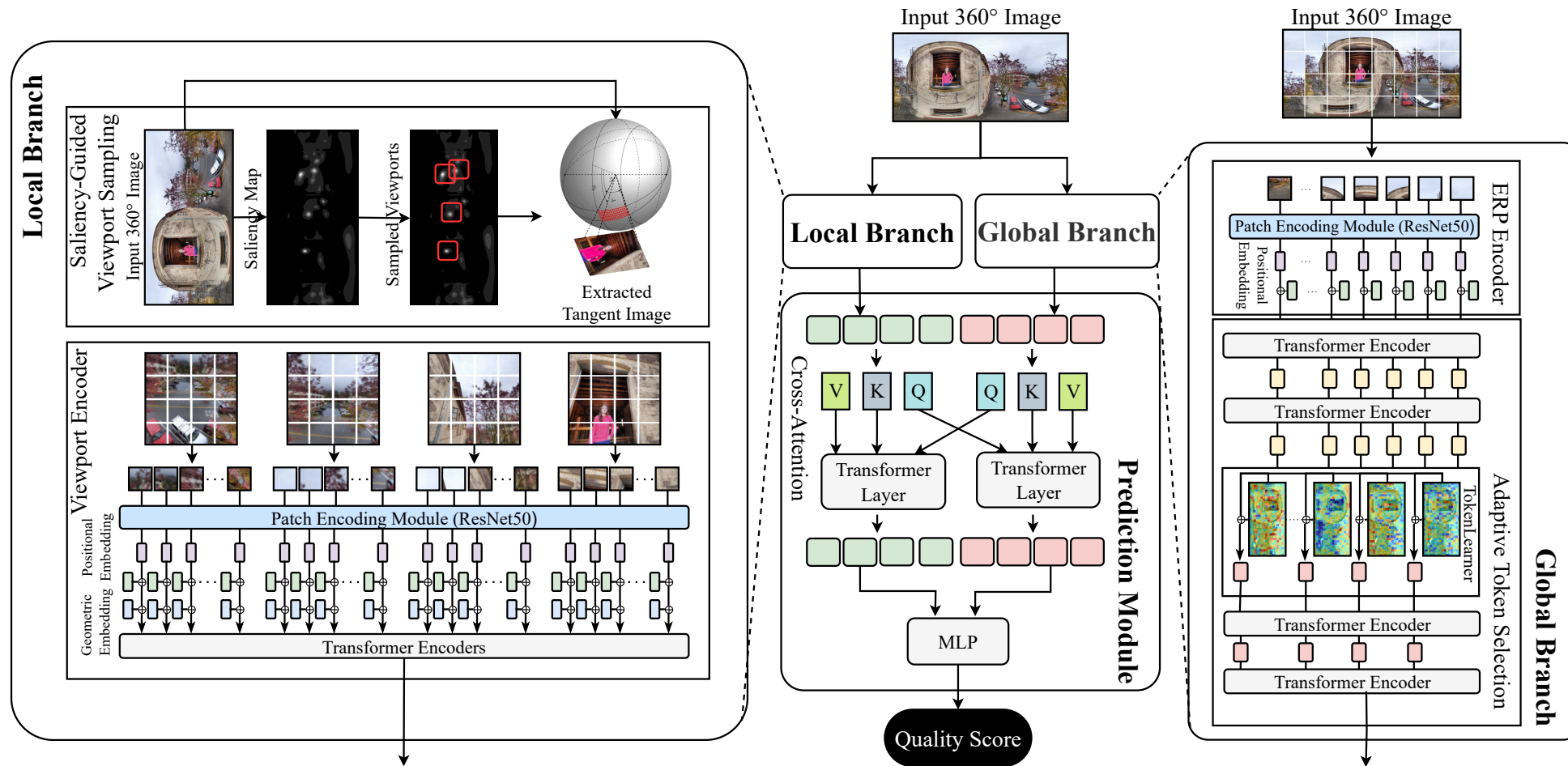
ST360IQ



- estimates the overall image quality through a few tangent viewports focusing on different parts of the spherical image
- exploits saliency information to increase efficiency of ViT architecture

# Transformer-based OIQA methods

LGT360IQ



- features dual branches tailored to mimic top-down and bottom-up visual attention mechanisms.
  - local branch processes tangent viewports from salient regions within the ERP image.
  - global branch uses a task-dependent token sampling strategy.

# Evaluation of IQA Models

# Standard Approach

## Main Steps

1. Select a set of images from the image domain of interest
2. Collect the MOS for each image via psychophysical experiments (i.e., subjective user studies)
3. Compare the goodness of fit among the competing IQA models (i.e., sort by average performance)

- Spearman rank correlation coefficient
  - prediction monotonicity
- Pearson linear correlation coefficient
  - prediction linearity
- Mean squared error
  - prediction accuracy

$$\text{SRCC} = 1 - \frac{6 \sum_i d_i^2}{M(M^2 - 1)}$$

$$\text{PLCC}(x, y) = \frac{\sum_i (x_i - \mu_x)(y_i - \mu_y)}{\sqrt{\sum_i (x_i - \mu_x)^2} \sqrt{\sum_i (y_i - \mu_y)^2}}$$

$$\text{MSE}(x, y) = \frac{1}{M} \sum_i (x_i - y_i)^2$$

# Caveats

- Sampling bias due to the extremely sparse distribution of the selected samples in the image space
  - i.e., the curse of dimensionality
- Algorithmic bias due to potentially overfitting the selected samples
  - The dataset creation precedes the algorithm development
- Subjective bias due to potentially cherry-picking test results

# The Perception-Distortion Tradeoff

# Perceptual Image Restoration

- The invention of Generative Adversarial Networks (GANs) greatly improves the perceptual performance



Ground Truth



Less distortion  
PSNR-oriented



Photo-realistic  
GAN-based

# Gap Between IQA Metric and Human Judgment

- Increasing inconsistency between high numerical performances (PSNR, SSIM, PI, etc.) and perceptual performance.



Ground Truth  
PSNR / SSIM



PSNR-oriented



GAN-based

# Gap Between IQA Metric and Human Judgment

- Before 2018, Evaluation Using PSNR/SSIM



Ground Truth  
PSNR / SSIM



23.52 / 0.7056  
Good in PSNR, SSIM



19.86 / 0.5530  
Preferred by Human

# Gap Between IQA Metric and Human Judgment

- After 2018, Evaluation Using PI/NIQE



Ground Truth  
PI / NIQE



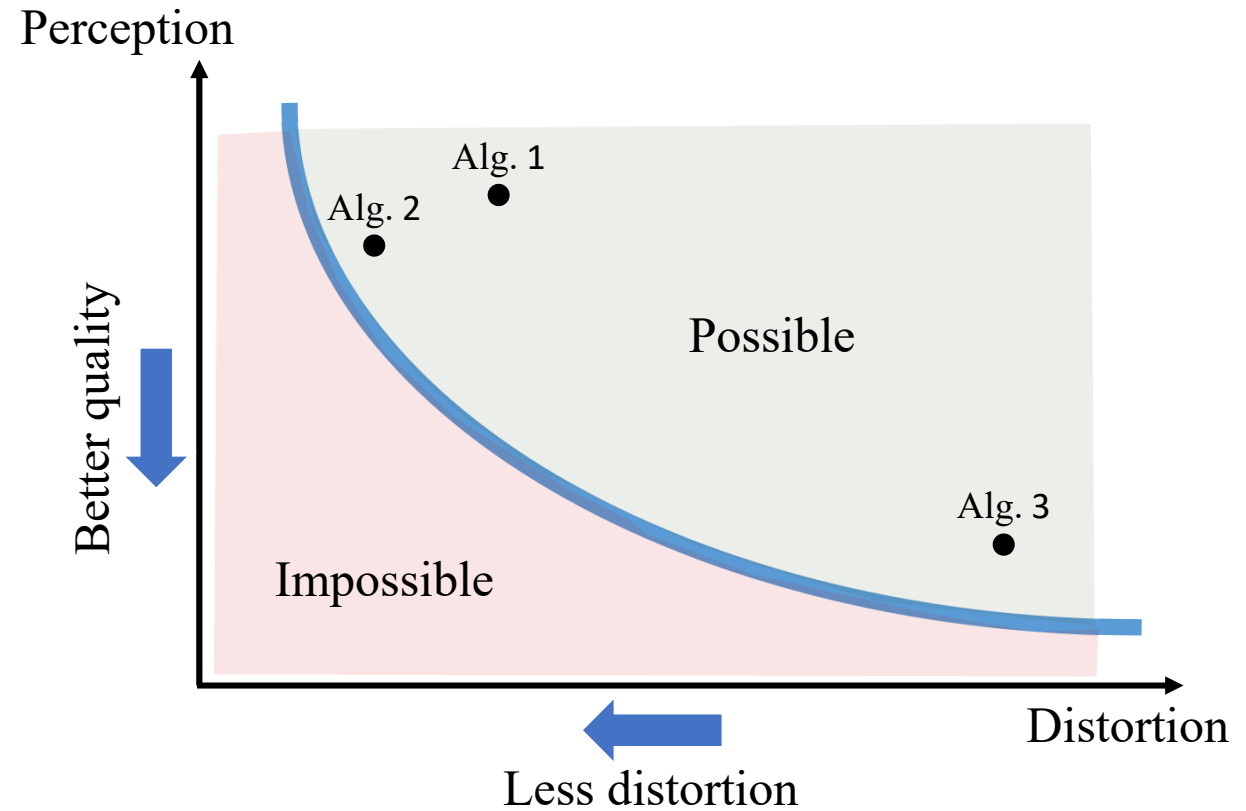
3.80 / 6.47  
Good in PI, NIQE



4.30 / 6.90  
Preferred by Human

# The Perception-Distortion Tradeoff

- How to evaluate image restoration methods?
- Distortion and perceptual quality are at odds with each other.
- The lower the distortion of an algorithm, the more its distribution must deviate from the statistics of natural scenes.



# What Makes a Great Picture?

# Image Quality vs. Image Aesthetics

- Quality assessment deals with measuring low-level degradations such as noise, blur, compression artifacts, etc.
- Aesthetic prediction quantifies semantic level characteristics associated with emotions and beauty in images.

# Photography 101: the where and when

- Composition

- Framing
- Rule of Thirds
- Leading Lines
- Textures and Patterns
- Simplicity

- Lighting

- Light Direction
- Color coordination / balance
- Sunny vs. cloudy
- “Golden Hour”
- B&W to focus attention
- (sur) realism

# Framing

“Photography is all about framing. We see a subject -- and we put a frame around it. Essentially, that is photography when all is said and done.”

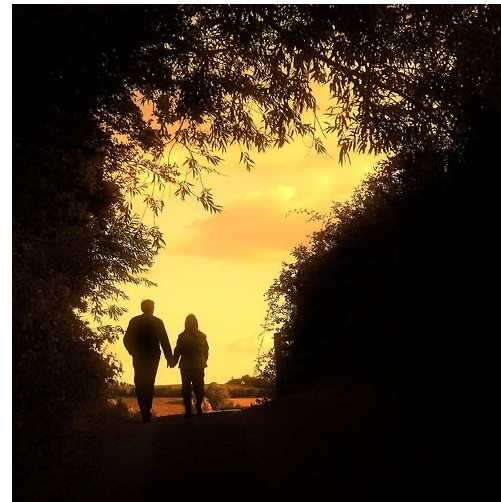
-- from [photo.blorge.com](http://photo.blorge.com)



# Frame serves several purposes:

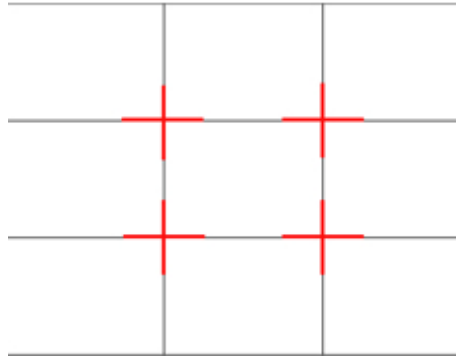
1. It gives the image depth
2. If used correctly, framing can draw the eye of the viewer of an interest to a particular part of the scene.
3. Framing can bring a sense of organization or containment to an image.
4. Framing can add context to a shot.

# Examples of nice framing



<http://flickr.com/photos/paulosacramento/226545698/>  
<http://flickr.com/photos/chrisbeach/13868545/>  
<http://flickr.com/photos/74531485@N00/929270814/>  
<http://flickr.com/photos/freakdog/223117229/>  
<http://flickr.com/photos/cdm/253805482/>

# Rules of Thirds



# Other examples



# Don't center, especially for motion



# Don't center, especially for motion



... or do center



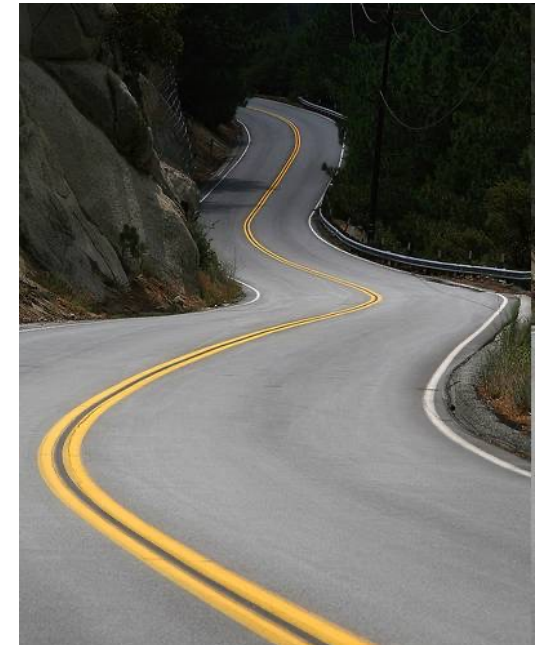
# Leading Lines



# Leading Lines



# More examples



# Textures and Patterns



# Simplicity

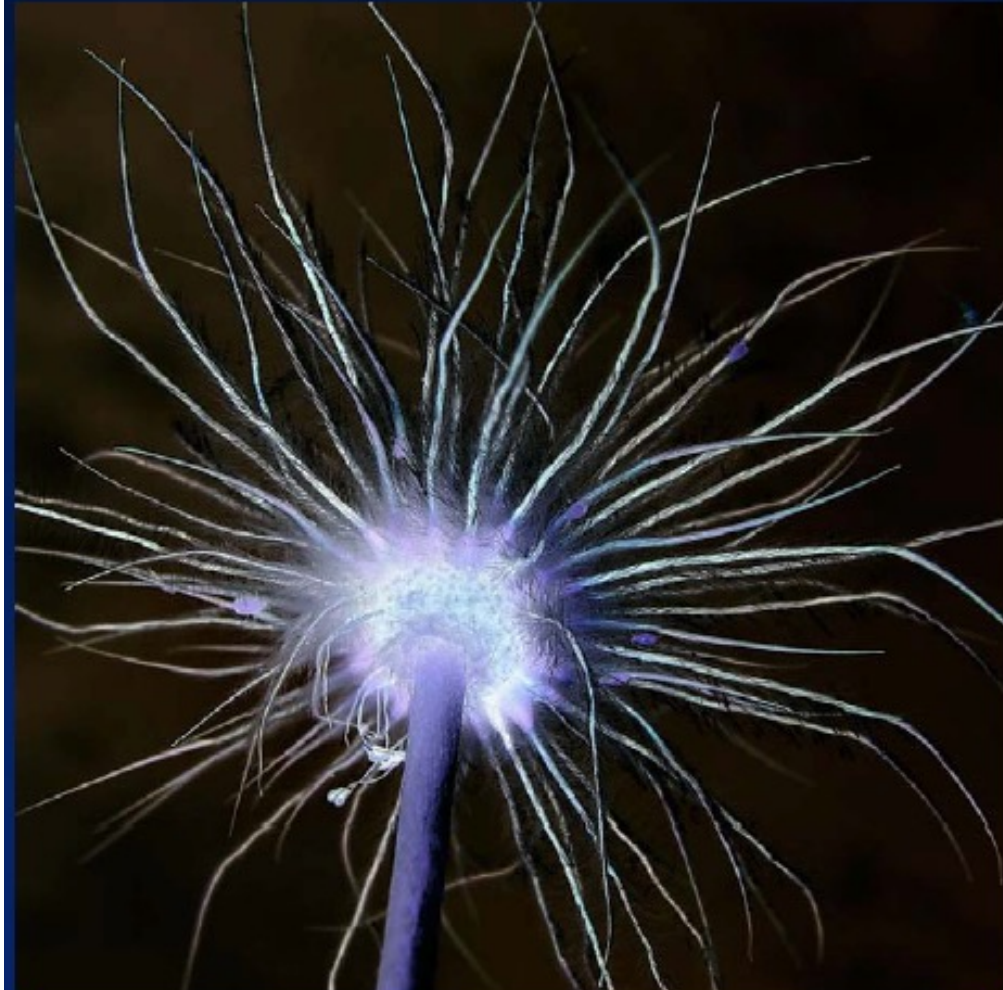


"Look Into" by Josh Brown @ Flickr



Prof - Obvious what one should be looking at, i.e. easy to separate subject from the background.  
Snap – unstructured, busy, filled with clutter.

# Simplicity



"alien flower" by Josef F. Stuefer @ Flickr



# Simplicity



“Waiting in line!” by Imapix @ Flickr

# B&W for Simplicity



Photo by A. A. Efros

# B&W for Simplicity



Photo by A. A. Efros

# B&W for Simplicity



Photo by A. A. Efros

# B&W for Simplicity



Photo by A. A. Efros

...but not always



Photo by A. A. Efros

...but not always

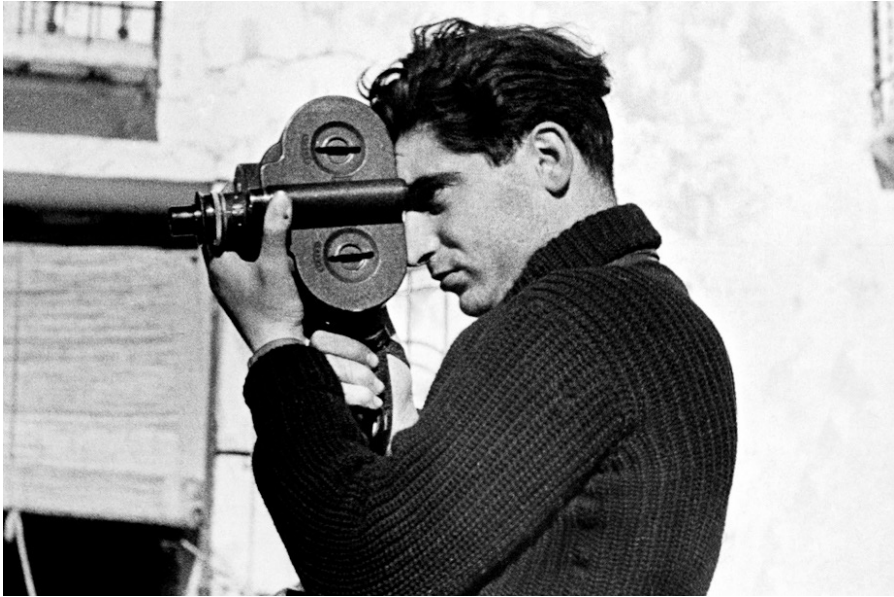


Photo by A. A. Efros

# Crop for Simplicity



# Crop for Simplicity



If your pictures aren't good enough, you're not close enough"  
— Robert Capa



# Clean Backgrounds



# Simplicity for Portraits



<https://vimeo.com/29722267>

# And now, all together...



Photo by A. A. Efros

# And now, all together...



# Get low

Try to be at eye level



Bad



Better

# Get low



# Bad angles



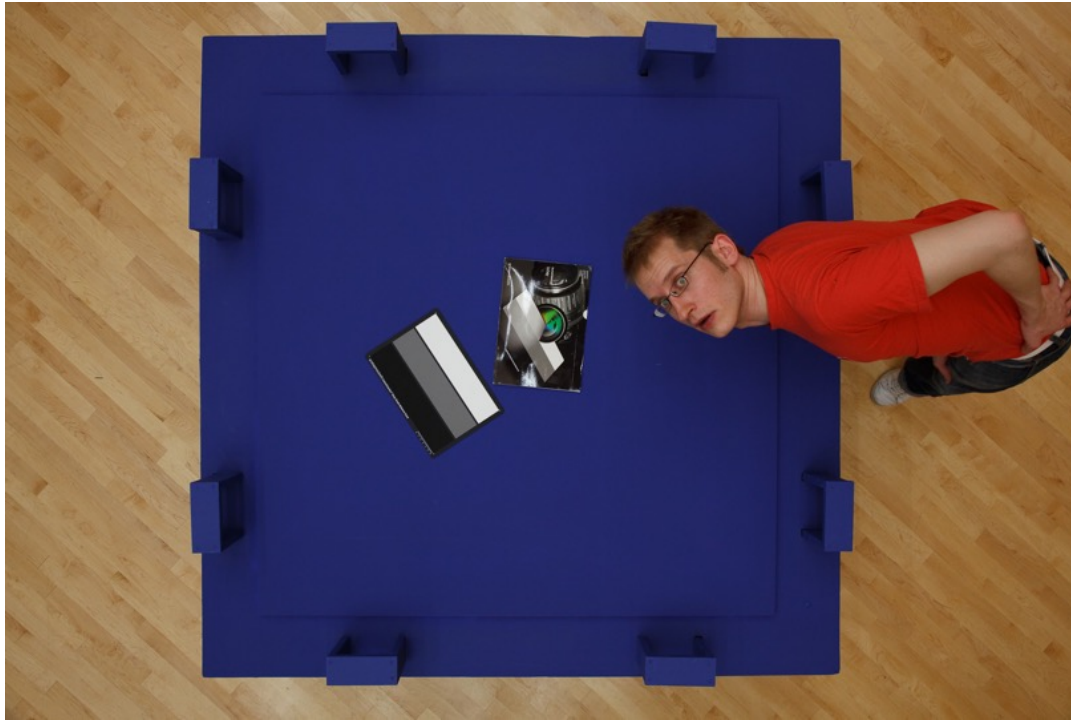
<https://www.youtube.com/watch?v=8EmRZO9fwvk&feature=youtu.be>

# Eye level



# Or really get high

As usual, follow a rule  
or really break it.



# Front Lighting



# Side Lighting



# Back Lighting



# Color Coordination



Complementary colors (of opposite hue on color wheel)

# Go in the shade

Light is more diffuse

Bad



Better



# Overcast days are the best

Just don't put the sky in the frame

The weather conditions



The pictures



Other overcast-day pictures



# Bottom line

Don't get married  
on a sunny day!



# Cloudy day



# Best time of day: sunset & sunrise

+/- 1 hour "Golden hours"

Night photography: always near sunset/sunrise

- because of nice diffuse light

Mid day:  
often not great



less than 1 hour  
after sunrise/  
before sunset



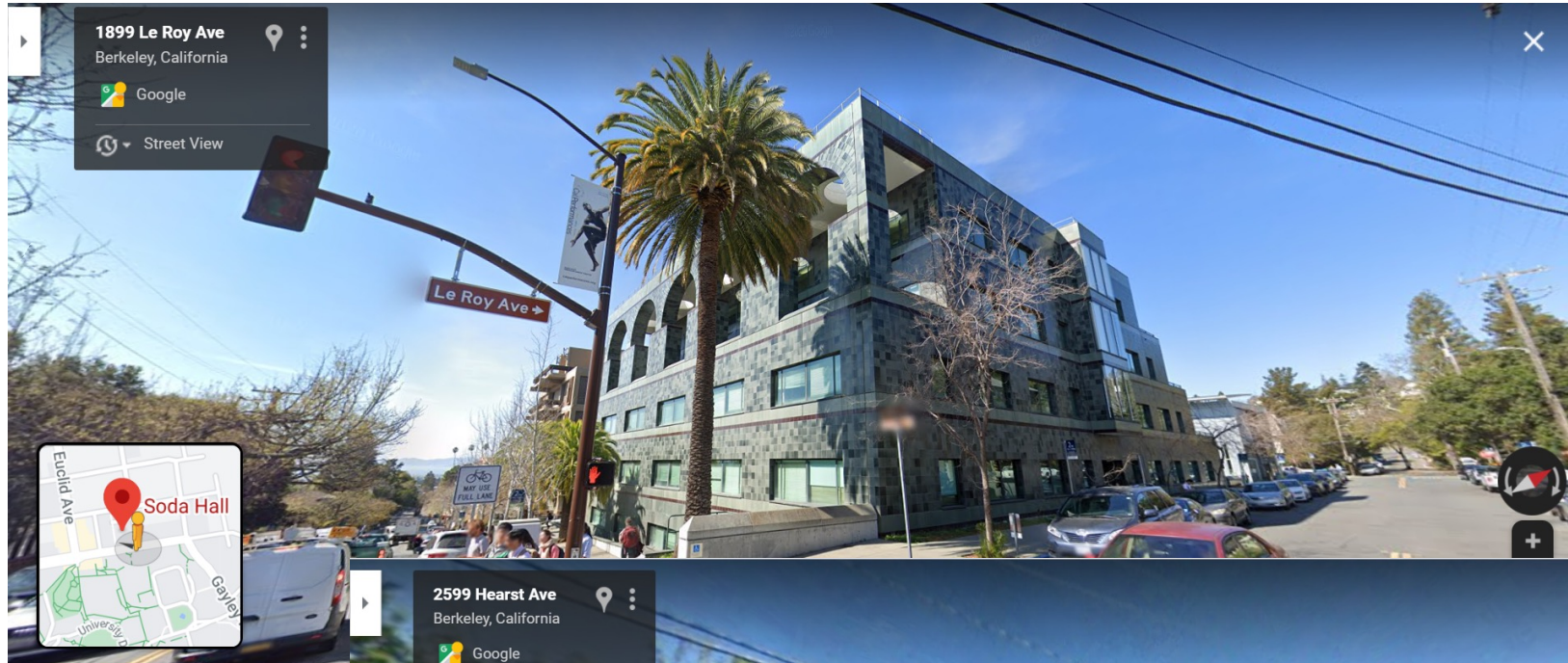
During sunset or  
sunrise



After sunset



# "Golden Hour"



less than 1 hour  
after sunrise



During sunset/sunrise



After sunset



# After sunset: blue hour



# Blue Hour (Russian River)

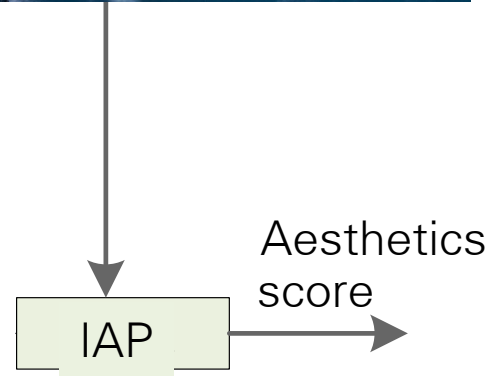


# Image Aesthetics Prediction

- **Goal:** Build computational models that accurately predict human perception of image aesthetics
- No-reference models in nature.

# Image Aesthetics Prediction

Test image



# AVA Dataset

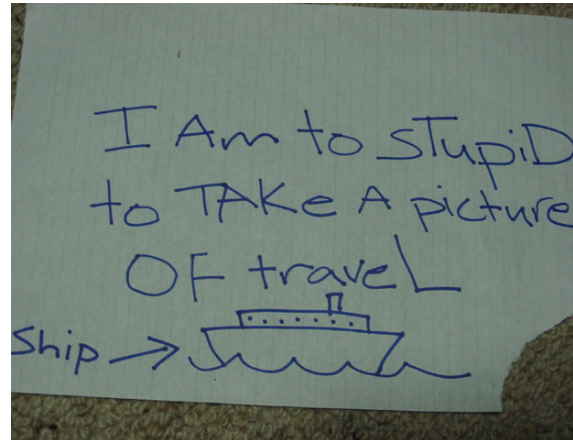
- Images: 255000 (rated based on aesthetic qualities by amateur photographer).
- Each photo is scored by an average of 200 people in response to photography contests.



(a) 6.36 ( $\pm 1.04$ )



(b) 7.84 ( $\pm 2.08$ )



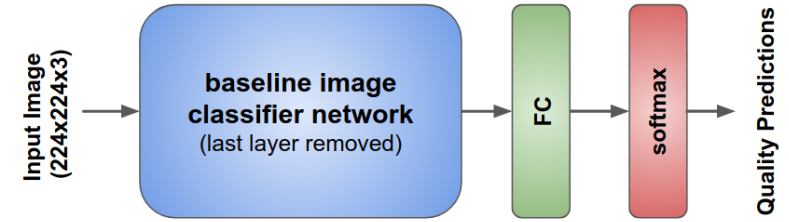
(c) 2.62 ( $\pm 2.15$ )



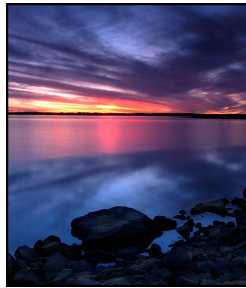
(d) 3.12 ( $\pm 1.28$ )

# NIMA: Neural Image Assessment [Talebi and Milanfar, 2018]

- Instead of predicting the mean opinion score, it predicts the distribution of human opinion scores using a CNN



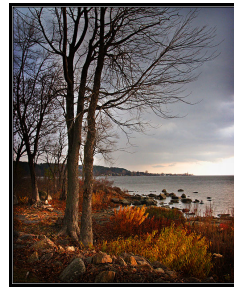
Predicted (and ground truth) scores



(a) 6.38 (7.16)



(b) 6.24 (6.79)



(c) 6.22 (6.64)



(d) 6.16 (6.93)



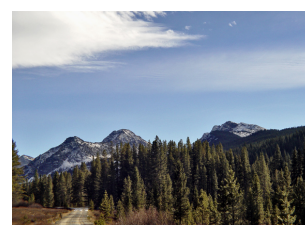
(e) 5.92 (6.23)



(f) 5.71 (5.78)



(g) 5.61 (5.54)



(h) 5.28 (5.32)



(i) 5.11 (5.23)



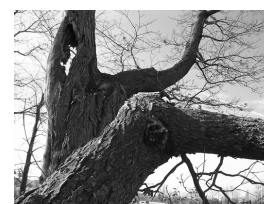
(j) 5.03 (5.35)



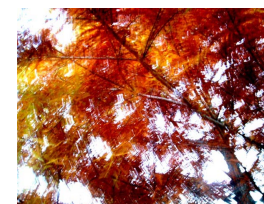
(k) 4.90 (4.91)



(l) 4.83 (4.89)



(m) 4.77 (4.55)



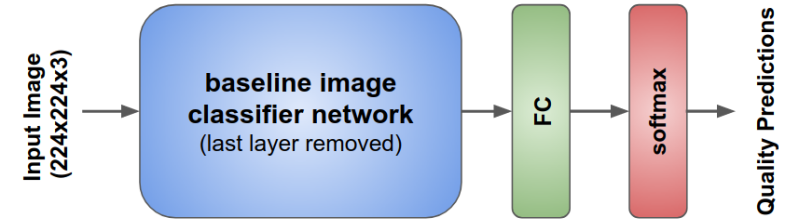
(n) 4.48 (3.95)



(o) 3.55 (3.53)

# NIMA: Neural Image Assessment [Talebi and Milanfar, 2018]

- It can be used for automatic parameter tuning to enhance the quality of the outputs



input (5.18)

enhanced (5.84)



input (4.85)

enhanced (5.44)

# **Next Lecture:** Advanced Topics