BBM 202 - ALGORITHMS



DEPT. OF COMPUTER ENGINEERING

ERKUT ERDEM

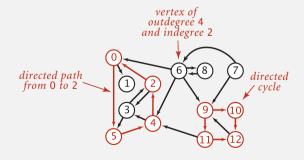
DIRECTED GRAPHS

Mar. 31, 2015

Acknowledgement: The course slides are adapted from the slides prepared by R. Sedgewick and K. Wayne of Princeton University.

Directed graphs

Digraph. Set of vertices connected pairwise by directed edges.

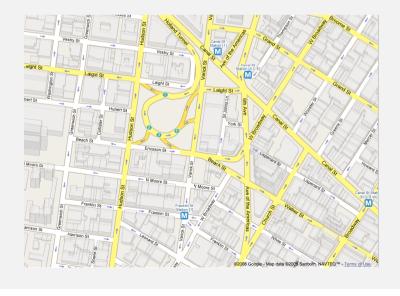


TODAY

- **▶ Directed Graphs**
- ▶ Digraph API
- ▶ Digraph search
- → Topological sort
- Strong components

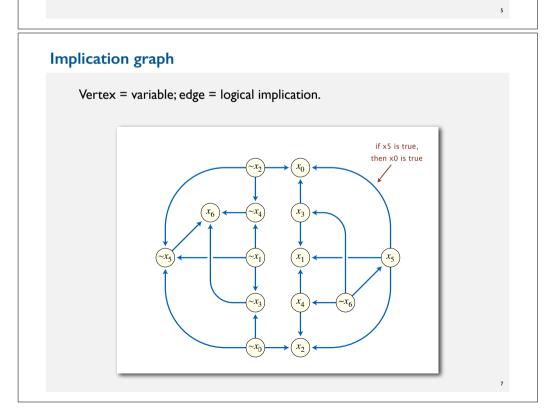
Road network

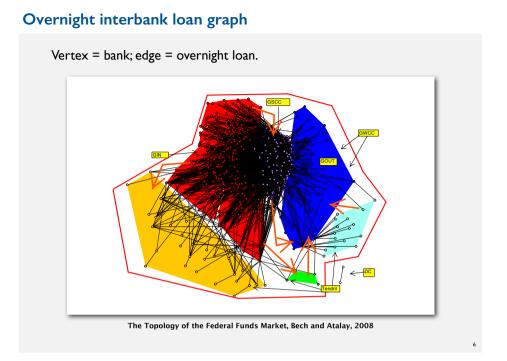
Vertex = intersection; edge = one-way street.

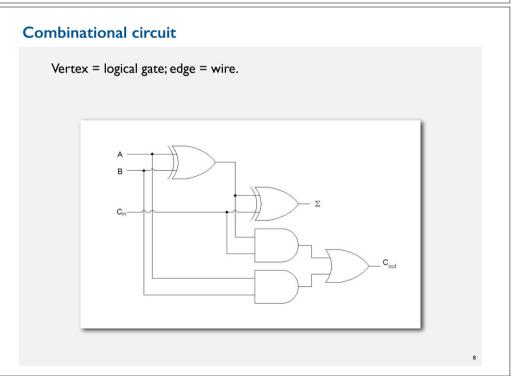


Political blogosphere graph Vertex = political blog; edge = link.

The Political Blogosphere and the 2004 U.S. Election: Divided They Blog, Adamic and Glance, 2005

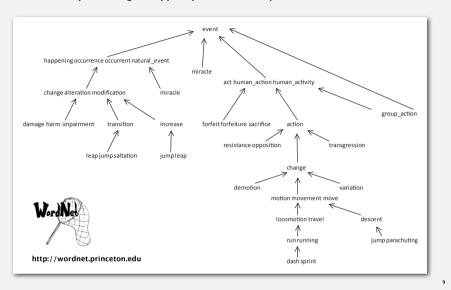






WordNet graph

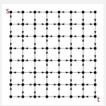
Vertex = synset; edge = hypernym relationship.



Some digraph problems

Path. Is there a directed path from s to t?

Shortest path. What is the shortest directed path from s to t?



Topological sort. Can you draw the digraph so that all edges point upwards?

Strong connectivity. Is there a directed path between all pairs of vertices?

Transitive closure. For which vertices v and w is there a path from v to w?

PageRank. What is the importance of a web page?

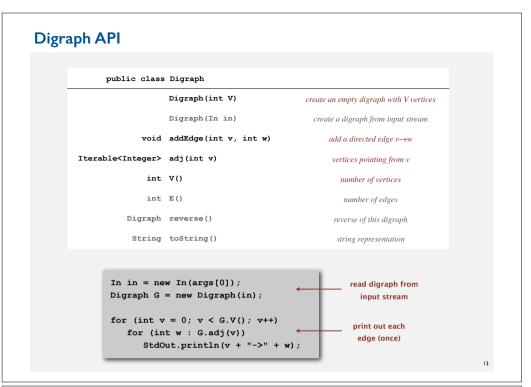
Digraph applications

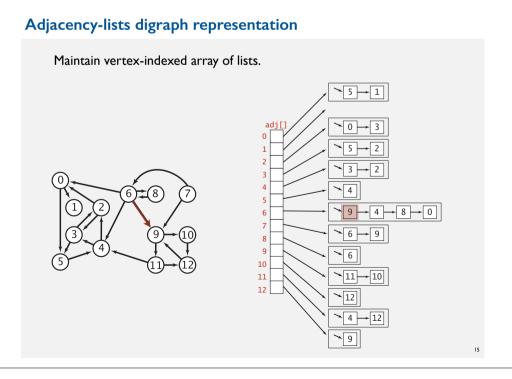
digraph	vertex	directed edge
transportation	street intersection	one-way street
web	web page	hyperlink
food web	species	predator-prey relationship
WordNet	synset	hypernym
scheduling	task	precedence constraint
financial	bank	transaction
cell phone	person	placed call
infectious disease	person	infection
game	board position	legal move
citation	journal article	citation
object graph	object	pointer
inheritance hierarchy	class	inherits from
control flow	code block	jump

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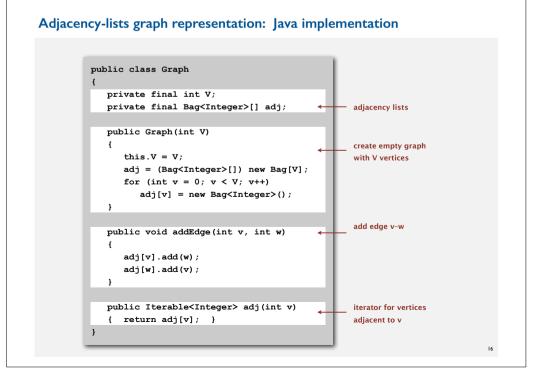
DIRECTED GRAPHS

- **▶** Digraph API
- Digraph search
- **→** Topological sort
- Strong components





Digraph API tinyDG.txt V ____13 % java Digraph tinyDG.txt 22 <u>E</u> 4 2 0->1 2 3 2->0 2->3 6 0 3->5 0 1 3->2 11 12 4->3 12 9 4->2 9 10 5->4 9 11 7 9 11->4 10 12 11 4 11->12 12-9 6 8 8 In in = new In(args[0]); read digraph from Digraph G = new Digraph(in); input stream for (int v = 0; v < G.V(); v++) print out each for (int w : G.adj(v)) edge (once) StdOut.println(v + "->" + w);



Adjacency-lists digraph representation: Java implementation

```
public class Digraph
  private final int V;
  private final Bag<Integer>[] adj;
                                                   adjacency lists
  public Digraph(int V)
                                                   create empty digraph
      this.V = V;
                                                   with V vertices
      adj = (Bag<Integer>[]) new Bag[V];
      for (int v = 0; v < V; v++)
         adj[v] = new Bag<Integer>();
                                                   add edge v→w
  public void addEdge(int v, int w)
      adj[v].add(w);
  public Iterable<Integer> adj(int v)
                                                   iterator for vertices
   { return adj[v]; }
                                                   pointing from v
```

DIRECTED GRAPHS

- **▶** Digraph API
- → Digraph search
- **→** Topological sort
- Strong components

Digraph representations

In practice. Use adjacency-lists representation.

- Algorithms based on iterating over vertices pointing from v.
- Real-world digraphs tend to be sparse.

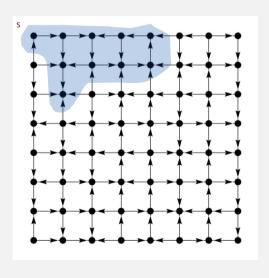
huge number of vertices, small average vertex degree

representation	space	insert edge from v to w	edge from v to w?	iterate over vertices pointing from v?
list of edges	E	1	E	E
adjacency matrix	V ²	1 †	1	V
adjacency lists	E + V	1	outdegree(v)	outdegree(v)

† disallows parallel edges

Reachability

Problem. Find all vertices reachable from *s* along a directed path.



Depth-first search in digraphs

Same method as for undirected graphs.

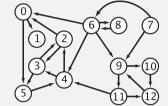
- Every undirected graph is a digraph (with edges in both directions).
- DFS is a digraph algorithm.

DFS (to visit a vertex v)

Mark v as visited.

Recursively visit all unmarked

vertices w pointing from v.

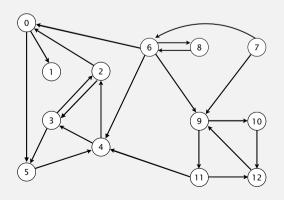


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Depth-first search

To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices pointing from v.



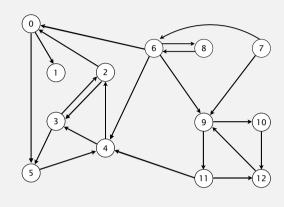
a directed graph

v	marked[]	edgeTo[]
0	F	-
1	F	-
2	F	-
3	F	-
4	F	-
5	F	-
6	F	-
7	F	-
8	F	-
9	F	-
10	F	-
11	F	-
12	F	- 2:

Depth-first search

To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices pointing from v.



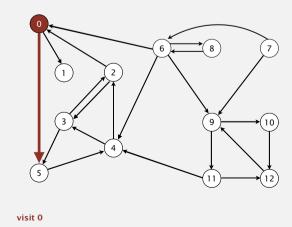
a directed graph

4→2
2→3
3→2
6→0
0→1
2→0
11→12
12→9
9→10
9→11
8→9
10→12
11→4
4→3
3→5
6→8
8→6
5→4
0→5
6→4

Depth-first search

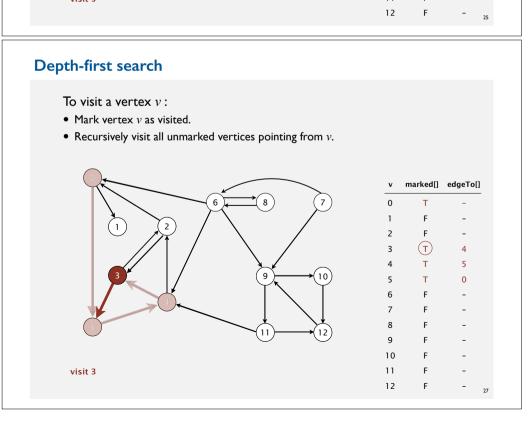
To visit a vertex v:

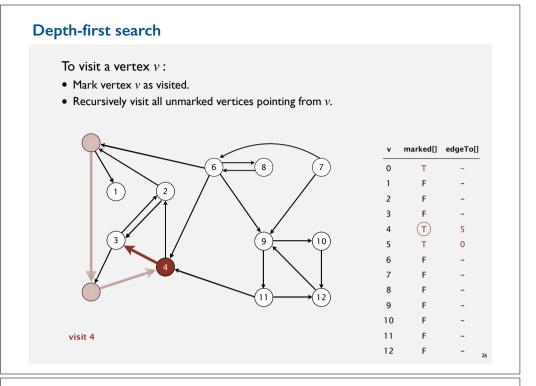
- Mark vertex v as visited.
- Recursively visit all unmarked vertices pointing from v.

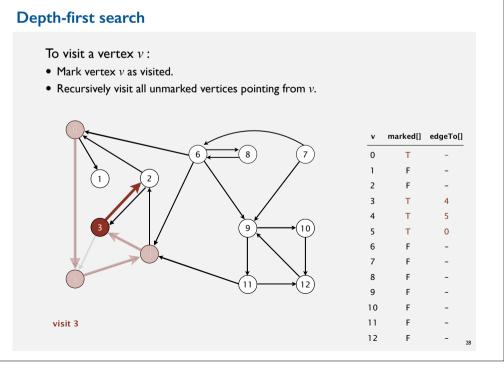


v	marked[]	edgeTo[]
0	T	-
1	F	-
2	F	-
3	F	-
4	F	-
5	F	-
6	F	-
7	F	-
8	F	-
9	F	-
10	F	-
11	F	-
12	F	-

Depth-first search To visit a vertex ν: • Mark vertex ν as visited. • Recursively visit all unmarked vertices pointing from ν. v marked[] edgeTo[] 0 T 1 F 2 F 3 F 4 F 3 F 4 F 5 T 0 6 F 7 F 8 F 9 F 10 F 10 F 11 F 1



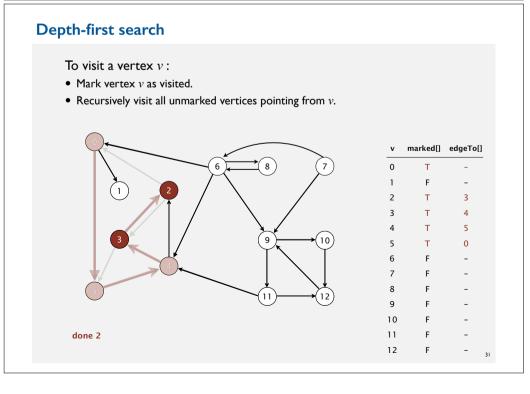


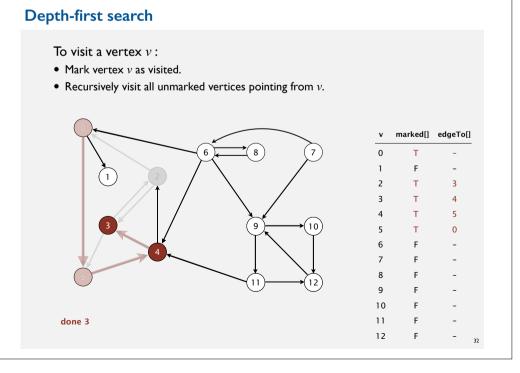


Depth-first search To visit a vertex v: • Mark vertex v as visited. • Recursively visit all unmarked vertices pointing from v. | v marked[] edgeTo[] | 0 T - 1 F - 2 T 3 3 T 4 4 T 5 5 T 0 6 F - 7 F - 8 F - 8 F - 7 F - 8 F - 8 F - 7 F - 8 F -

visit 2

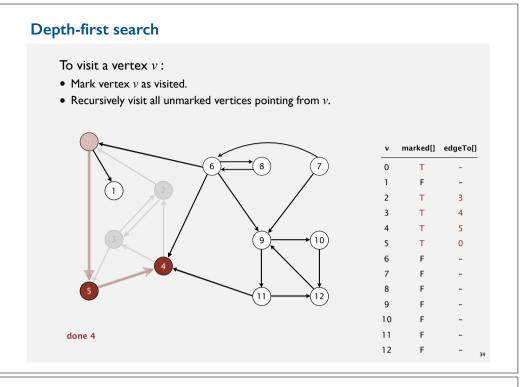
To visit a vertex v: • Mark vertex v as visited. • Recursively visit all unmarked vertices pointing from v. $\frac{v \text{ marked[] edgeTo[]}}{0 \text{ T }}$ \frac

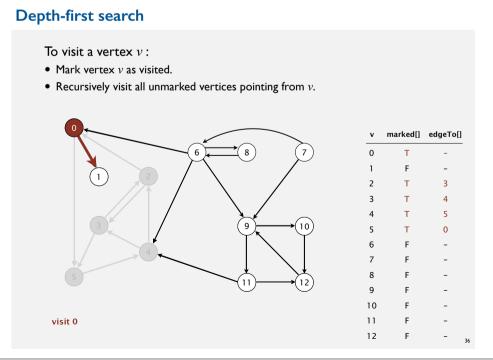


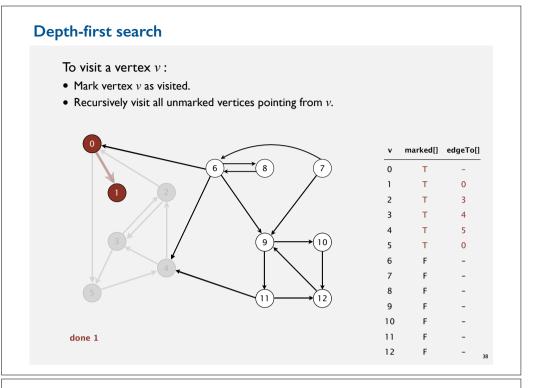


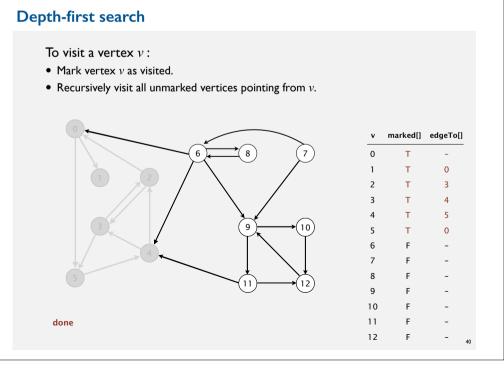
visit 4

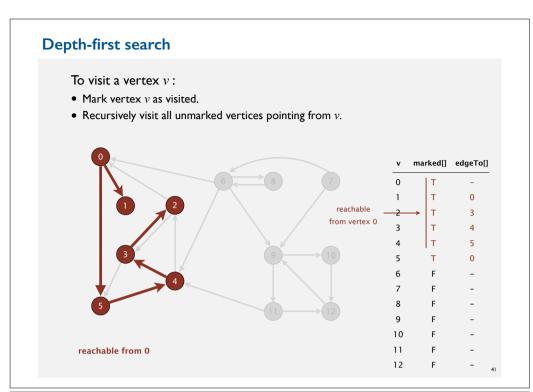
Depth-first search To visit a vertex v: • Mark vertex v as visited. • Recursively visit all unmarked vertices pointing from v. $\frac{v \text{ marked}[] \text{ edgeTo}[]}{0 \text{ T} - \frac{1}{1} \text{ F} - \frac{2}{2} \text{ T} - \frac{3}{3}}$ $\frac{3}{3} \text{ T} - \frac{4}{4} \text{ T} - \frac{5}{5} \text{ T} - \frac{1}{3} \text{ Grade of } \frac{1}{1} \text{ F} - \frac{1}{2} \text{ F} - \frac{1}{3} \text{ Grade of } \frac{1}{1} \text{ F} - \frac{1}{3} \text{ Grade of } \frac{1}{1} \text{ F} - \frac{1}{3} \text{ Grade of } \frac{1}{1} \text{ F} - \frac{1}{3} \text{ Grade of } \frac{1}{1} \text{ F} - \frac{1}{3} \text{ Grade of } \frac{1}{$

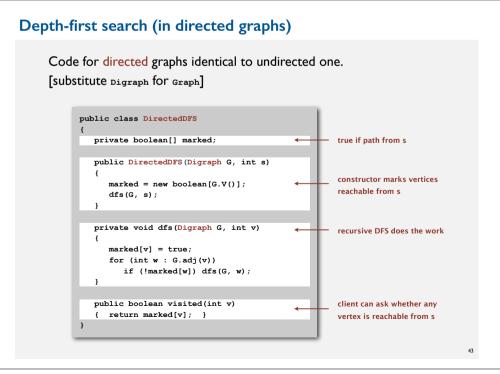


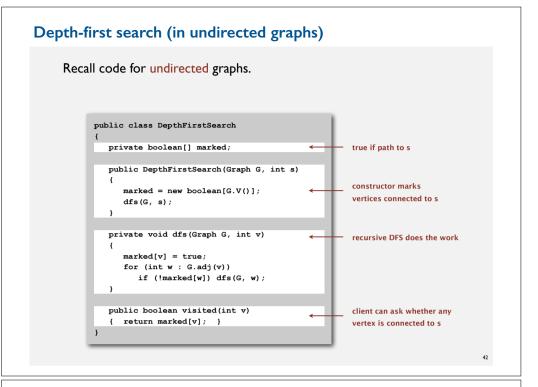












Reachability application: program control-flow analysis

Every program is a digraph.

• Vertex = basic block of instructions (straight-line program).

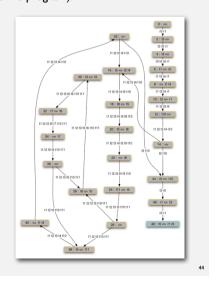
Edge = jump.

Dead-code elimination.

Find (and remove) unreachable code.

Infinite-loop detection.

Determine whether exit is unreachable.



Reachability application: mark-sweep garbage collector

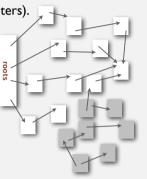
Every data structure is a digraph.

- Vertex = object.
- Edge = reference.

Roots. Objects known to be directly accessible by program (e.g., stack).

Reachable objects. Objects indirectly accessible by program

(starting at a root and following a chain of pointers).



Depth-first search in digraphs summary

DFS enables direct solution of simple digraph problems.

- ✓ Reachability.
 - Path finding.
 - Topological sort.
 - Directed cycle detection.

Basis for solving difficult digraph problems.

- 2-satisfiability.
- Directed Euler path.
- Strongly-connected components.

SIAM J. COMPUT.

DEPTH-FIRST SEARCH AND LINEAR GRAPH ALGORITHMS*

ROBERT TARJAN†

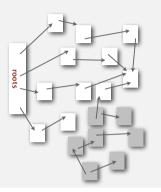
Abstract. The value of dayth first search or "backtracking" as a technique for solving problems is illustrated by two examples. An improved version of an algorithm for finding the terrongly connected components of a directed graph and an algorithm for finding the bloomered components of an undirect graph are presented. The space and time requirements of both algorithms are bounded by $k_1 V + k_2 F + k_3$ for some constants k_1 , k_2 , and k_3 , where V is the number of vertices and E is the number of edges of the graph being examined.

Reachability application: mark-sweep garbage collector

Mark-sweep algorithm. [McCarthy, 1960]

- Mark: mark all reachable objects.
- Sweep: if object is unmarked, it is garbage (so add to free list).

Memory cost. Uses I extra mark bit per object (plus DFS stack).



Breadth-first search in digraphs

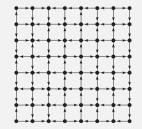
Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- BFS is a digraph algorithm.

BFS (from source vertex s)

Put s onto a FIFO queue, and mark s as visited. Repeat until the queue is empty:

- remove the least recently added vertex v
- for each unmarked vertex pointing from v: add to gueue and mark as visited.



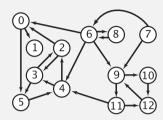
Proposition. BFS computes shortest paths (fewest number of edges) from s to all other vertices n a digraph in time proportional to E+V.

Multiple-source shortest paths

Multiple-source shortest paths. Given a digraph and a set of source vertices, find shortest path from any vertex in the set to each other vertex.

Ex.
$$S=\{1, 7, 10\}.$$

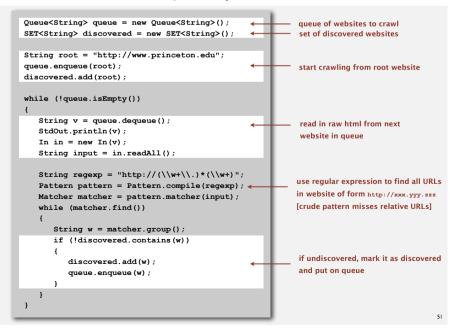
- Shortest path to 4 is $7\rightarrow 6\rightarrow 4$.
- Shortest path to 5 is $7 \rightarrow 6 \rightarrow 0 \rightarrow 5$.
- Shortest path to 12 is $10\rightarrow12$.



- Q. How to implement multi-source constructor?
- A. Use BFS, but initialize by enqueuing all source vertices.

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Bare-bones web crawler: Java implementation



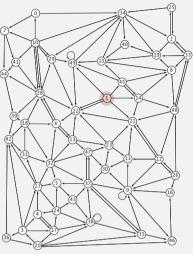
Breadth-first search in digraphs application: web crawler

Goal. Crawl web, starting from some root web page, say www.princeton.edu. Solution. BFS with implicit graph.

BFS.

- Choose root web page as source s.
- Maintain a Queue of websites to explore.
- Maintain a SET of discovered websites.
- Dequeue the next website and enqueue websites to which it links (provided you haven't done so before).

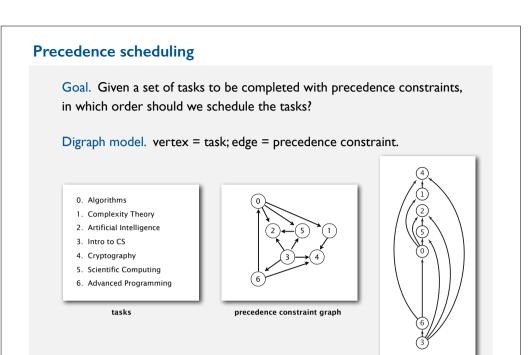
Q. Why not use DFS?

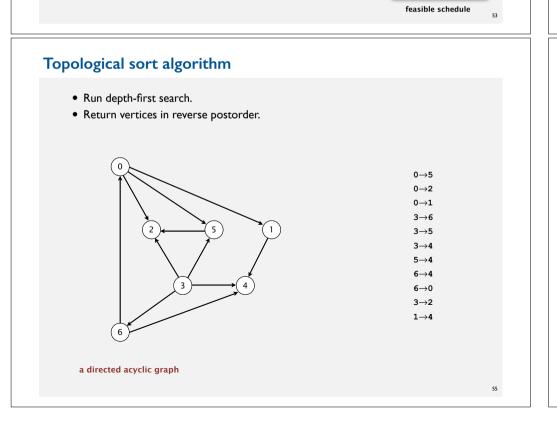


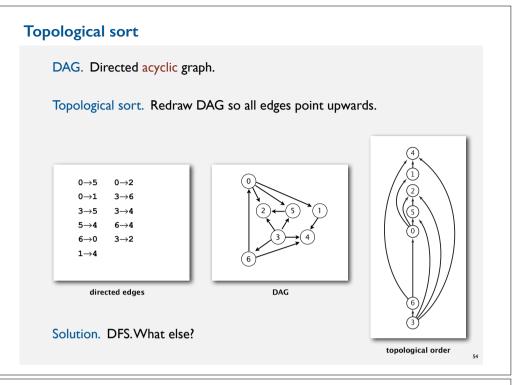
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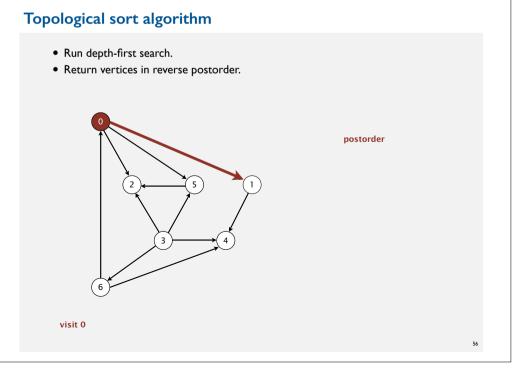
DIRECTED GRAPHS

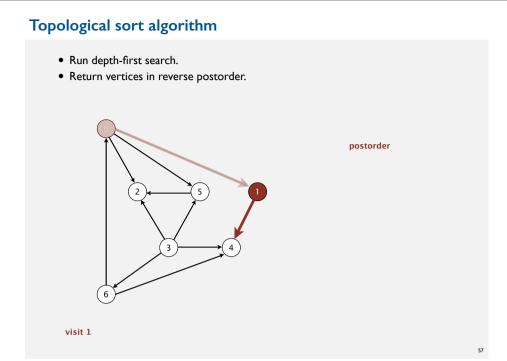
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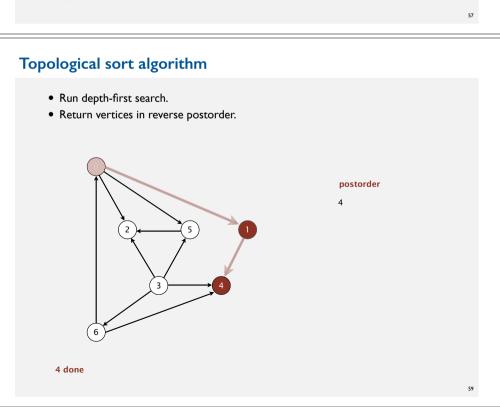


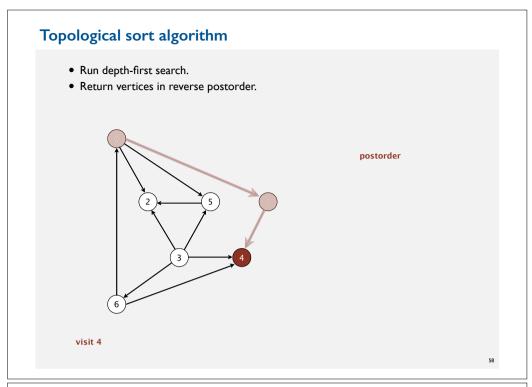


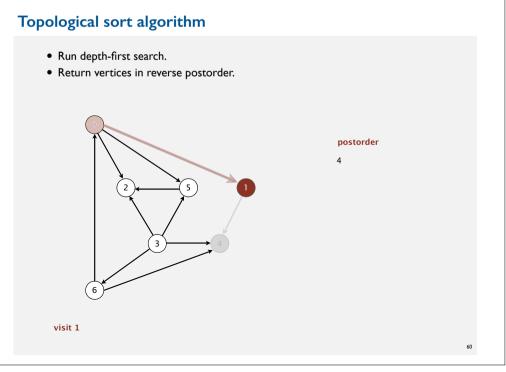


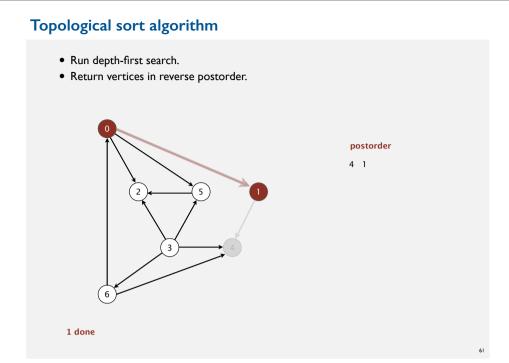


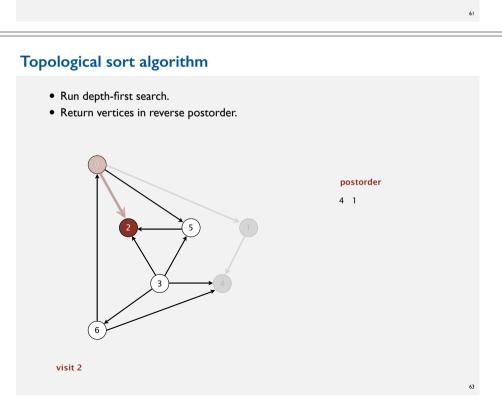


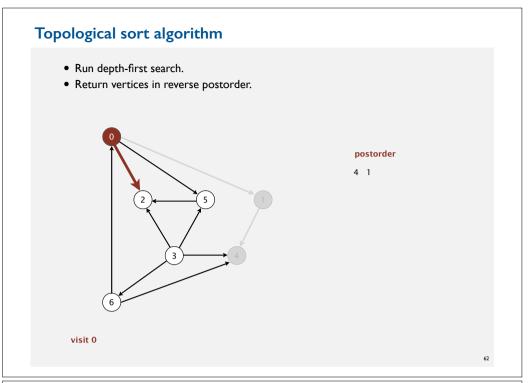


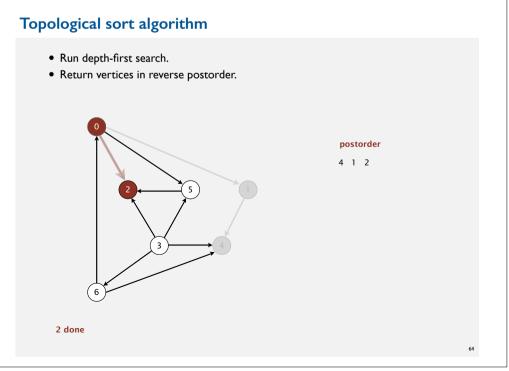


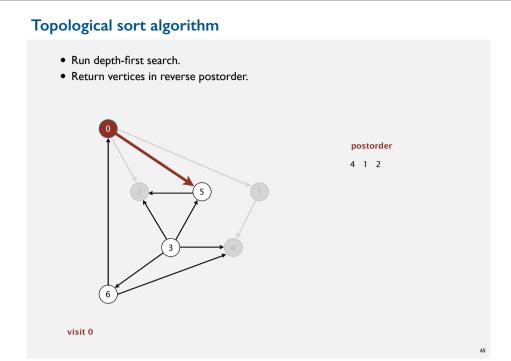


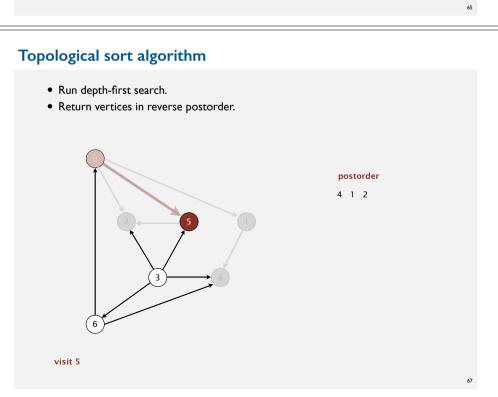


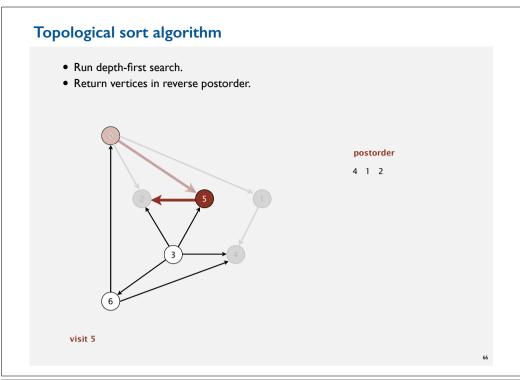


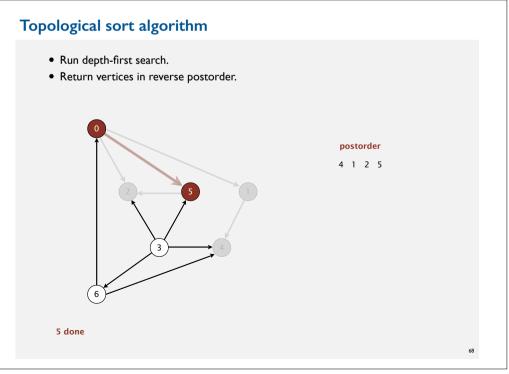


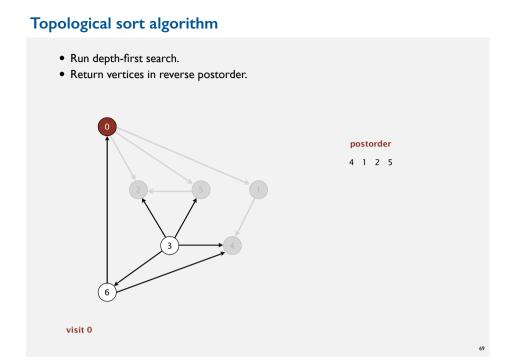


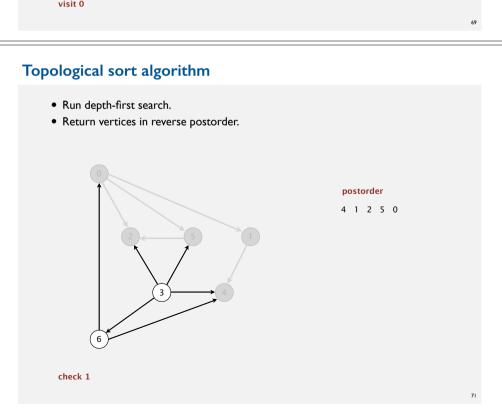


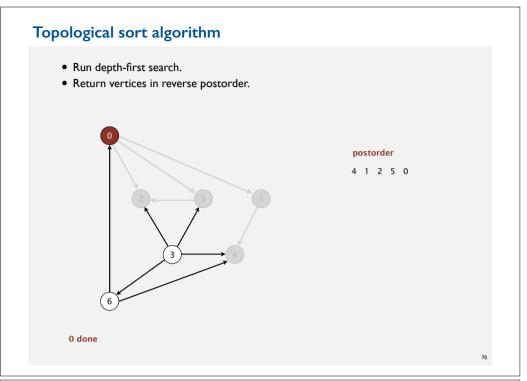


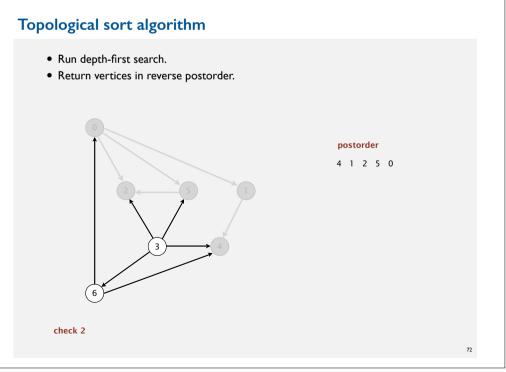


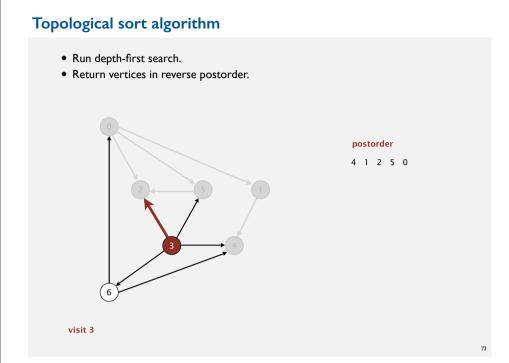


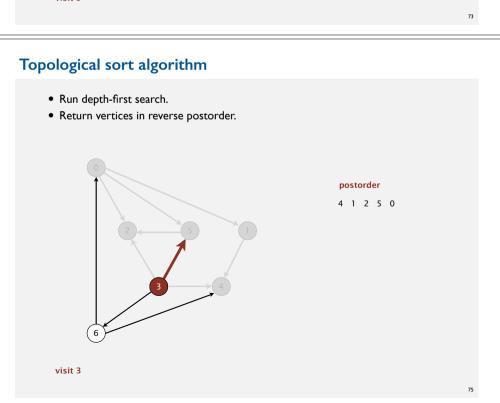


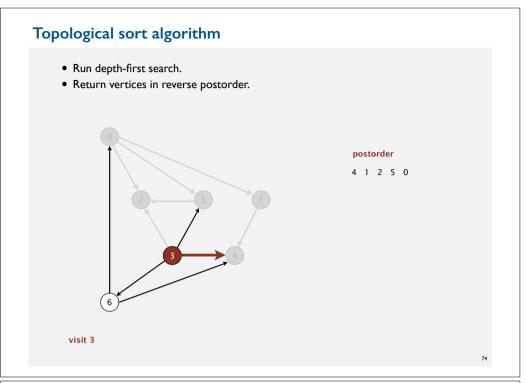


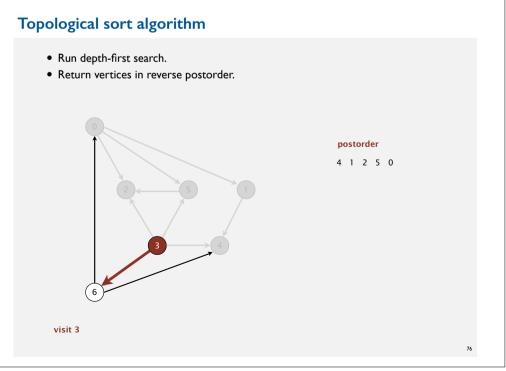


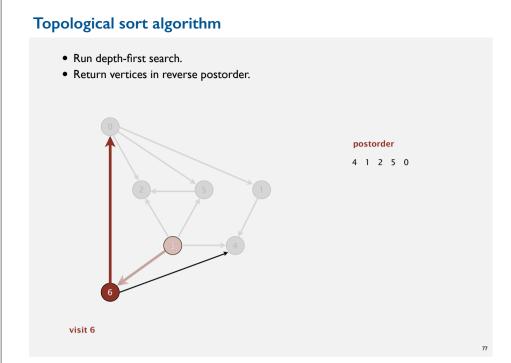


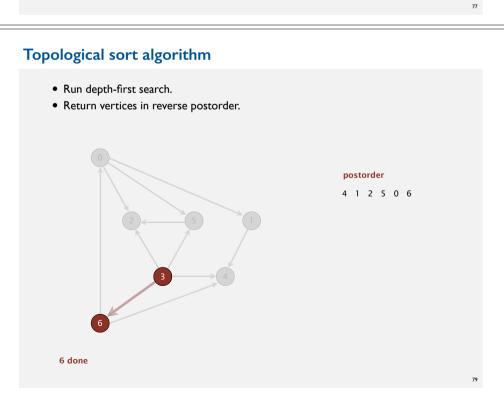


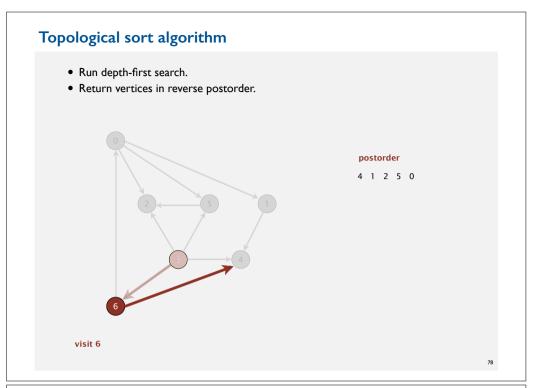


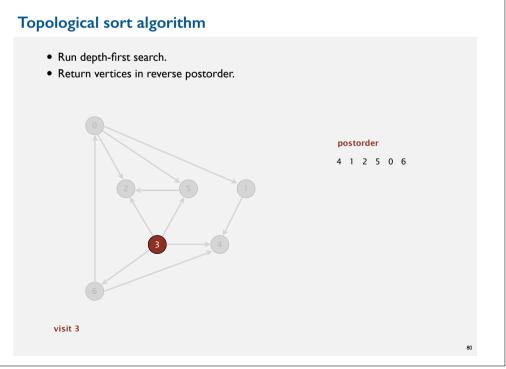


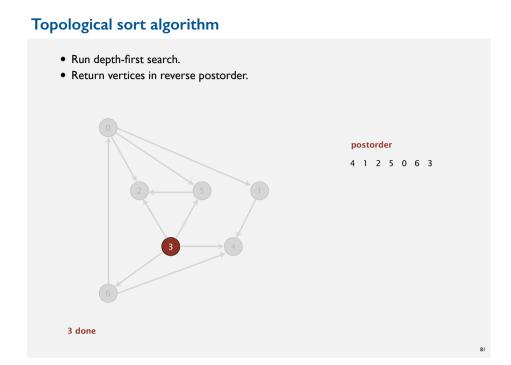


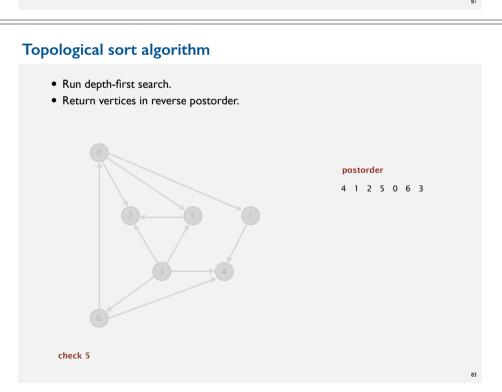


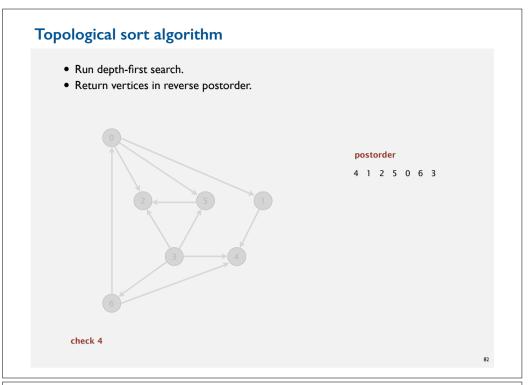


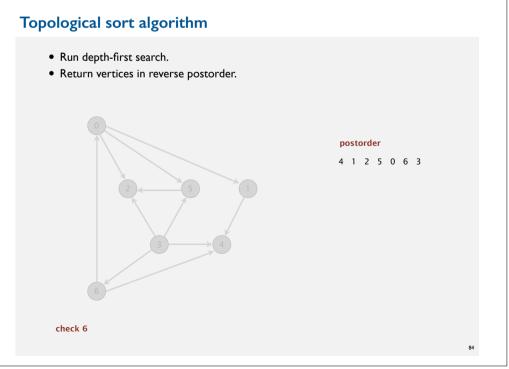


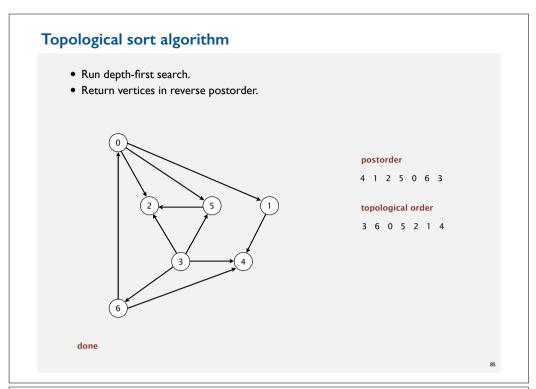




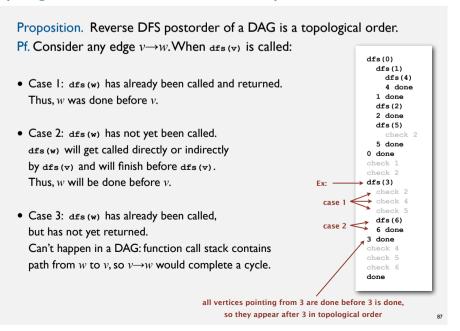








Topological sort in a DAG: correctness proof



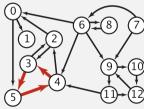
Depth-first search order

```
public class DepthFirstOrder
  private boolean[] marked;
  private Stack<Integer> reversePost;
  public DepthFirstOrder(Digraph G)
      reversePost = new Stack<Integer>();
     marked = new boolean[G.V()];
      for (int v = 0; v < G.V(); v++)
         if (!marked[v]) dfs(G, v);
  private void dfs(Digraph G, int v)
     marked[v] = true;
     for (int w : G.adj(v))
         if (!marked[w]) dfs(G, w);
     reversePost.push(v);
  public Iterable<Integer> reversePost()
                                                     returns all vertices in
   { return reversePost; }
                                                     "reverse DFS postorder"
```

Directed cycle detection

Proposition. A digraph has a topological order iff no directed cycle. Pf.

- If directed cycle, topological order impossible.
- If no directed cycle, DFS-based algorithm finds a topological order.



a digraph with a directed cycle

Goal. Given a digraph, find a directed cycle. Solution. DFS. What else? See textbook.

Directed cycle detection application: precedence scheduling

Scheduling. Given a set of tasks to be completed with precedence constraints, in what order should we schedule the tasks?

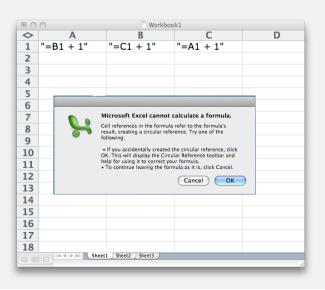
PAG	E 3			
DE	PARTMENT	COURSE	DESCRIPTION	PREREQS
	MPUTER CIENCE		INTERMEDIATE COMPILER DESIGN, WITH A FOCUS ON DEPENDENCY RESOLUTION.	CPSC 432
			Waller of Columbia Description	~

http://xkcd.com/754

Remark. A directed cycle implies scheduling problem is infeasible.

Directed cycle detection application: spreadsheet recalculation

Microsoft Excel does cycle detection (and has a circular reference toolbar!)



Directed cycle detection application: cyclic inheritance

The Java compiler does cycle detection.

```
public class A extends B
{
    ...
}
```

```
public class B extends C
{
    ...
}
```

```
public class C extends A
{
    ...
}
```

```
% javac A.java
A.java:1: cyclic inheritance
involving A
public class A extends B { }
^
1 error
```

70

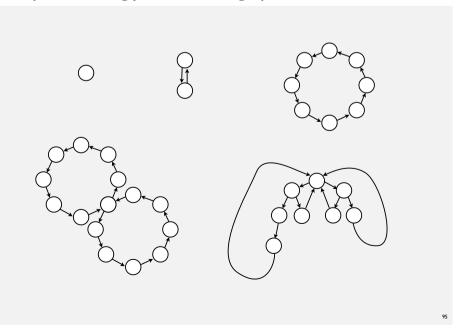
Directed cycle detection applications

- Causalities.
- Email loops.
- Compilation units.
- Class inheritance.
- Course prerequisites.
- Deadlocking detection.
- Precedence scheduling.
- Temporal dependencies.
- Pipeline of computing jobs.
- Check for symbolic link loop.
- Evaluate formula in spreadsheet.

DIRECTED GRAPHS

- **▶** Digraph API
- ▶ Digraph search
- **→** Topological sort
- Strong components

Examples of strongly-connected digraphs



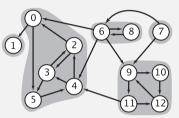
Strongly-connected components

Def. Vertices v and w are strongly connected if there is a directed path from v to w and a directed path from w to v.

Key property. Strong connectivity is an equivalence relation:

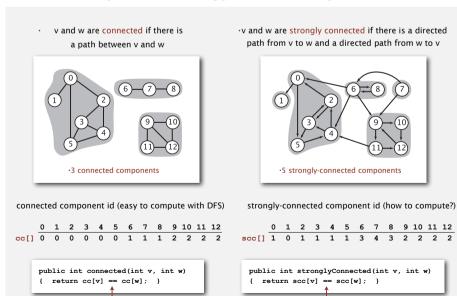
- *v* is strongly connected to *v*.
- If v is strongly connected to w, then w is strongly connected to v.
- If v is strongly connected to w and w to x, then v is strongly connected to x.

Def. A strong component is a maximal subset of strongly-connected vertices.



9

Connected components vs. strongly-connected components

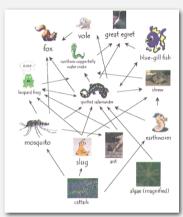


constant-time client strong-connectivity query

constant-time client connectivity query

Strong component application: ecological food webs

Food web graph. Vertex = species; edge = from producer to consumer.



http://www.twingroves.district96.k12.il.us/Wetlands/Salamander/SalGraphics/salfoodweb.gi

Strong component. Subset of species with common energy flow.

Strong components algorithms: brief history

1960s: Core OR problem.

- Widely studied; some practical algorithms.
- Complexity not understood.

1972: linear-time DFS algorithm (Tarjan).

- Classic algorithm.
- Level of difficulty: Algs4++.
- Demonstrated broad applicability and importance of DFS.

1980s: easy two-pass linear-time algorithm (Kosaraju-Sharir).

- Forgot notes for lecture; developed algorithm in order to teach it!
- Later found in Russian scientific literature (1972).

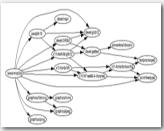
1990s: more easy linear-time algorithms.

- Gabow: fixed old OR algorithm.
- Cheriyan-Mehlhorn: needed one-pass algorithm for LEDA.

Strong component application: software modules

Software module dependency graph.

- Vertex = software module.
- Edge: from module to dependency.



Internet Explorer

Strong component. Subset of mutually interacting modules.

Approach I. Package strong components together.

Approach 2. Use to improve design!

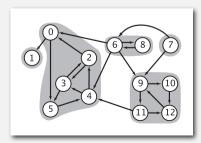
Kosaraju's algorithm: intuition

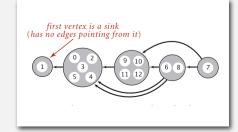
Reverse graph. Strong components in G are same as in G^R .

Kernel DAG. Contract each strong component into a single vertex.

Idea.

- how to compute?
- Compute topological order (reverse postorder) in kernel DAG.
- Run DFS, considering vertices in reverse topological order.



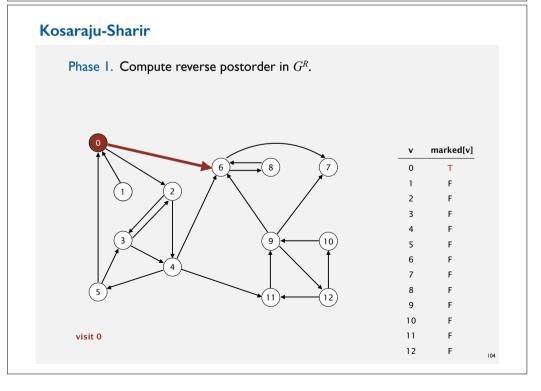


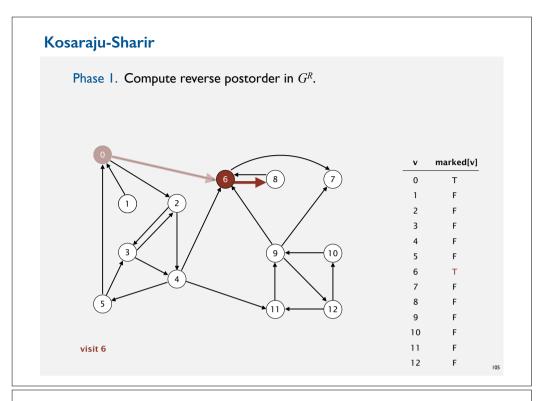
digraph G and its strong components

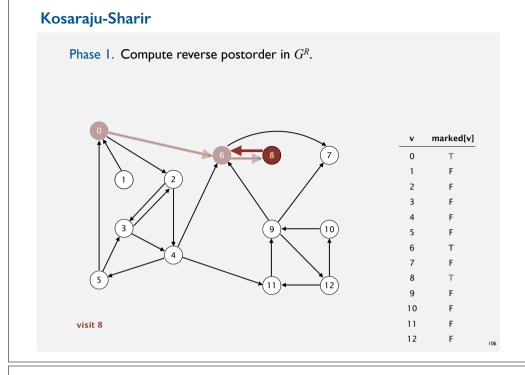
kernel DAG of G (in reverse topological order)

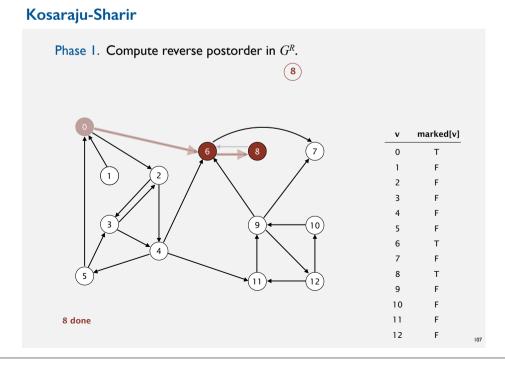
Kosaraju's Algorithm

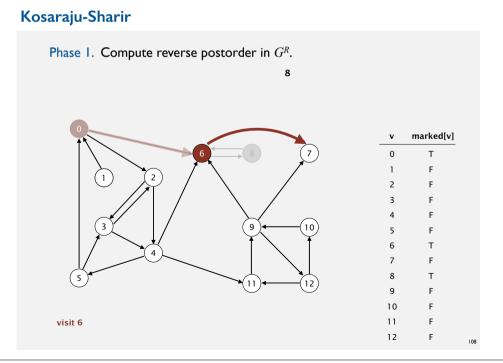
- ▶ DFS in reverse graph
- **▶ DFS in original graph**

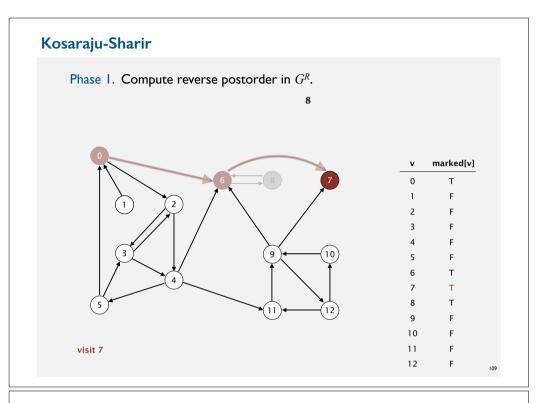


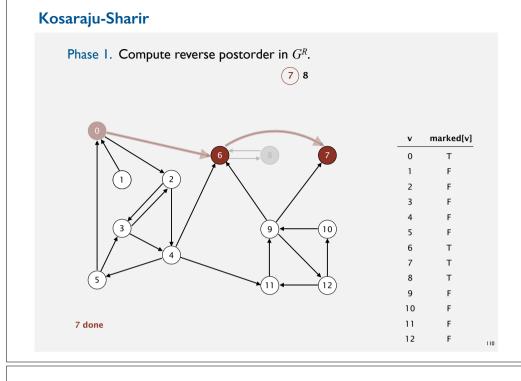


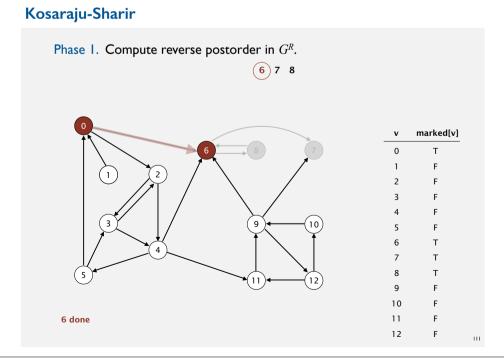


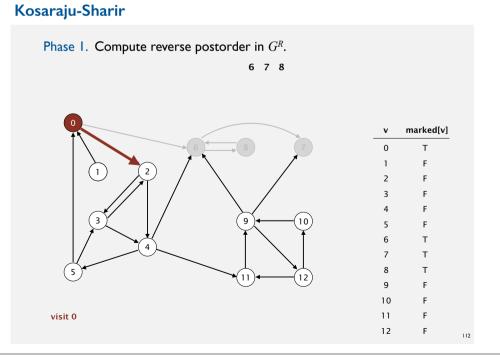


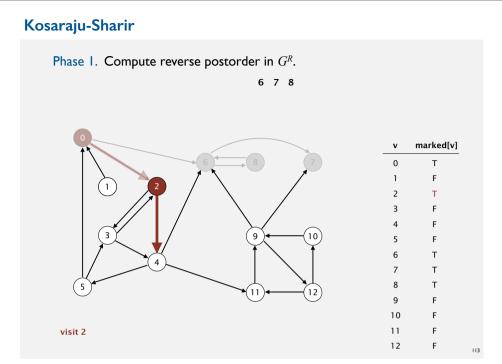


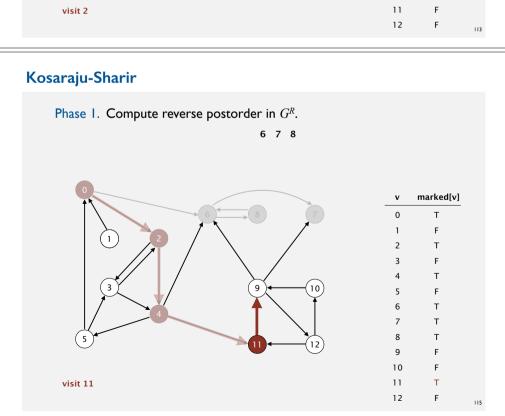


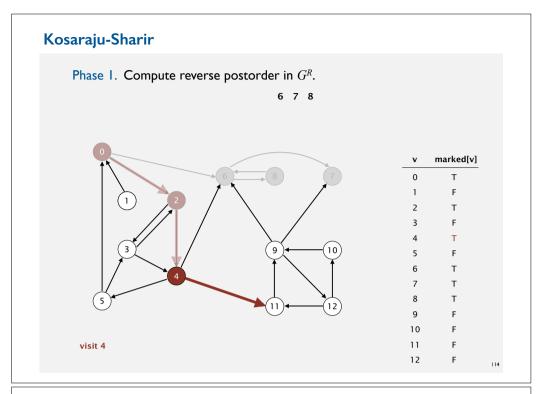


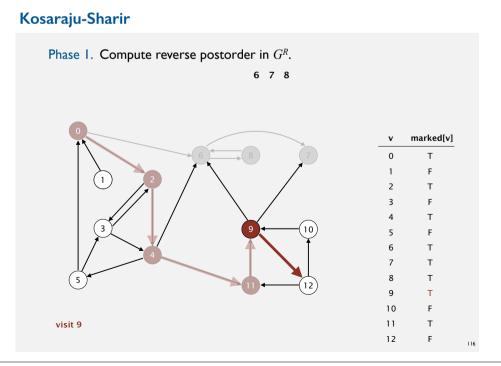


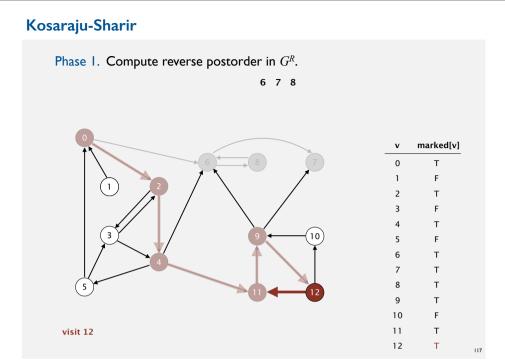


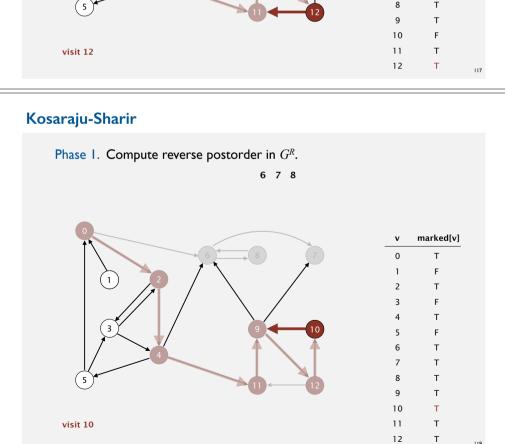


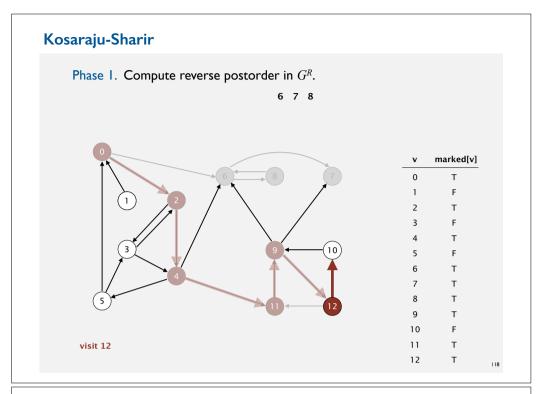


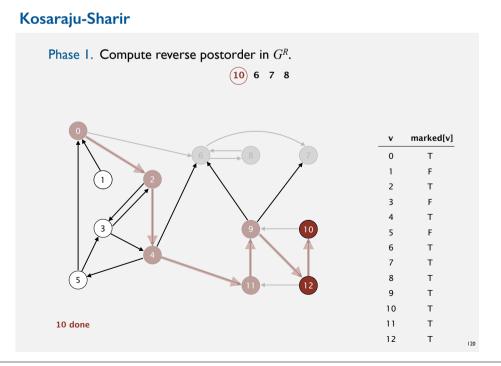


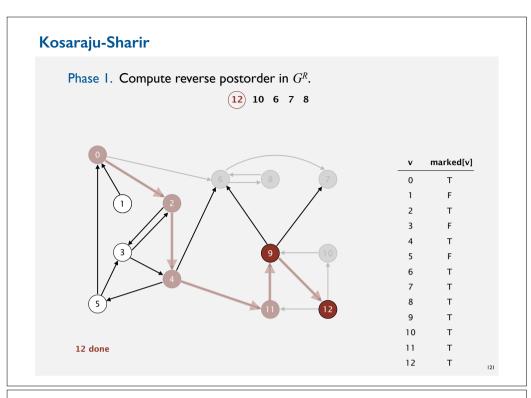


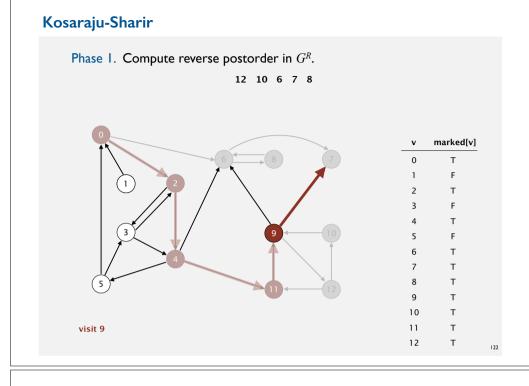


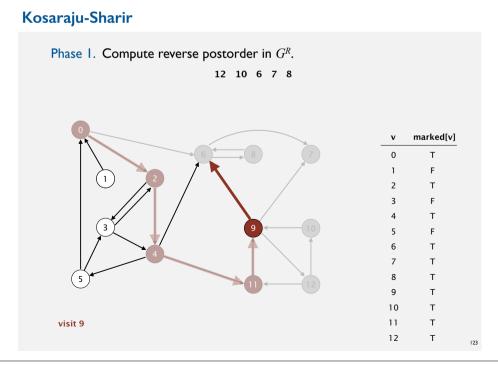


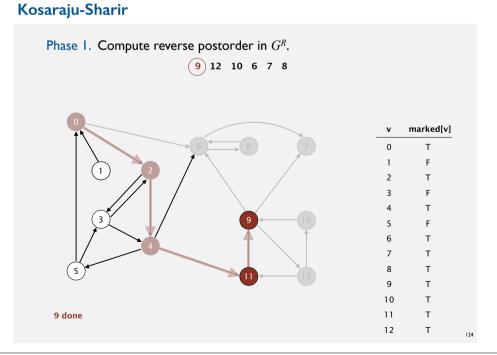


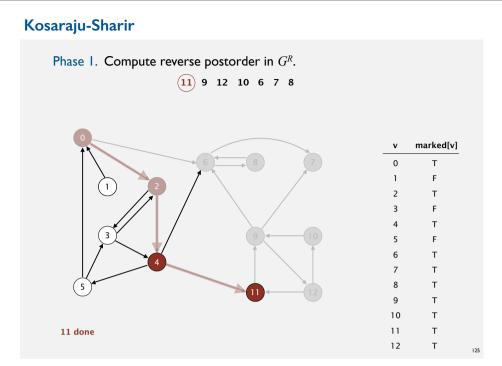


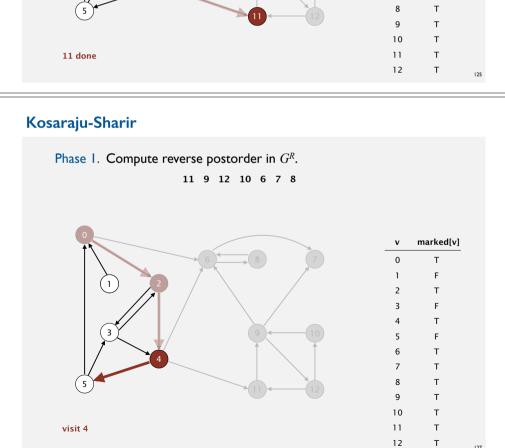


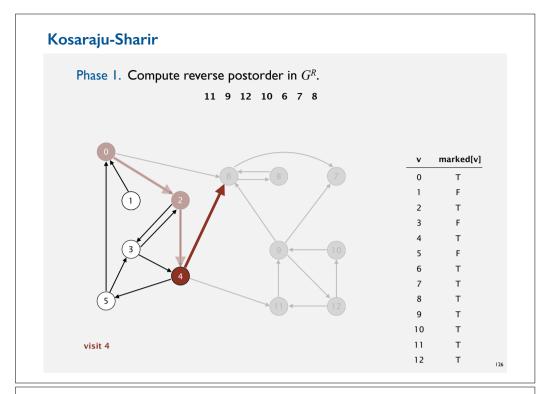


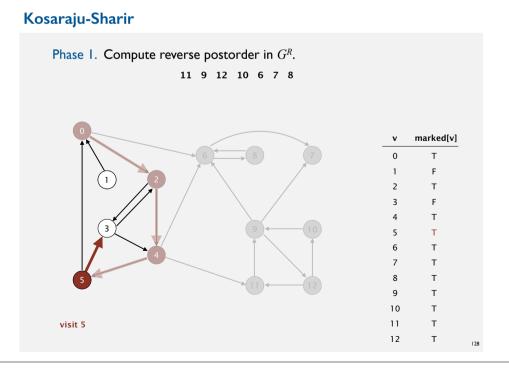


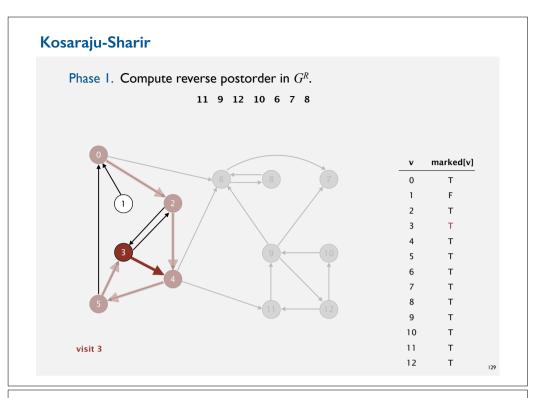


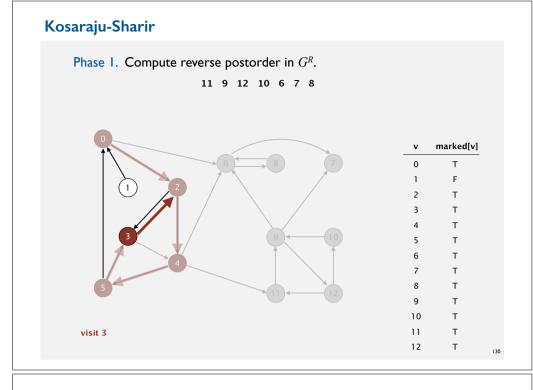


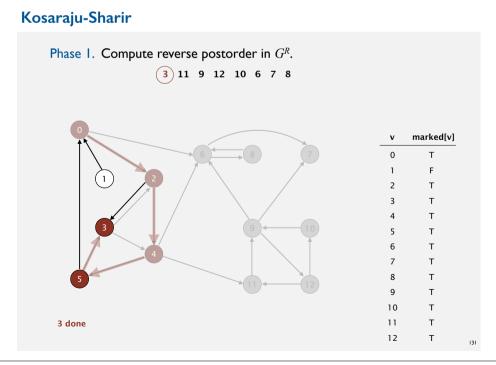


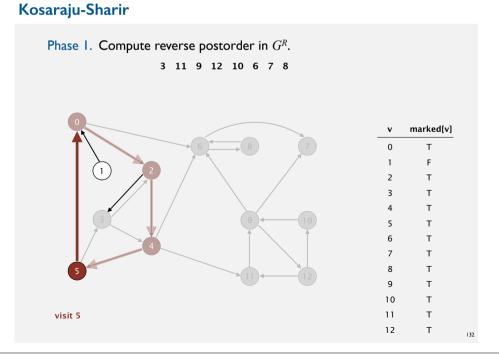


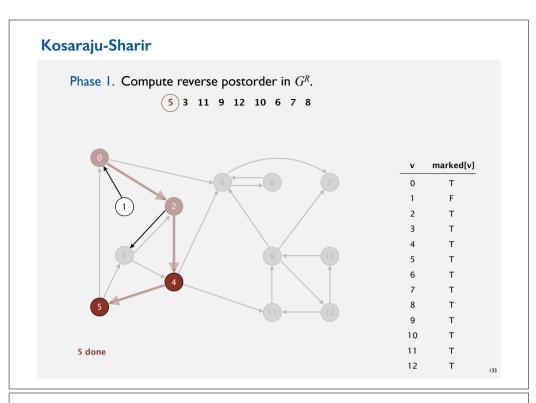


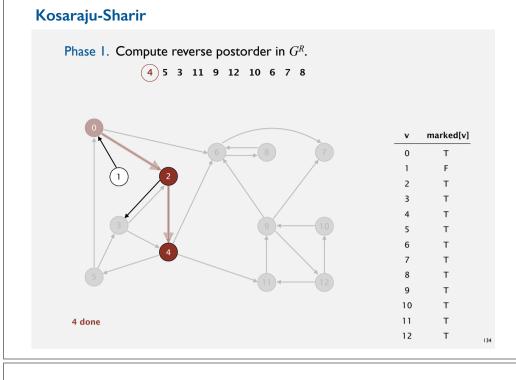


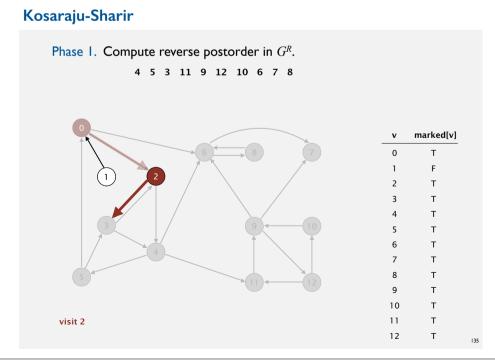


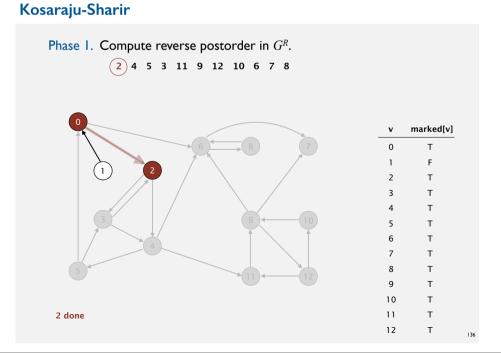


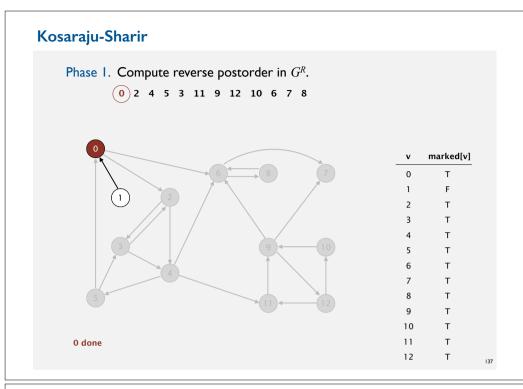


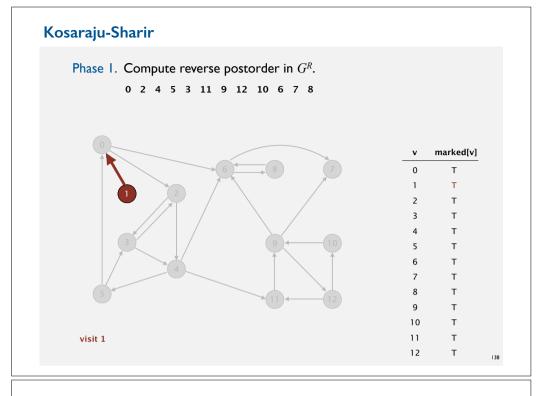


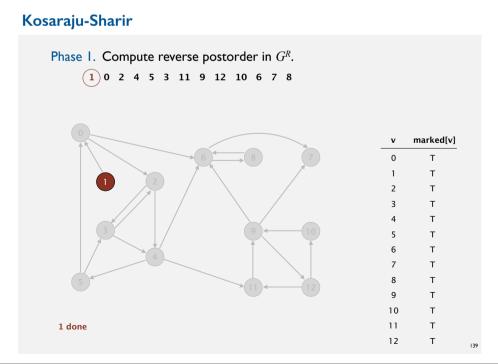


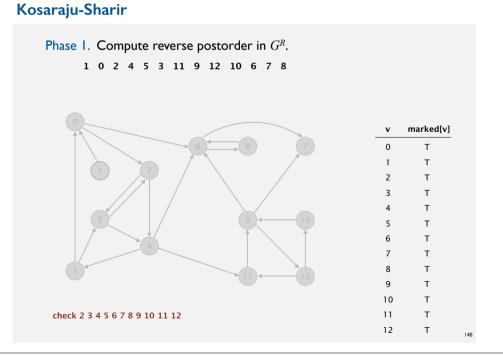


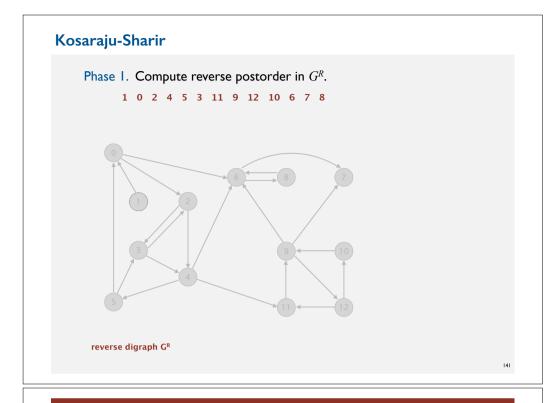






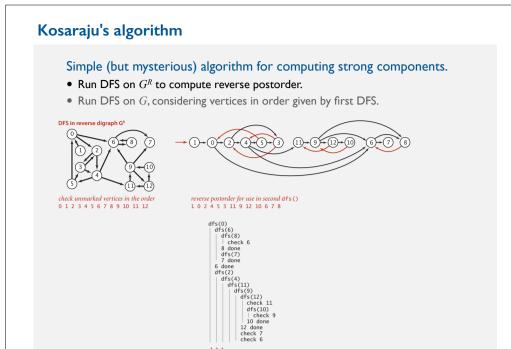






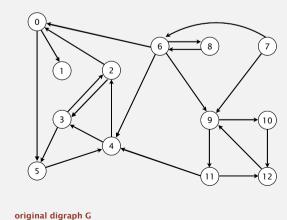
Kosaraju's algorithm

- ▶ DFS in reverse graph
- ▶ DFS in original graph



Kosaraju-Sharir

Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8

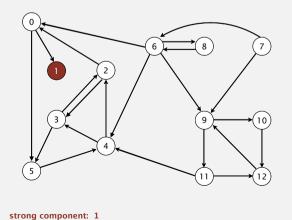


v	scc[v]	
0	-	
1	-	
2	-	
3	-	
4	-	
5	-	
6	-	
7	-	
8	-	
9	-	
10	-	
11	-	
12	-	144

Kosaraju-Sharir

visit 1

Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8

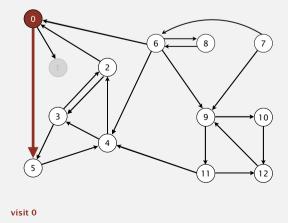


V	scc[v]
0	-
1	0
2	-
3	-
4	-
5	-
6	-
7	-
8	-
9	-
10	-
11	-
12	-

12

Kosaraju-Sharir

Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8

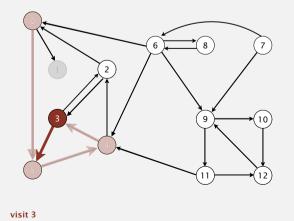


v	SCC[V]
0	1
1	0
2	-
3	-
4	-
5	-
6	-
7	-
8	-
9	-
10	-
11	-
12	-

Kosaraju-Sharir

visit 5

Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8



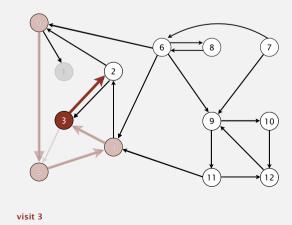
· ·	SCC[V]
0	1
1	0
2	-
3	1
4	1
5	1
6	-
7	-
8	-
9	-
10	-
11	-
12	-

11

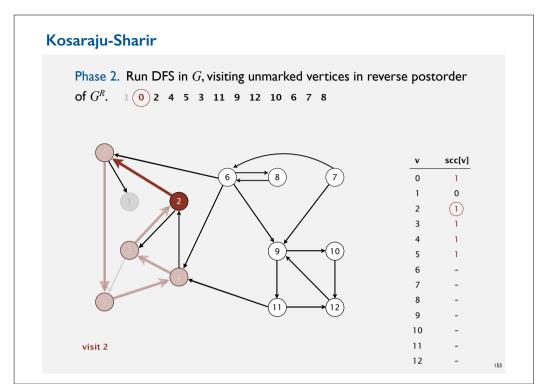
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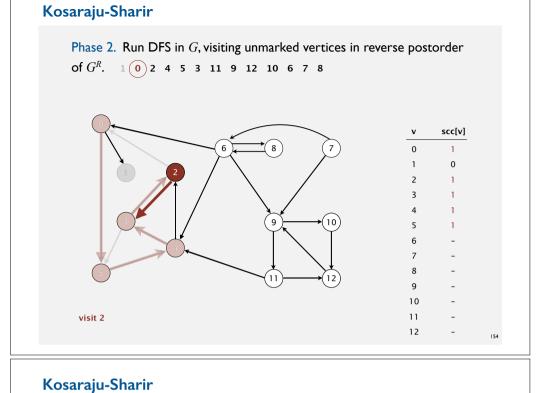
Kosaraju-Sharir

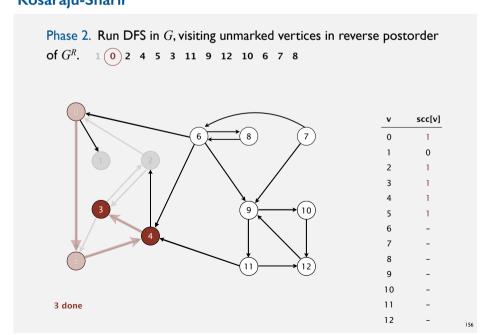
Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8



v	SCC[V]
0	1
1	0
2	-
3	1
4	1
5	1
6	-
7	-
8	-
9	-
10	-
11	-
12	-





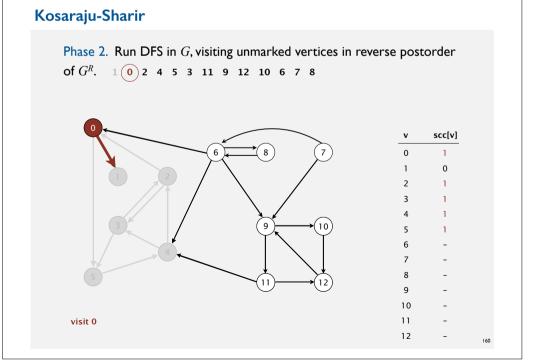


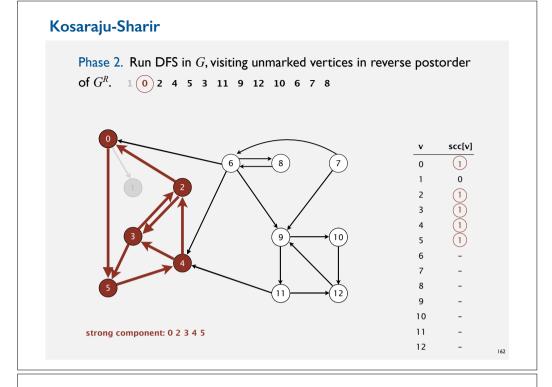
Kosaraju-Sharir Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8 $\frac{\mathbf{v} \quad \mathbf{scc(v)}}{0} \quad \frac{\mathbf{v} \quad \mathbf{v} \quad \mathbf{v}}{0} \quad \mathbf{v} \quad$

12

Kosaraju-Sharir Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8 $\frac{v}{0} = \frac{scc[v]}{0} = \frac{v}{1} = \frac{v}{0} = \frac{v}{0}$

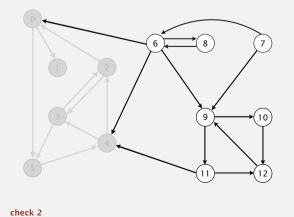
Kosaraju-Sharir Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8 $\frac{\mathbf{v} \quad \mathbf{scc[v]}}{0} \quad \frac{\mathbf{v} \quad \mathbf{sc$





Kosaraju-Sharir

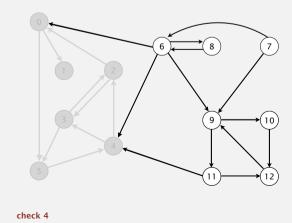
Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 (2) 4 5 3 11 9 12 10 6 7 8



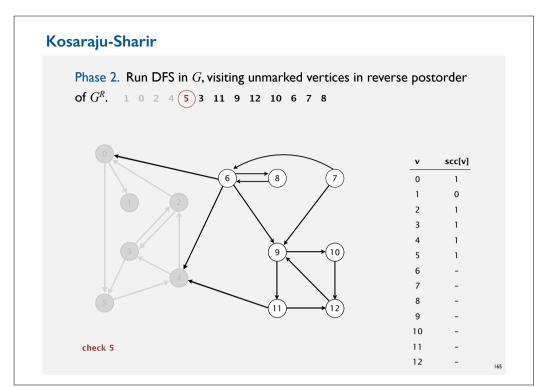
v	SCC[V]
0	1
1	0
2	1
3	1
4	1
5	1
6	-
7	-
8	-
9	-
10	-
11	-
12	-

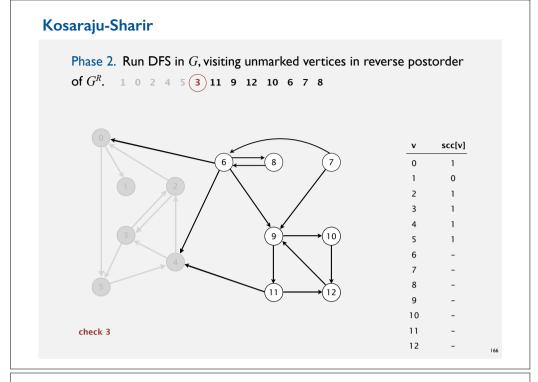
Kosaraju-Sharir

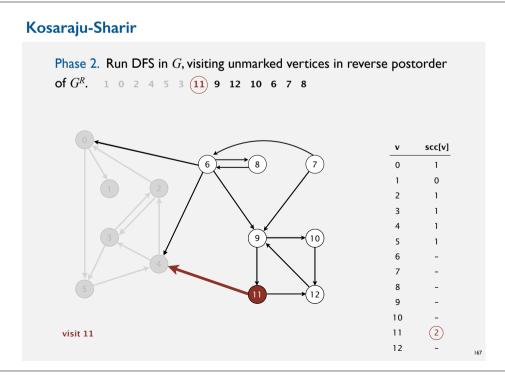
Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 10 6 7 8

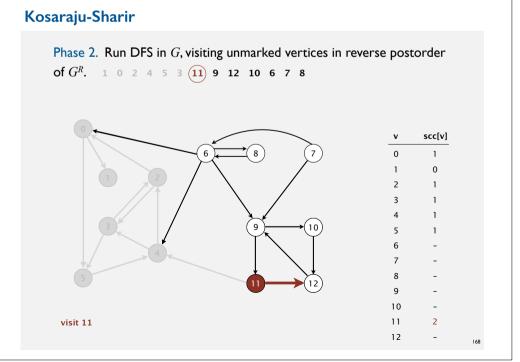


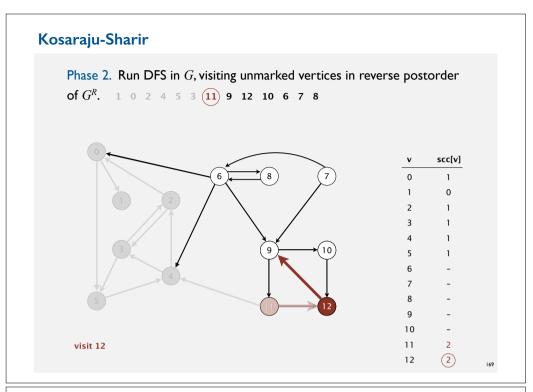
v	scc[v]
0	1
1	0
2	1
3	1
4	1
5	1
6	-
7	-
8	-
9	-
10	-
11	-
12	-

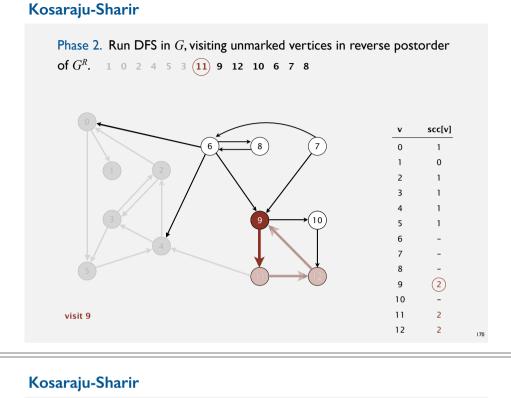


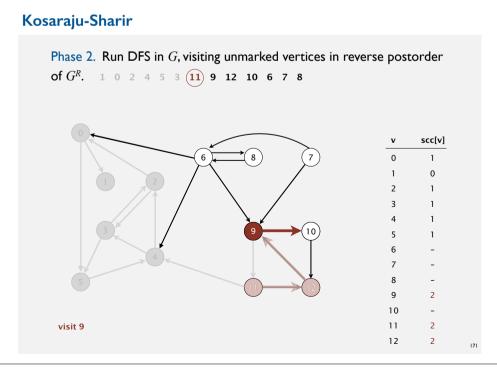


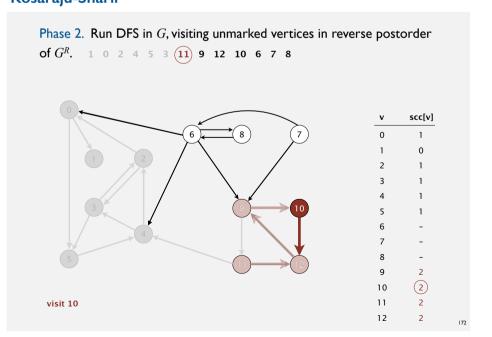


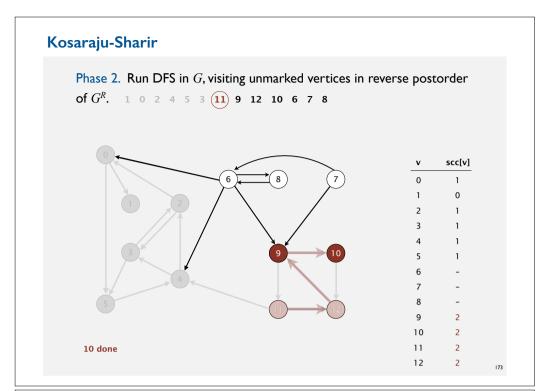


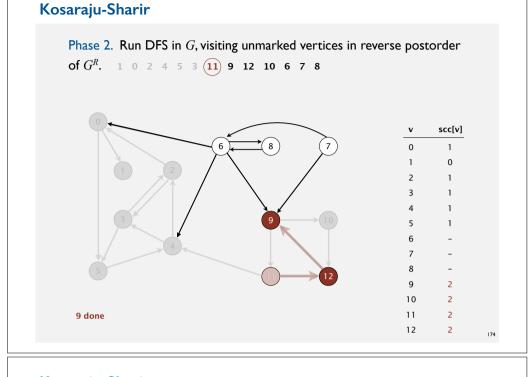






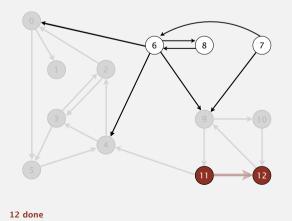






Kosaraju-Sharir Phase 2. Run D

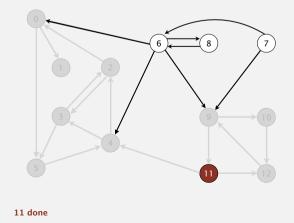
Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 \bigcirc 1 1 9 12 10 6 7 8



v	scc[v]
0	1
1	0
2	1
3	1
4	1
5	1
6	-
7	-
8	-
9	2
10	2
11	2
12	2

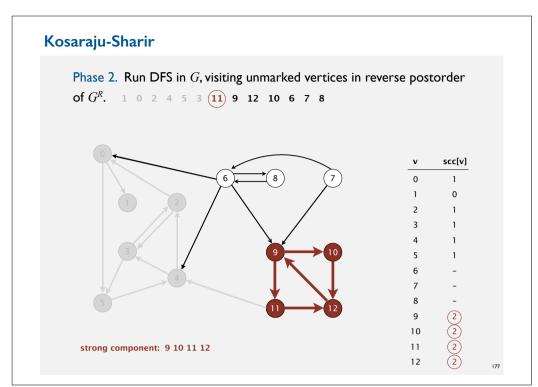
Kosaraju-Sharir

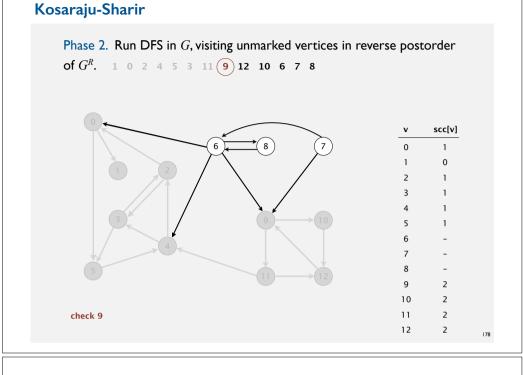
Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 \bigcirc 11) 9 12 10 6 7 8



0
1
1
1
1
-
-
-
2
2
2
2

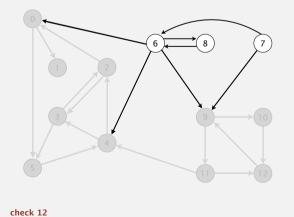
scc[v]





Kosaraju-Sharir

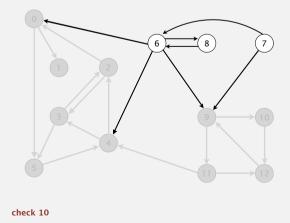
Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 (12) 10 6 7 8



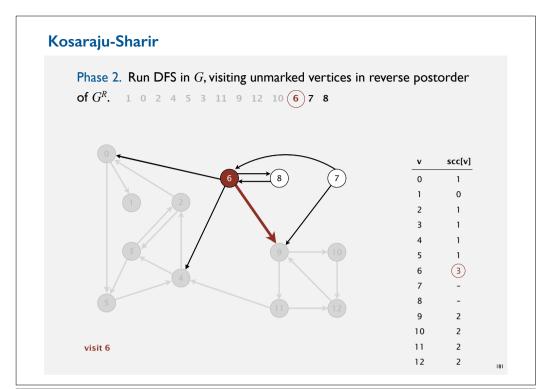
v	scc[v]
0	1
1	0
2	1
3	1
4	1
5	1
6	-
7	-
8	-
9	2
10	2
11	2
12	2

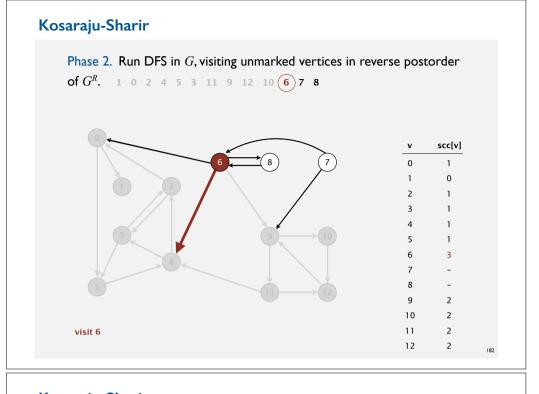
Kosaraju-Sharir

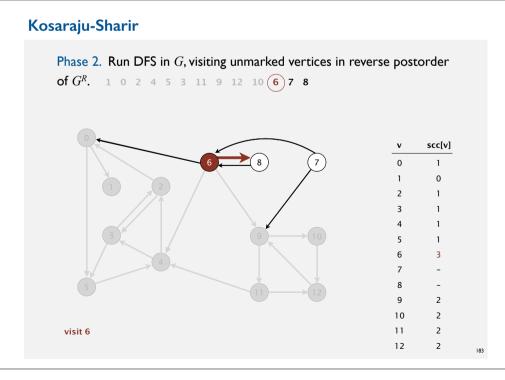
Phase 2. Run DFS in G, visiting unmarked vertices in reverse postorder of G^R . 1 0 2 4 5 3 11 9 12 $\fbox{10}$ 6 7 8

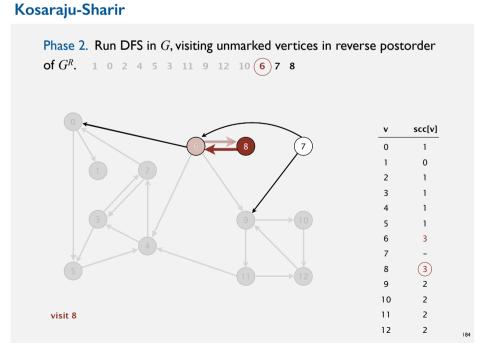


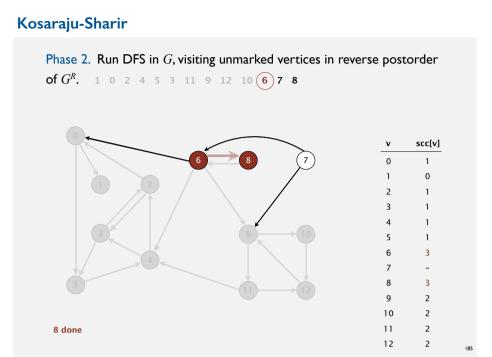
v	scc[v]
0	1
1	0
2	1
3	1
4	1
5	1
6	-
7	-
8	-
9	2
10	2
11	2
12	2 180

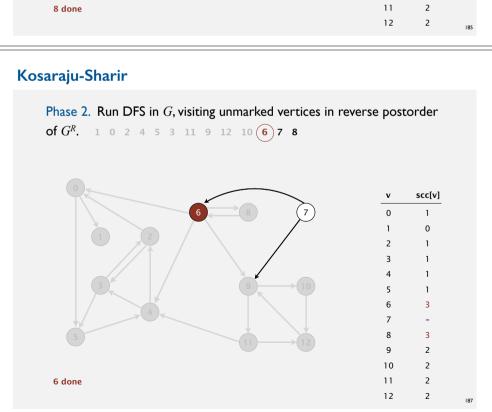


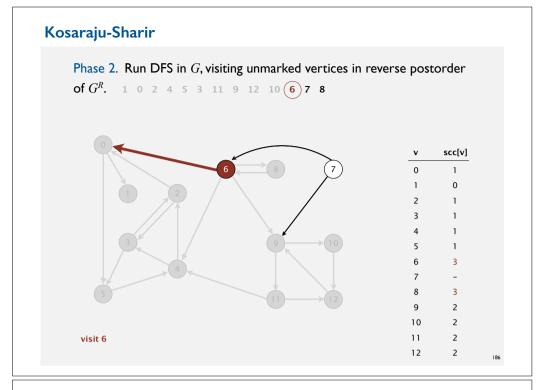


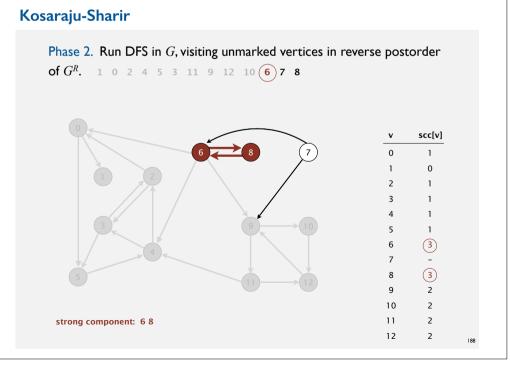


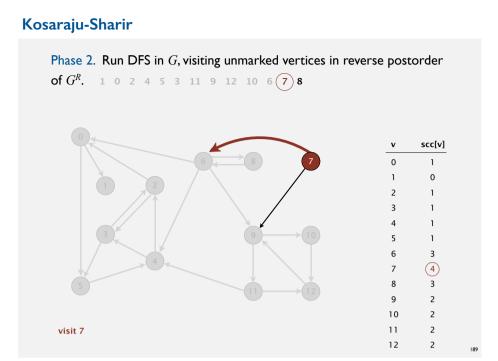


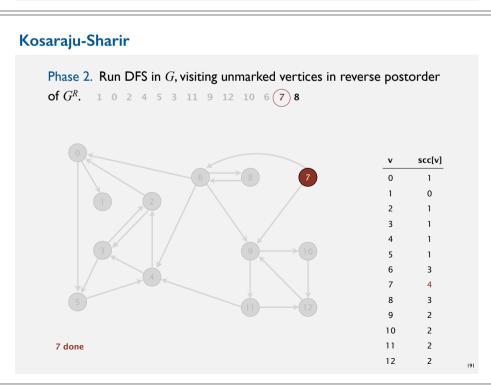


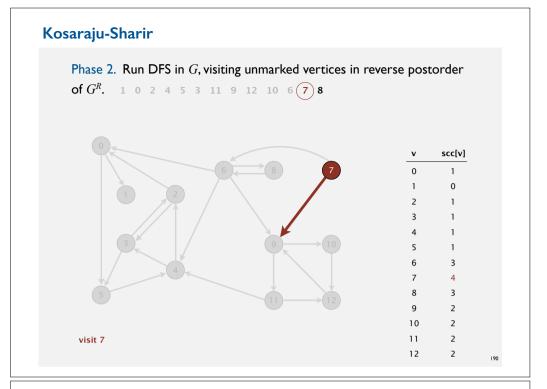


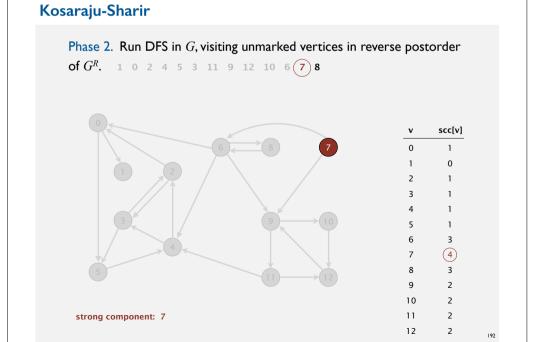


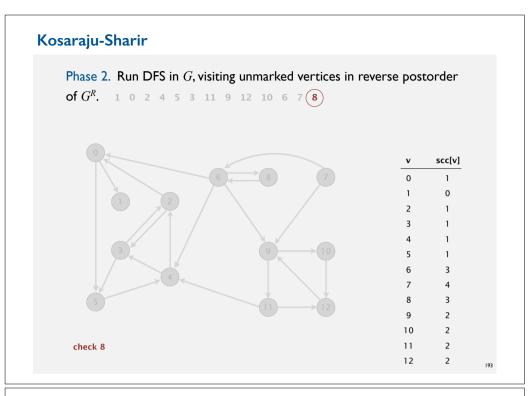


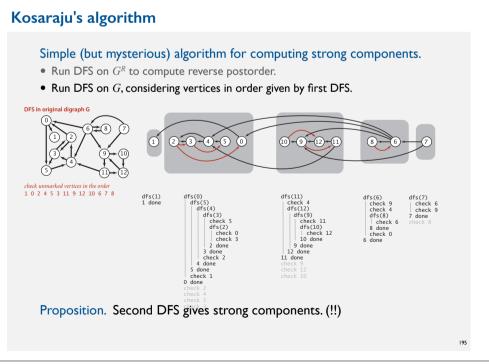


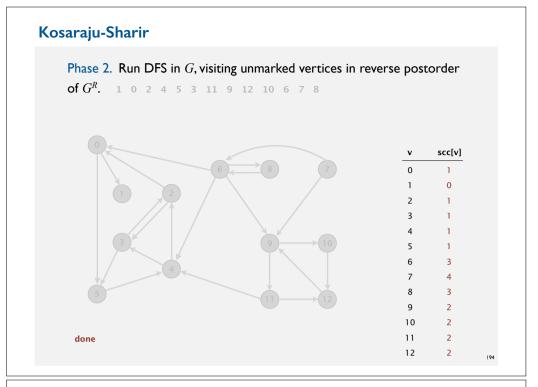












Connected components in an undirected graph (with DFS)

```
public class CC
  private boolean marked[];
  private int[] id;
  private int count;
  public CC (Graph G)
     marked = new boolean[G.V()];
     id = new int[G.V()];
     for (int v = 0; v < G.V(); v++)
        if (!marked[v])
            dfs(G, v);
            count++;
  private void dfs(Graph G, int v)
     marked[v] = true;
     id[v] = count;
     for (int w : G.adj(v))
        if (!marked[w])
           dfs(G, w);
  public boolean connected(int v, int w)
  { return id[v] == id[w]; }
```

Strong components in a digraph (with two DFSs)

```
public class KosarajuSCC
  private boolean marked[];
private int[] id;
   private int count;
   public KosarajuSCC(Digraph G)
      marked = new boolean[G.V()];
      id = new int[G.V()];
      DepthFirstOrder (G.reverse());
for (int v : dfs.reversePost())
         if (!marked[v])
            dfs(G, v);
             count++;
   private void dfs(Digraph G, int v)
      marked[v] = true;
      id[v] = count;
      for (int w : G.adj(v))
  if (!marked[w])
             dfs(G, w);
   public boolean stronglyConnected(int v, int w)
   { return id[v] == id[w]; }
```

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Digraph-processing summary: algorithms of the day

