

# **BBM 413**

# **Fundamentals of Image Processing**

Erkut Erdem  
Dept. of Computer Engineering  
Hacettepe University

Introduction

# Today

- **Introduction**
  - About the class
  - Organization of this course
- **What is image processing?**
  - What does it mean, to see?
  - Vision as a computational problem
  - Sample image processing problems and applications

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# About this course

- This course is an advanced level undergraduate course about the fundamentals of image processing.
- **Requirements**
  - Programming skills (C/C++, Matlab)
  - Good math background (Calculus, Linear Algebra, Statistical Methods)
  - Little or no prior knowledge of image processing techniques
- **BBM 415 Introduction to Programming Practicum**
  - The students will gain hand-on experience via a set of programming assignments.

# About this course (cont'd.)

- **Goals of the course:**

- to provide an introduction to students who wish to specialize in interrelated disciplines like image processing, computer vision and computational photography

- **Skills to develop:**

- a foundational understanding and knowledge of concepts that underlie image processing

- **What is image processing?**

- What does image processing deal with?
- Computational analysis of low and mid-level vision

# BBM 413-415 Team

## Instructor



Erkut ERDEM  
[erkut@cs.hacettepe.edu.tr](mailto:erkut@cs.hacettepe.edu.tr)  
Office: 114

## TA

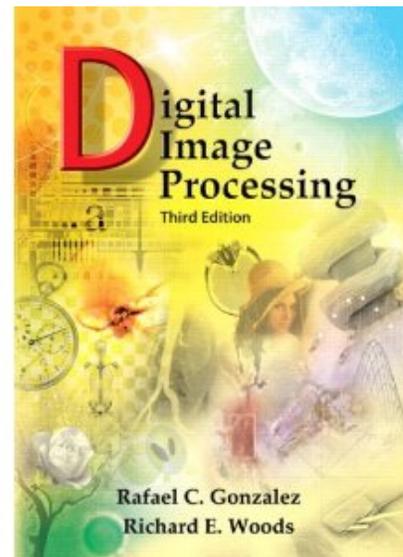
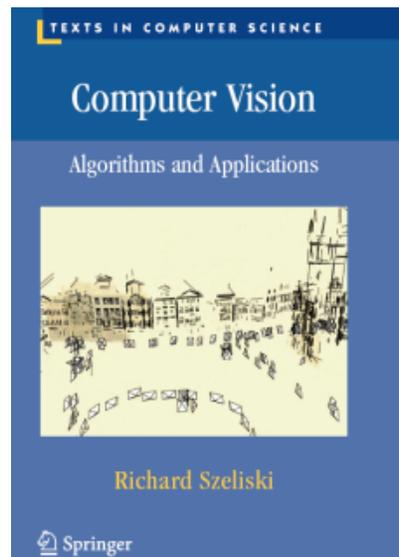


Aysun KOCAK  
[aysunkocak@cs.hacettepe.edu.tr](mailto:aysunkocak@cs.hacettepe.edu.tr)  
Office: Vision Lab

- **Office hours:** to be announced!

# Textbooks and Reference Material

- Computer Vision: Algorithms and Applications, Richard Szeliski, Springer, 2010
- Digital Image Processing, R. C. Gonzalez, R. E. Woods, 3rd Edition, Prentice Hall, 2008



- Lecture notes and handouts
- Papers and journal articles

# Communication

- The course webpage will be updated regularly throughout the semester with lecture notes, programming and reading assignments and important deadlines.

<http://web.cs.hacettepe.edu.tr/~erkut/bbm413.f15>

# Getting Help

- **Office hours**
    - See webpage for the schedule
  - **BBM 415 Image Processing Practicum**
    - Course related recitations, practice with example codes, etc.
  - **Communication**
    - Announcements and course related discussions through 
- <https://piazzo.com/hacettepe.edu.tr/fall2015/bbm413>

# Course work and grading

- **Reading assignments (12%)**
  - Reading research papers and preparing their summaries
- **Quizzes (16%)**
  - Pop-up quizzes during class
- **Midterm exam (32%)**
  - Closed book and notes
  - In class on November 19<sup>th</sup>
- **Final exam (40%)**
  - Closed book and notes
  - To be scheduled by Registrar

# Course Overview

- Introduction (*0.5 week*)
- What is image processing? (*0.5 week*)
- Image formation and the digital camera (*1 week*)
- Color perception and color spaces (*1 week*)
- Point operations (*1 week*)
- Spatial filtering (*1 week*)
- Frequency Domain Techniques (*2 weeks*) Midterm exam
- Image pyramids and wavelets (*1 week*)
- Gradients, edges, contours (*1 week*)
- Image segmentation (*2 weeks*)
- Image smoothing (*1 week*)

# BBM 415 Image Processing Practicum

- **Programming assignments (PAs)**
  - Five programming assignments throughout the semester.
  - Each assignment has a well-defined goal such as solving a specific problem.
  - You must work alone or a group of two on all assignments stated unless otherwise.
  
- **Important Dates (*Tentative*)**
  - PA 1: October 8<sup>th</sup>
  - PA 2: October 22<sup>nd</sup>
  - PA 3: November 12<sup>th</sup>
  - PA 4: November 26<sup>th</sup>
  - PA 5: December 10<sup>th</sup>

# Policies

- **Work groups**

- You must work alone or a group of two on all assignments stated unless otherwise

- **Submission**

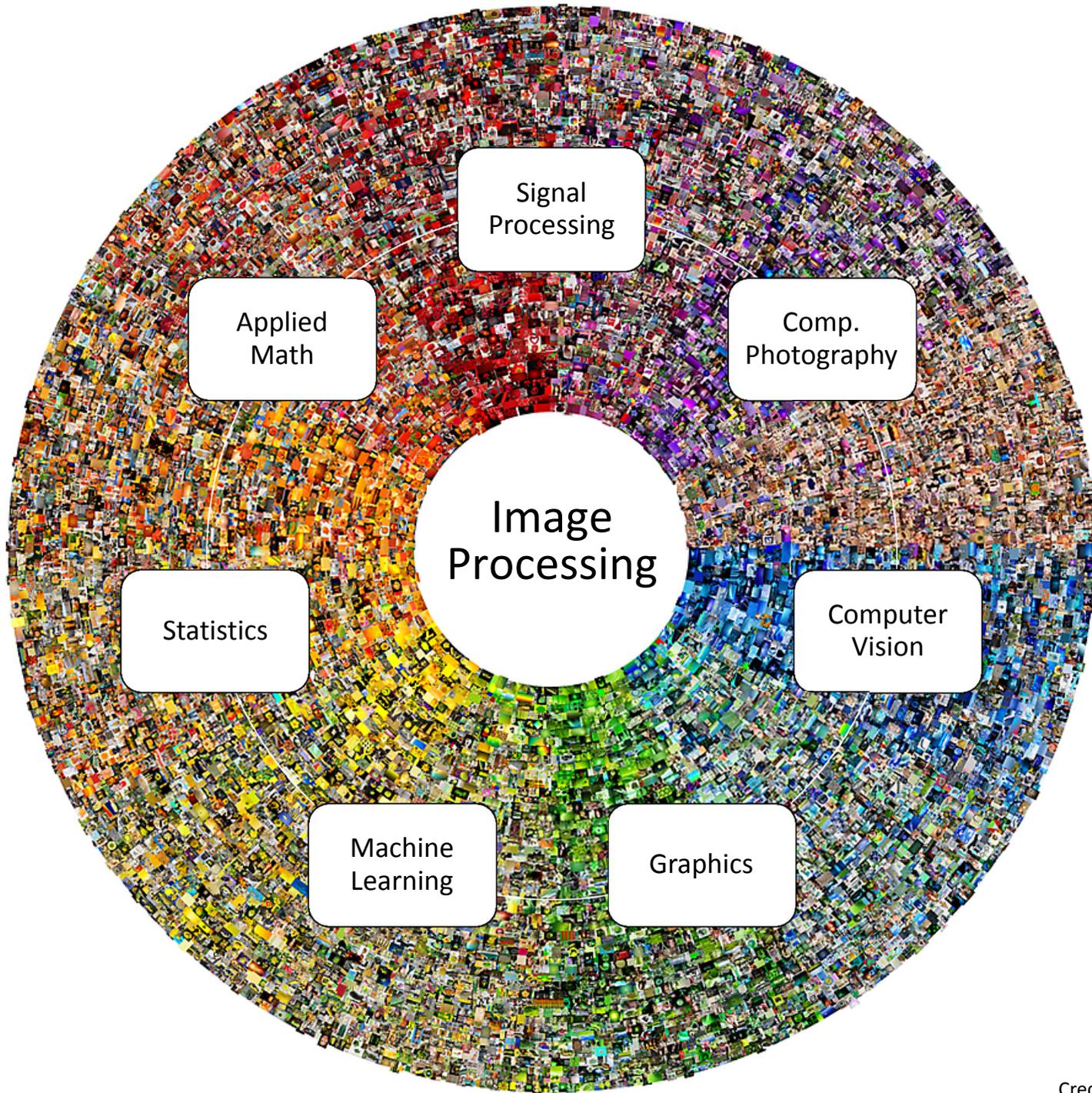
- Assignments due at 23:59 on Friday evenings
- Electronic submissions (no exceptions!)

- **Lateness penalties**

- Get penalized **10% per day**
- No late submission later than **3 days after due date**

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  - Vision as a computational problem
  - Sample image processing problems



# ***What does it mean, to see?***

- *“The plain man’s answer (and Aristotle’s, too) would be, to know what is where by looking. In other words, vision is the process of discovering from images what is present in the world, and where it is.”* David Marr, Vision, 1982
- Our brain is able to use an image as an input, and interpret it in terms of objects and scene structures.



# What does Salvador Dali's *Study for the Dream Sequence in Spellbound (1945)* say about our visual perception?

We see a two dimensional image

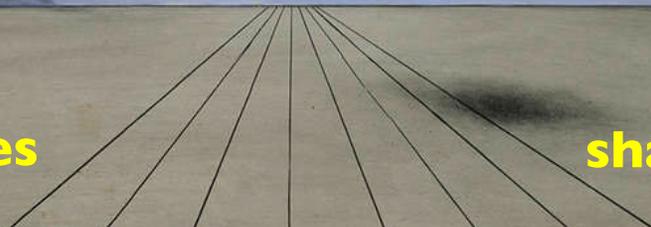
But, we perceive depth information

light reflected  
on the retina



converging lines

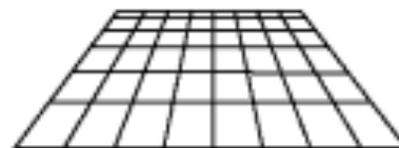
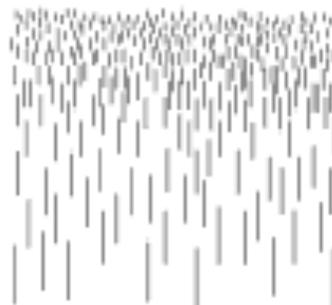
shadows of the eye



# Why does vision appear easy to humans?

- Our brains are specialized to do vision.
- Nearly half of the cortex in a human brain is devoted to doing vision (cf. motor control ~20-30%, language ~10-20%)
- “*Vision has evolved to convert the ill-posed problems into solvable ones by adding premises: assumptions about how the world we evolved in is, on average, put together”  
Steven Pinker, How the Mind Works, 1997*

- Gestalt Theory  
(Laws of Visual Perception),  
Max Wertheimer, 1912



# Why does vision appear easy to humans?



IN CS, IT CAN BE HARD TO EXPLAIN THE DIFFERENCE BETWEEN THE EASY AND THE VIRTUALLY IMPOSSIBLE.

# Computer Vision

- “Vision is a process that produces from images of the external world a description that is useful to the viewer and not cluttered with irrelevant information”  
~David Marr
- The goal of Computer Vision:  
To develop artificial machine vision systems that make inferences related to the scene being viewed through the images acquired with digital cameras.

**Things that are easy for us  
are difficult for computers  
and viceversa ~ Marvin Minsky**

MASSACHUSETTS INSTITUTE OF TECHNOLOGY  
PROJECT MAC

Artificial Intelligence Group  
Vision Memo. No. 100.

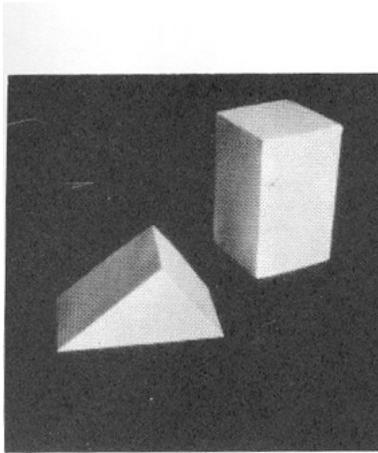
July 7, 1966

THE SUMMER VISION PROJECT

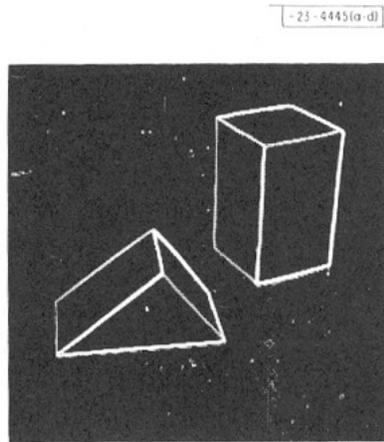
Seymour Papert

The summer vision project is an attempt to use our summer workers effectively in the construction of a significant part of a visual system. The particular task was chosen partly because it can be segmented into sub-problems which will allow individuals to work independently and yet participate in the construction of a system complex enough to be a real landmark in the development of "pattern recognition".

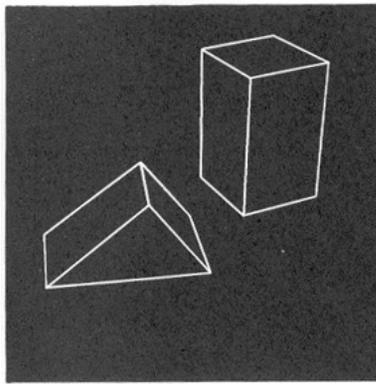
# Origins of computer vision



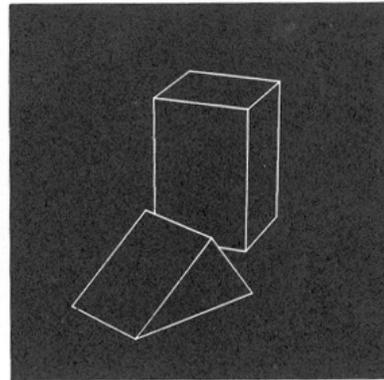
(a) Original picture.



(b) Differentiated picture.



(c) Line drawing.



(d) Rotated view.

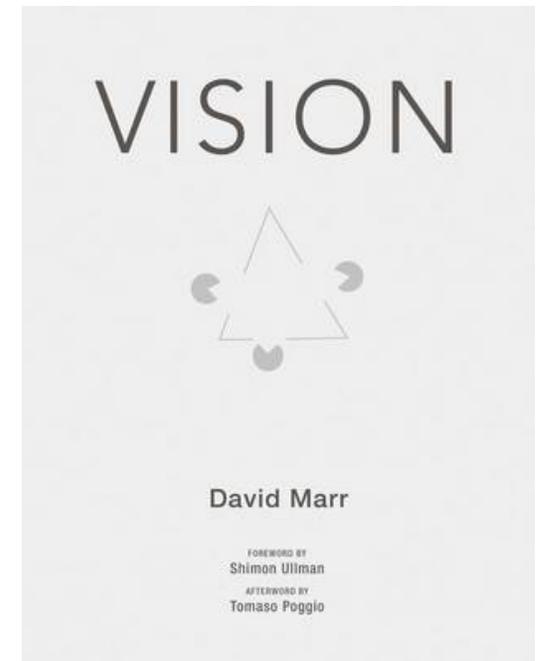
L. G. Roberts, *Machine Perception of Three Dimensional Solids*, Ph.D. thesis, MIT Department of Electrical Engineering, 1963.

# **Vision: a very difficult computational problem, at several levels of understanding**

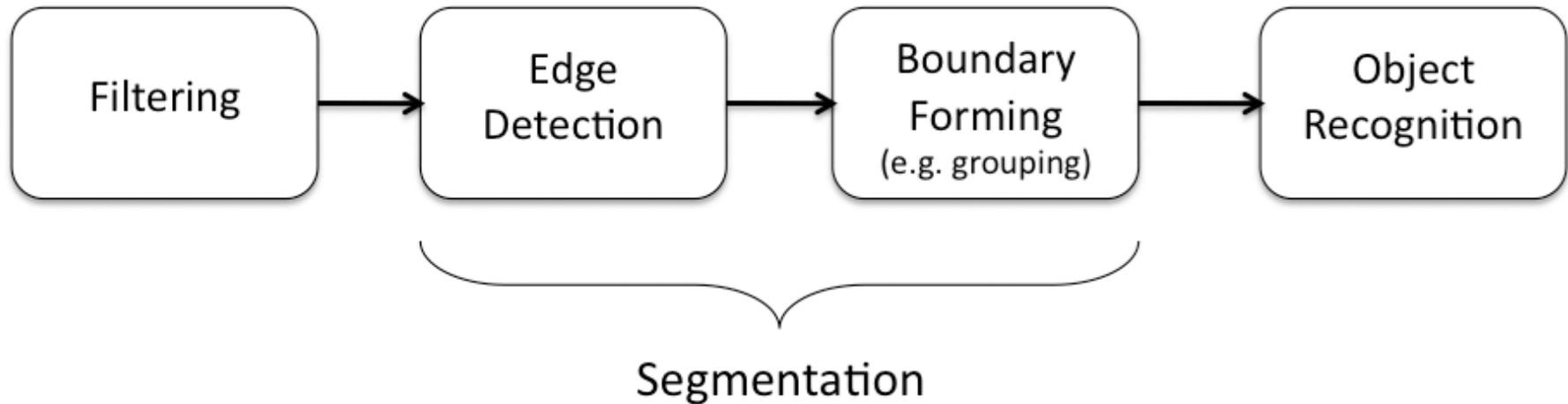
- Vision as an information processing task [David Marr, 1982]
- Three levels of understanding:
  1. Computational theory
    - What is computed? Why it is computed?
  2. Representation and Algorithm
    - How it is computed?
    - Input, Output, Transformation
  3. Physical Realization
    - Hardware

# Reading Assignment #1

- D. Marr (1982). Vision: A Computational Investigation into the Human Representation and Processing of Visual Information. Chapter 1.
- Due on 15<sup>th</sup> of October.
- Submit a brief 1-2 pages summary (in English) electronically.
- Use LaTeX to prepare your reports in pdf file format.

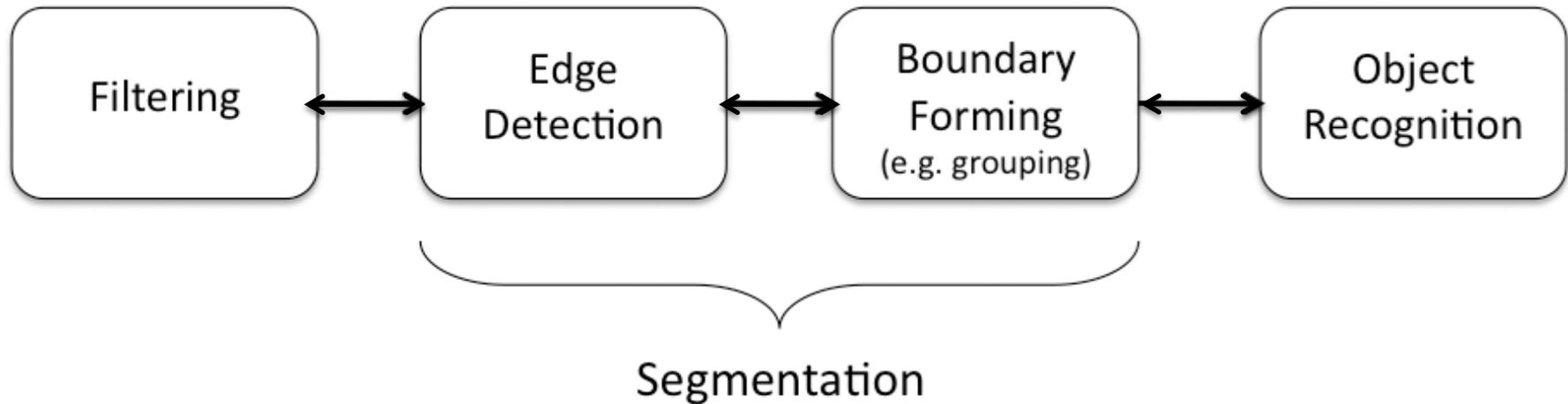


# Visual Modules and the Information Flow



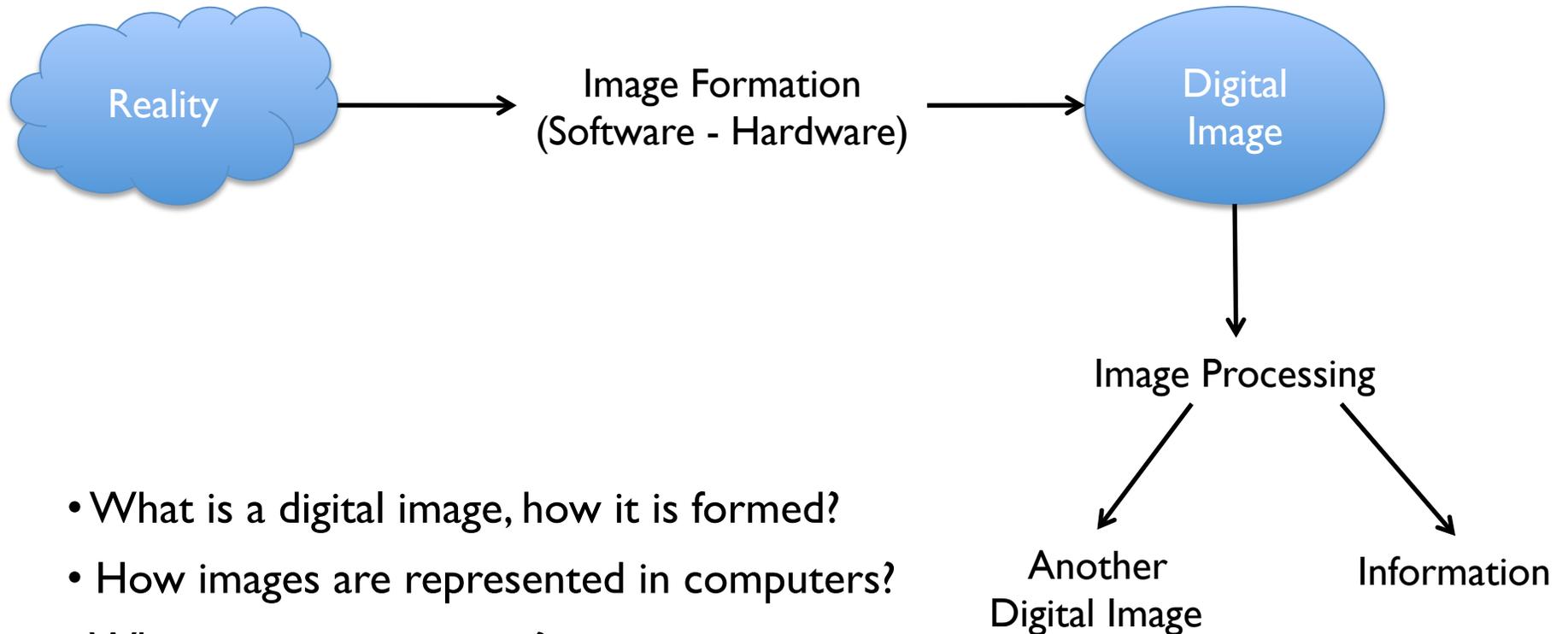
- Visual perception as a data-driven, bottom-up process (traditional view since D. Marr)
- Unidirectional information flow
- Simple low-level cues >> Complex abstract perceptual units

# Visual Modules and the Information Flow



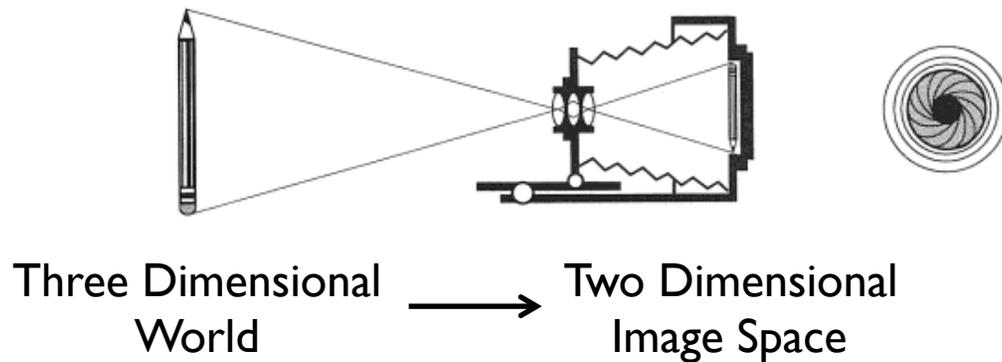
- Vision modules can be categorized into three groups according to their functionality:
  - Low-level vision: filtering out irrelevant image data
  - Mid-level vision: grouping pixels or boundary fragments together
  - High-level vision: complex cognitive processes

# Fundamentals of Image Processing



- What is a digital image, how it is formed?
- How images are represented in computers?
- Why we process images?
- How we process images?

# Image Formation

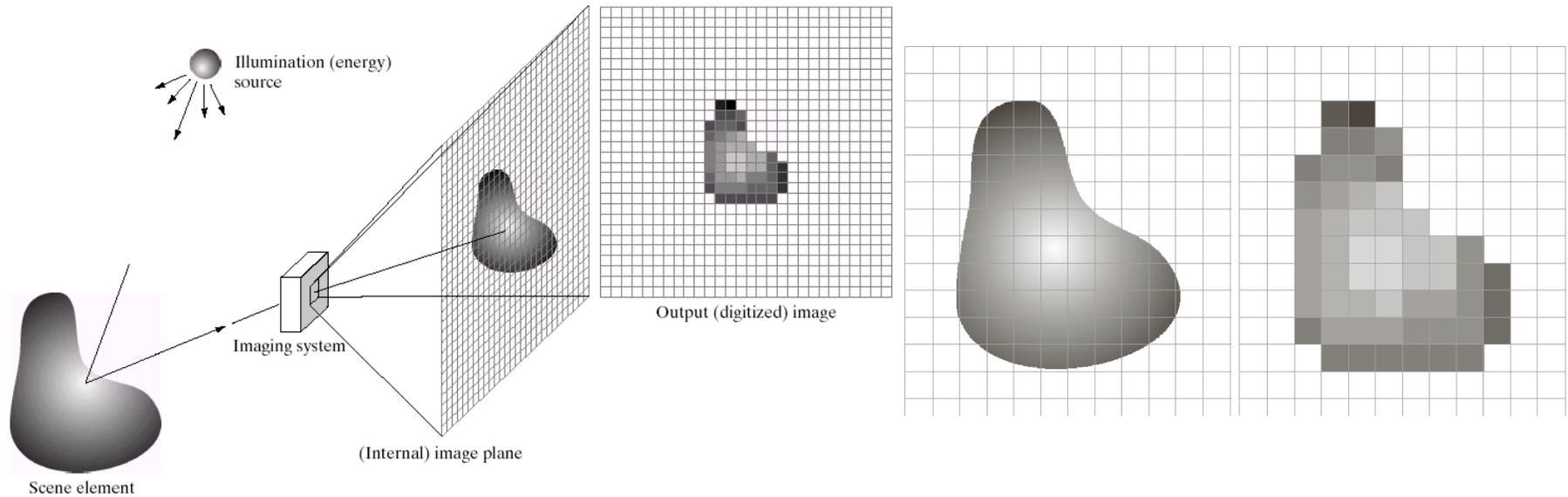


- What is measured in an image location?

- brightness
- color

<< viewpoint  
illumination conditions  
local geometry  
local material properties

# Image Formation



- **Discretization**
  - in image space - sampling
  - In image brightness - quantization

# Image Representation

- **Digital image:** 2D discrete function  $f$
- **Pixel:** Smallest element of an image  $f(x,y)$

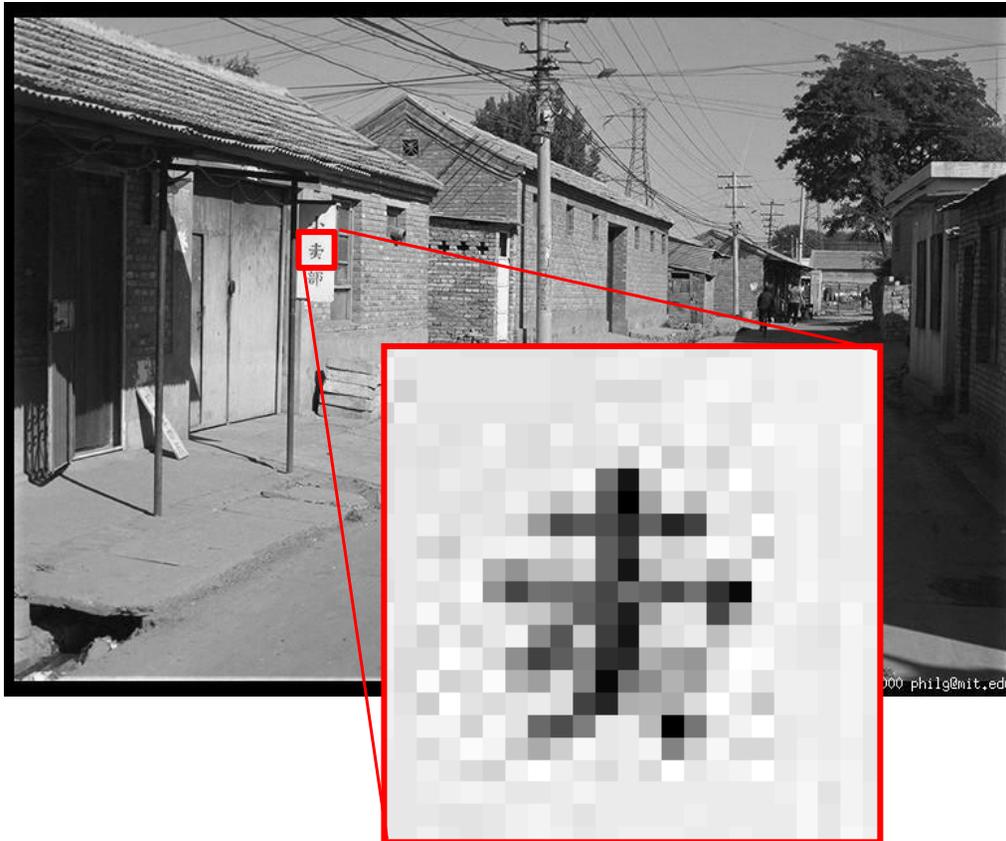


Figure: M. J. Black

# Image Representation

- **Digital image:** 2D discrete function  $f$
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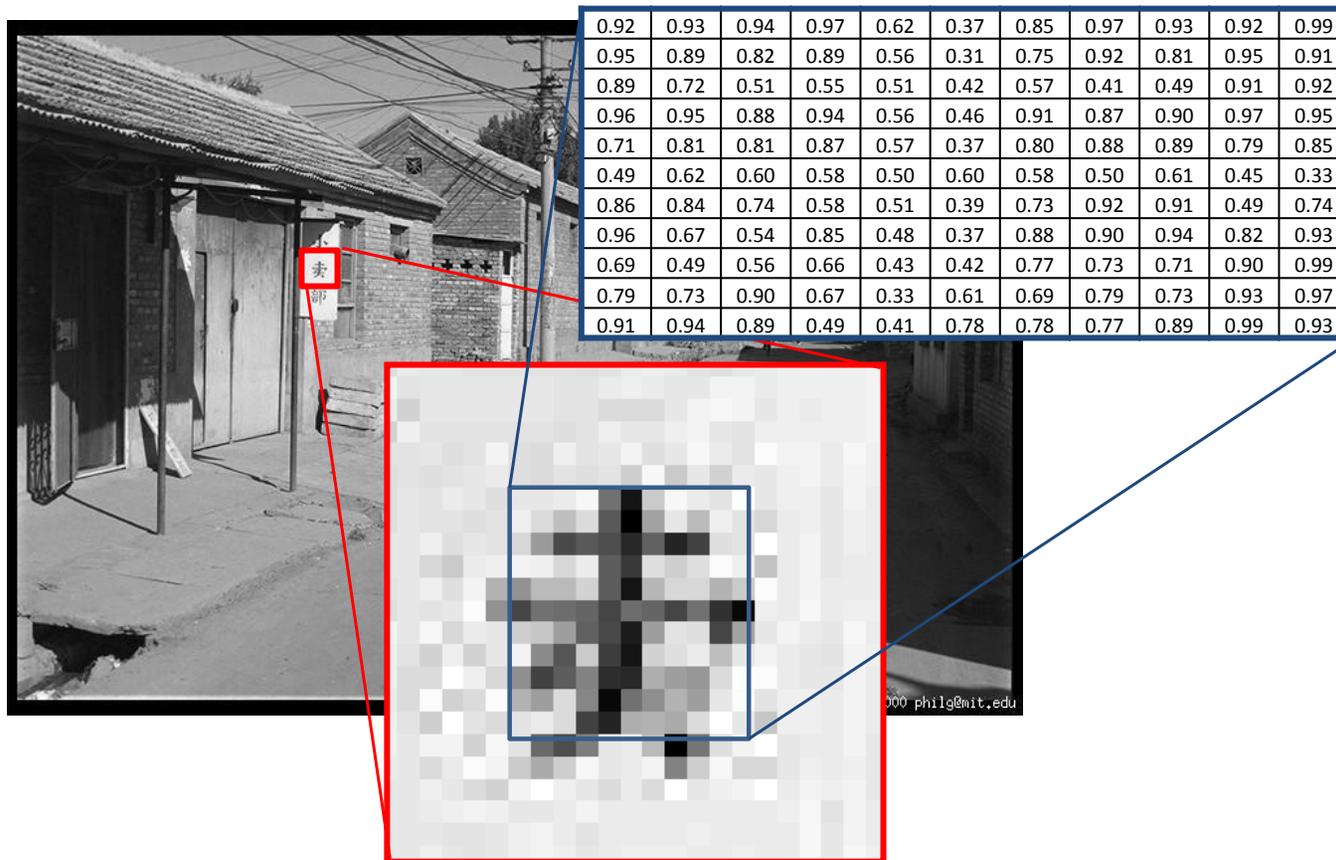
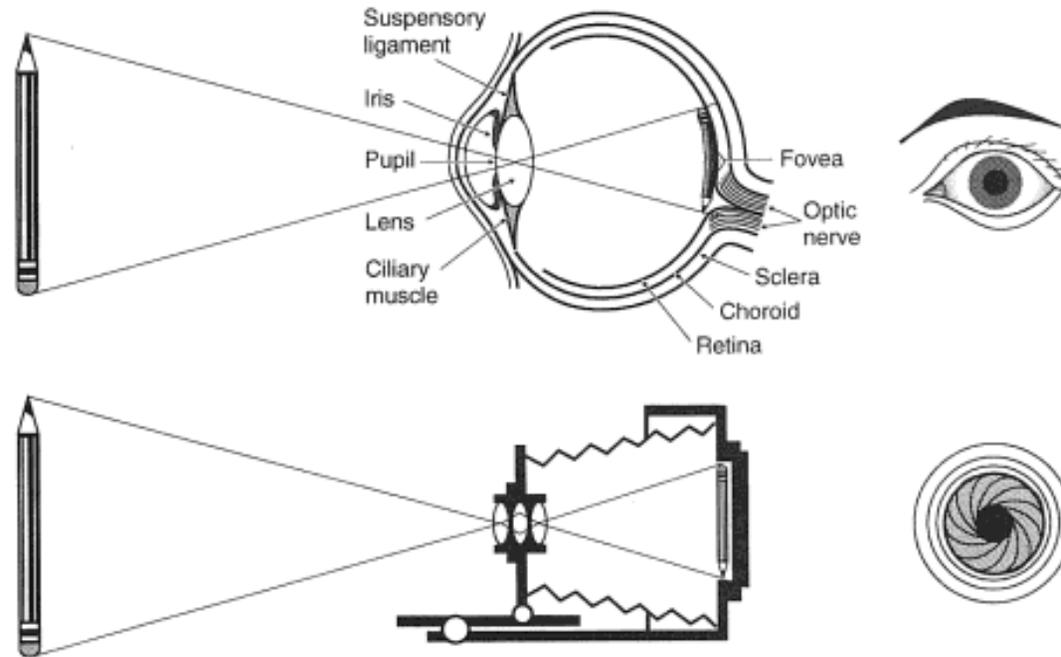


Figure: M. J. Black

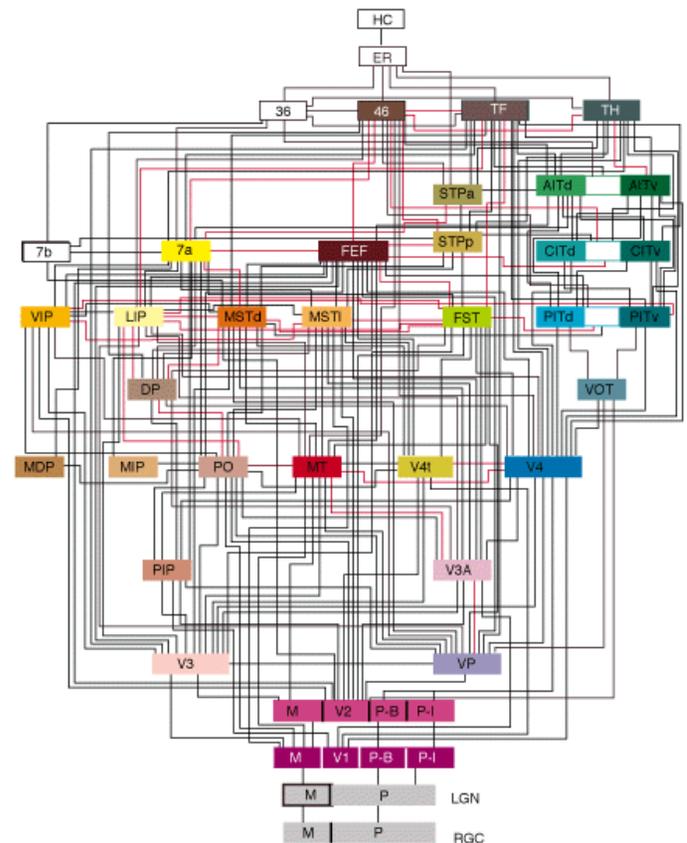
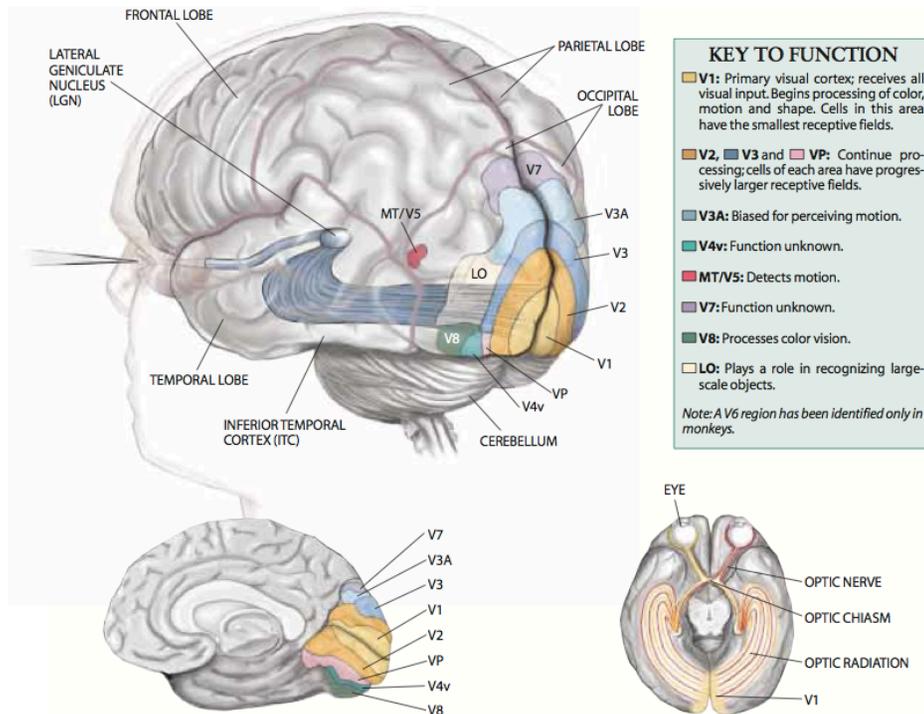
# Human Eye



- Two types of receptor cells in retina:
  - Cone Receptor cells: 6-7 million → function in bright light, color sensitive, fine detail
  - Rod receptor cells: 75-150 million → function in dim light, color insensitive, coarse detail
- A recent discovery: Photosensitive retinal ganglion cells → sensitive to blue light

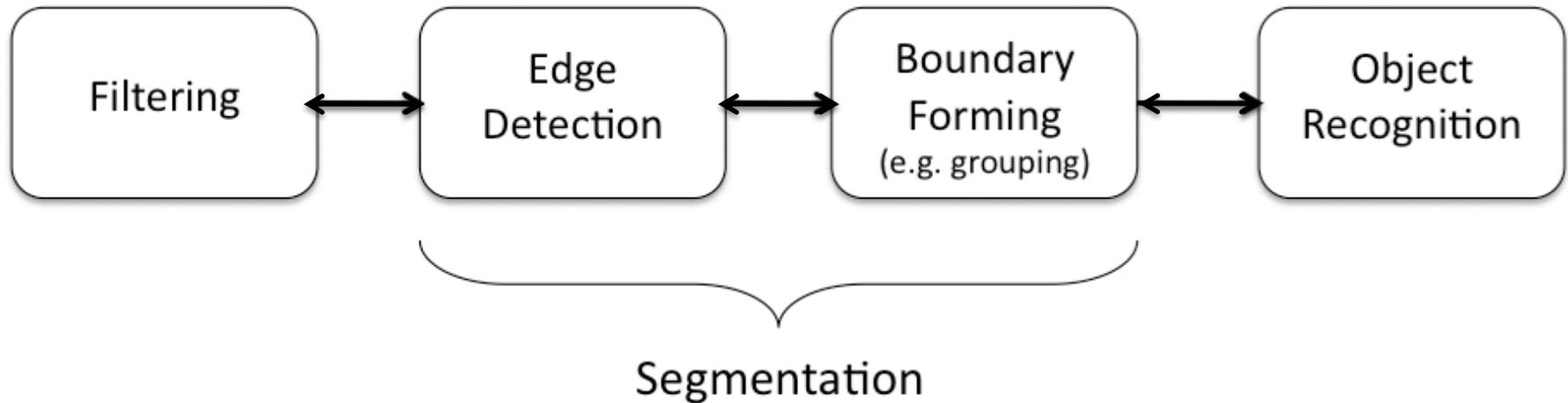
# Hierarchy of Visual Areas

- There are many different neural connections between different visual areas.



Figures: Nikos K. Logothetis, Vision: A Window on Consciousness, SciAm, Nov 1999F (on the left)  
 Felleman & van Essen, 1991 (on the right)

# Visual Modules and the Information Flow



**Subject matter of this course**

- Vision modules can be categorized into three groups according to their functionality:
  - Low-level vision: filtering out irrelevant image data
  - Mid-level vision: grouping pixels or boundary fragments together
  - High-level vision: complex cognitive processes

# Image Filtering

- Instagram
  - A photo-sharing and social networking service
  - Built-in vintage filters



# Image Filtering

- Filtering out the irrelevant information

$$\begin{array}{ccc} f(x) = u(x) + n(x) & & \\ \downarrow & & \downarrow \\ \text{observed} & \text{desired} & \text{irrelevant} \\ \text{image} & \text{image} & \text{data} \end{array}$$

- Image denoising, image sharpening, image smoothing, image deblurring, etc.
- Edge detection
- Required for many other image image manipulation tasks

# Edge Detection

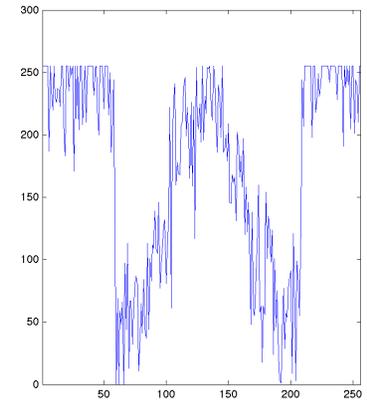
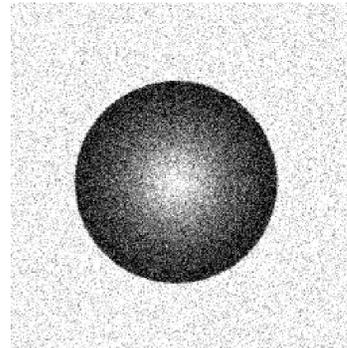
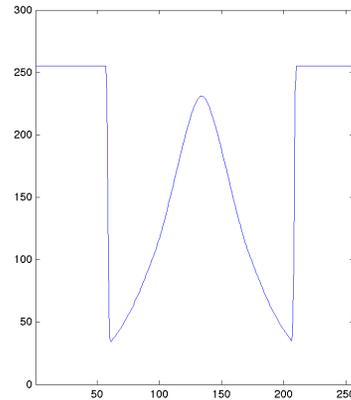
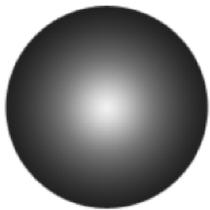


Canny edge detector

- Edges: abrupt changes in the intensity
  - Uniformity of intensity or color
- Edges to object boundaries

# Image Filtering

- **Difficulty:** Some of the irrelevant image information have characteristics similar to those of important image features



# Image Smoothing - A Little Bit of History

- Gaussian Filtering / linear diffusion
  - the most widely used method

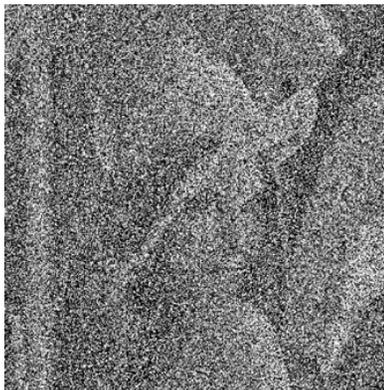
$$\frac{\partial u}{\partial t} = \nabla \cdot (\nabla u) = \nabla^2 u$$



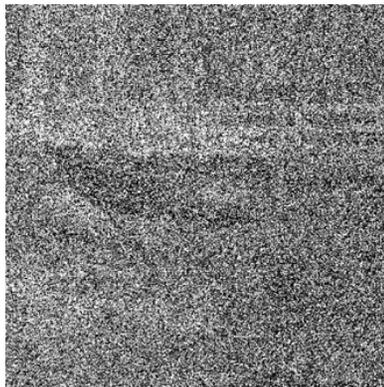
- mid 80's – unified formulations
  - methods that combine smoothing and edge detection
  - Geman & Geman'84, Blake & Zisserman'87, Mumford & Shah'89, Perona & Malik'90

# Image Denoising

- Images are corrupted with 70% salt-and-pepper noise



What do these examples demonstrate?

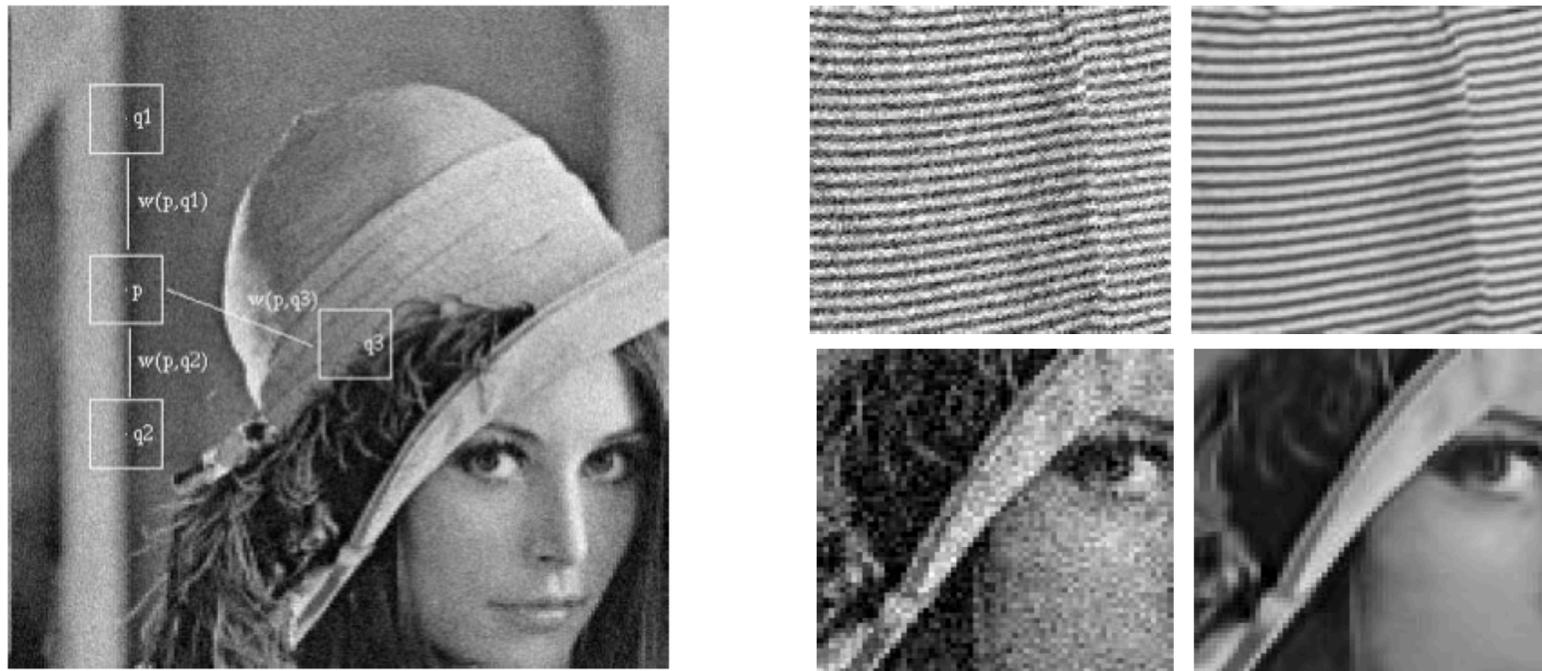


Noisy input

Recovered image

Original image

# Non-local Means Denoising

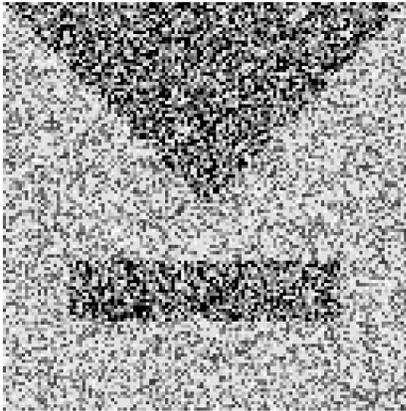


**Figure 1. Scheme of NL-means strategy. Similar pixel neighborhoods give a large weight,  $w(p, q_1)$  and  $w(p, q_2)$ , while much different neighborhoods give a small weight  $w(p, q_3)$ .**

Preserve fine image details and texture during denoising

# Context-Guided Smoothing

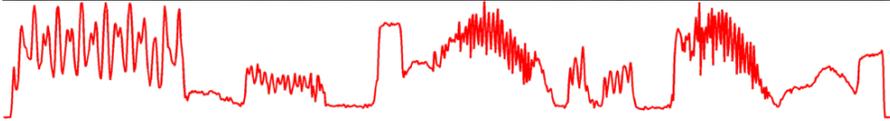
- Use local image context to steer filtering



Preserve main image structures during filtering



# Structure-Preserving Smoothing

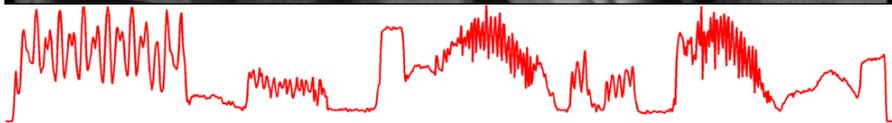
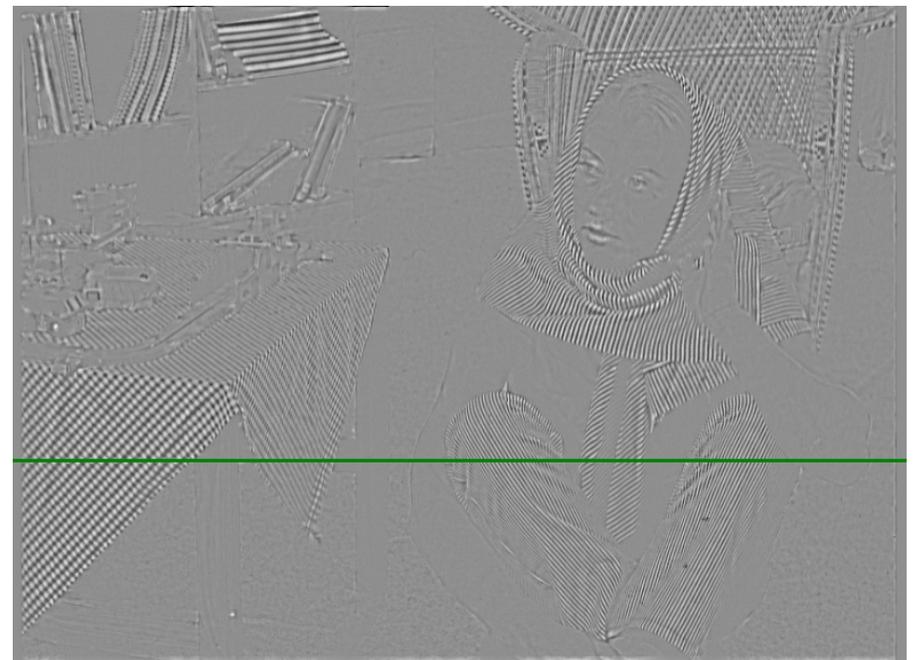


input



structure

# Structure-Preserving Smoothing



input



texture

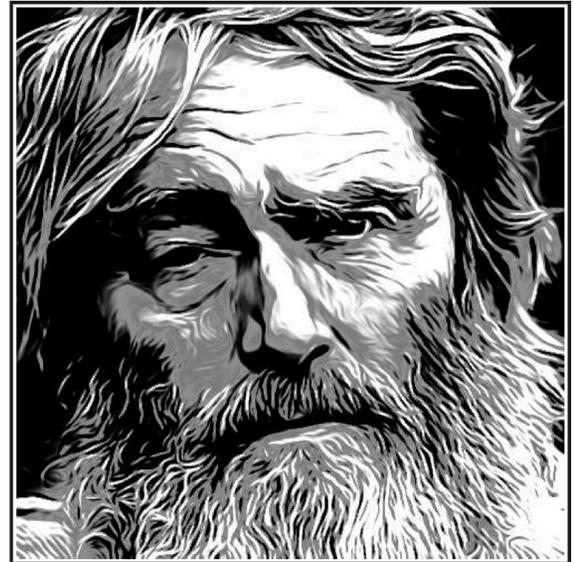
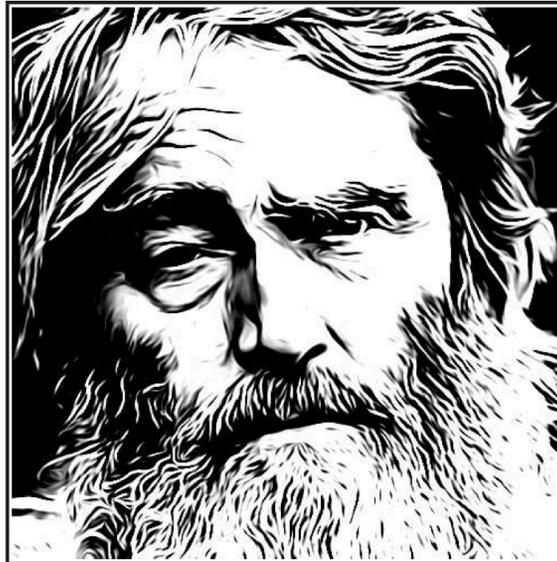
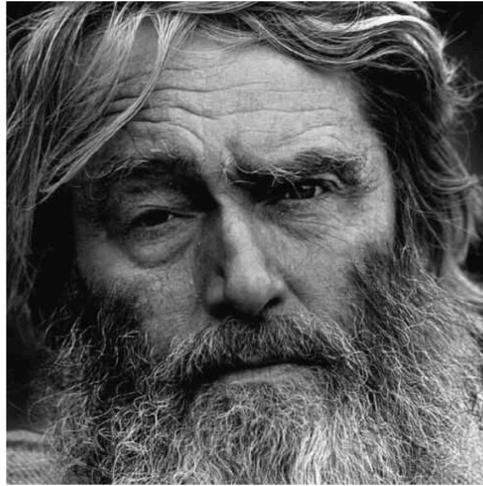
# Image Abstraction



# Detail Enhancement



# Artistic Stylizations



H. Winnemöller, J. E. Kyprianidis and S. C. Olsen, XDoG: An eXtended difference-of-Gaussians compendium including advanced image stylization, Computers & Graphics, 2012

# Image Segmentation

- Partition an image into meaningful regions that are likely to correspond to objects exist in the image



Grouping of pixels  
according to what  
criteria?

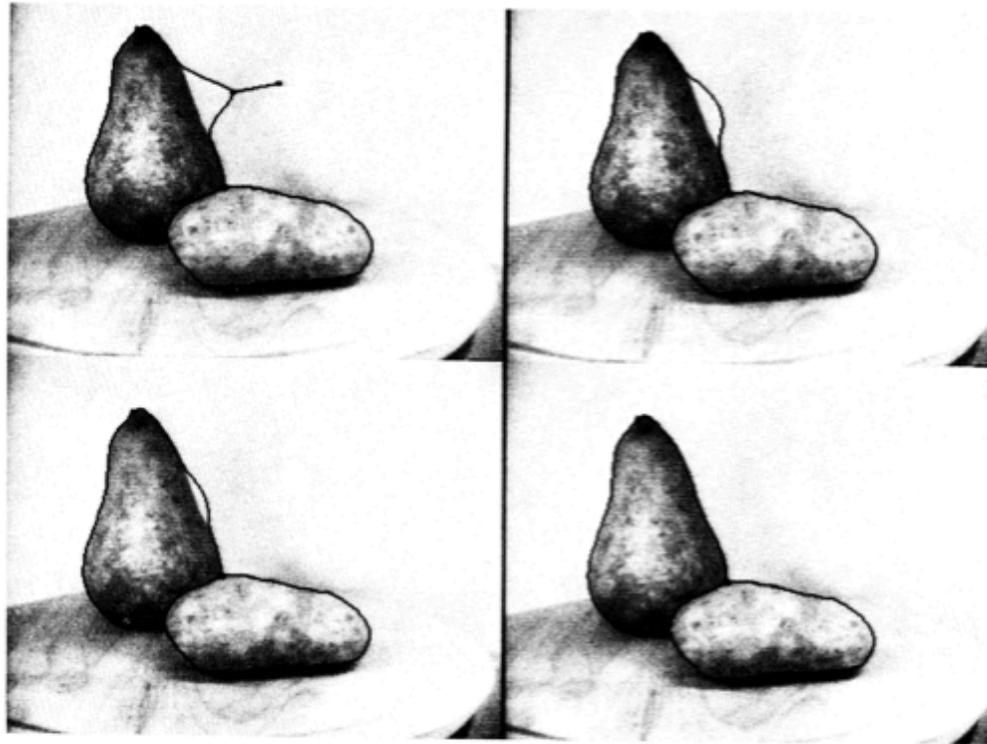
high-level object  
specific knowledge  
matters!

# Image Segmentation

- Boundary-based segmentation
- Region-based segmentation
- Unified formulations

# Snakes

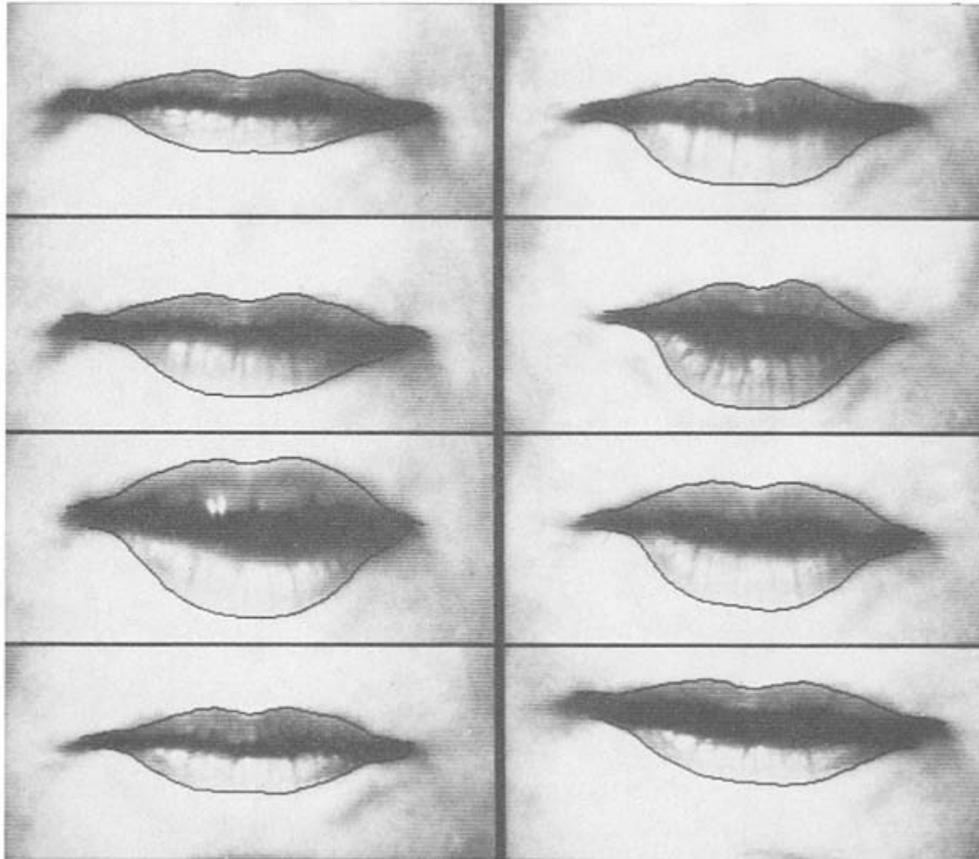
- Curve Evolution - parametric curve formulation



*Fig. 3.* Two edge snakes on a pear and potato. Upper-left: The user has pulled one of the snakes away from the edge of the pear. Others: After the user lets go, the snake snaps back to the edge of the pear.

# Snakes

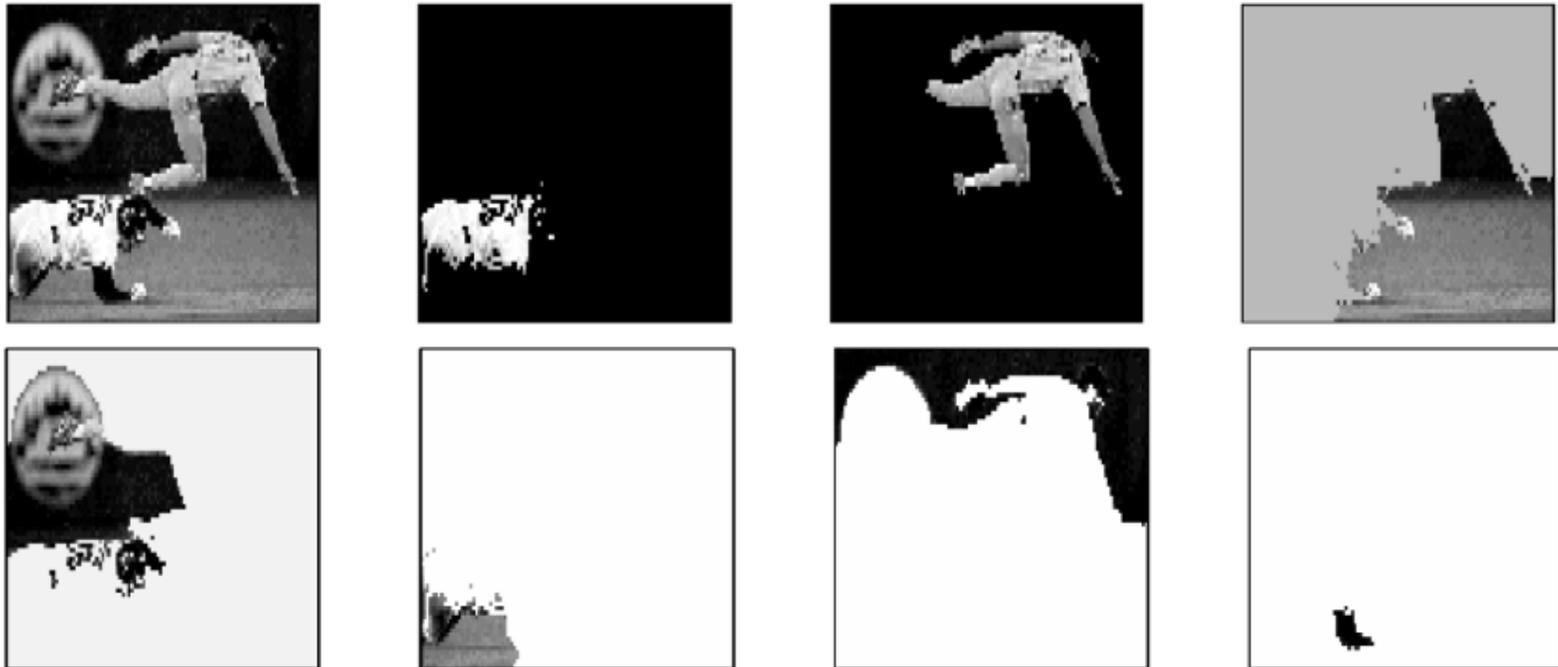
- Curve Evolution - parametric curve formulation



Non-rigid,  
deformable objects  
can change their  
shape over time,  
e.g. lips, hands...

# Normalized Cuts

- A graph-theoretic formulation for segmentation

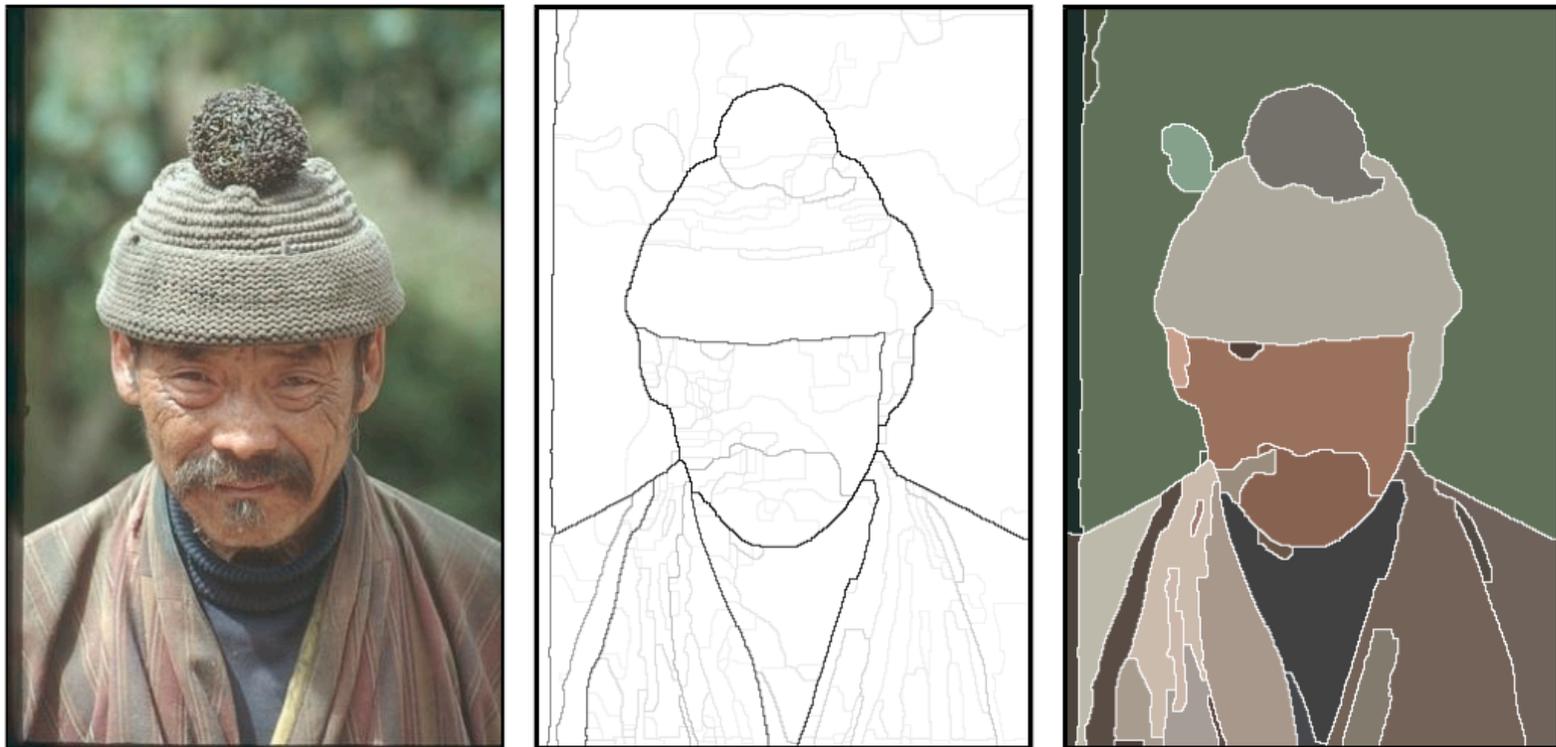


# Normalized Cuts



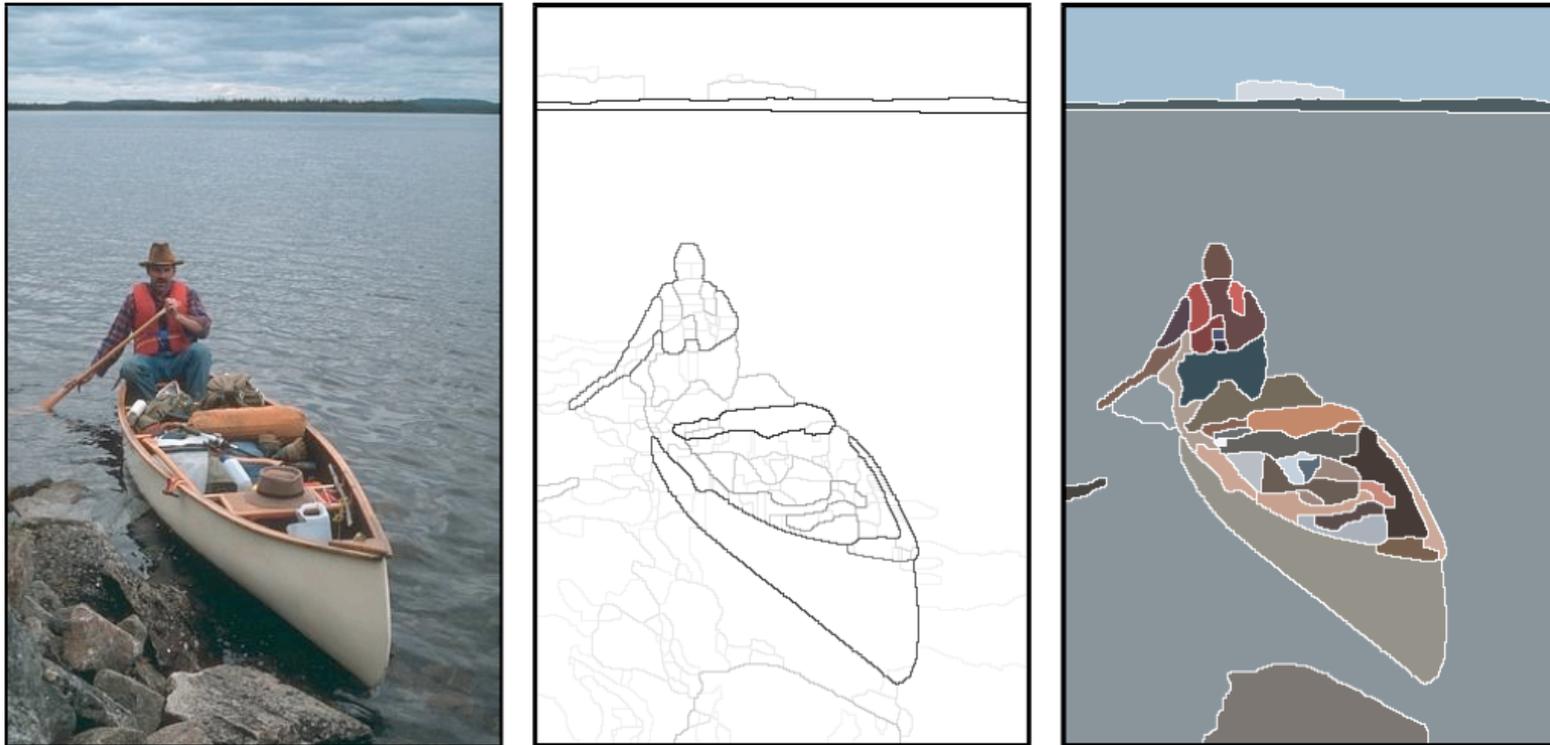
# From contours to regions

- State-of-the-art: gPb-owt-ucm segmentation algorithm



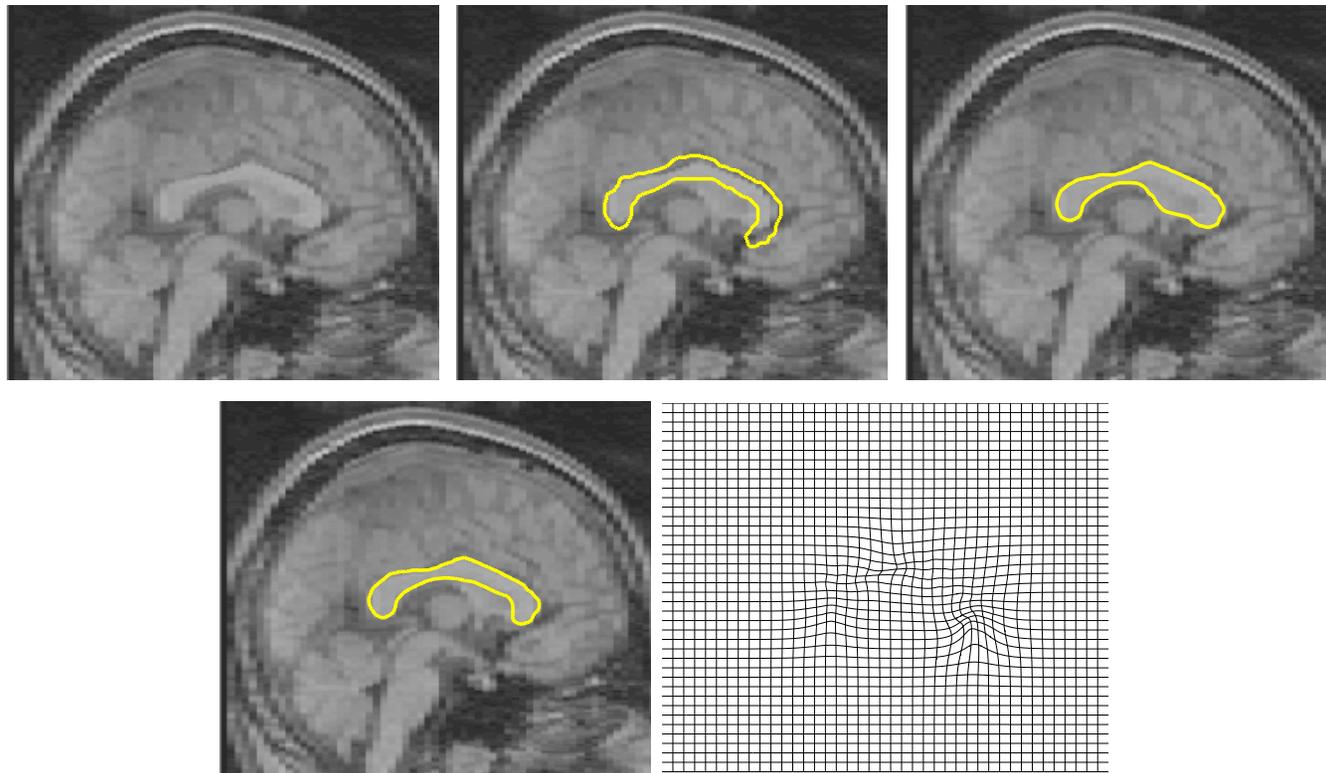
# From contours to regions

- State-of-the-art: gPb-owt-ucm segmentation algorithm



# Prior-Shape Guided Segmentation

- Incorporate prior shape information into the segmentation process



Our result

Deformation map

E. Erdem, S. Tari, and L. Vese, Segmentation Using The Edge Strength Function as a Shape Prior within a Local Deformation Model, ICIP 2009

# Image Inpainting

- Reconstructing lost or deteriorated parts of images



What do these examples demonstrate?



# Image Resizing

- Resize an image to arbitrary aspect ratios



# Image Retargetting

- a  
p



S. Avidan and A. Shamir, Seam Carving for Content-Aware Image Resizing, SIGGRAPH, 2007

# Image Retargeting



S. Avidan and A. Shamir, Seam Carving for Content-Aware Image Resizing, SIGGRAPH, 2007

# Image Retargeting



# Next week

- Image formation
- Digital camera and images