

BIL 717

Image Processing

Feb. 8, 2016

Introduction

Erkut Erdem

Hacettepe University

Computer Vision Lab (HUCVL)

Today

- About me
- About you
- Introduction to Image Processing
- Course outline and logistics

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About me

- Asst. Prof. Erkut Erdem

<http://web.cs.hacettepe.edu.tr/~erkut/>



Hacettepe University
Faculty Member
2010-now



Middle East Technical
University
1997-2008
Ph.D., 2008
M.Sc., 2003
B.Sc., 2001



Ecole Nationale
Supérieure des
Télécommunications
Post-doctoral Researcher
2009-2010



University of California
Los Angeles
Visiting Researcher
Oct. 2007 - Dec. 2007

About me

- Asst. Prof. Erkut Erdem

<http://web.cs.hacettepe.edu.tr/~erkut/>



HACETTEPE UNIVERSITY
COMPUTER VISION LAB

<http://vision.cs.hacettepe.edu.tr/>

About my research

- My research centers on the areas of computer vision and machine learning.
- specifically interested in the role of context in visual processing.
- I try to incorporate different kinds of context (*spatial, temporal* and/or *cross-modal*) into all levels of visual processing from low to mid and high-level vision.

About my research



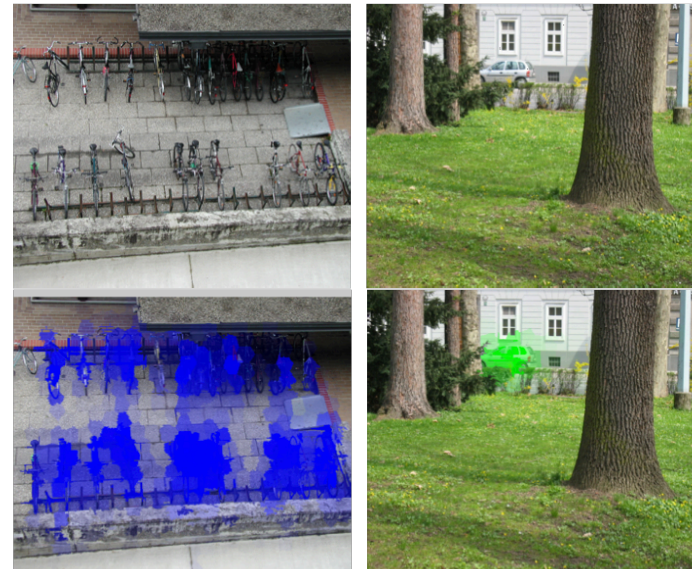
image smoothing



image colorization



visual saliency



object segmentation

Today

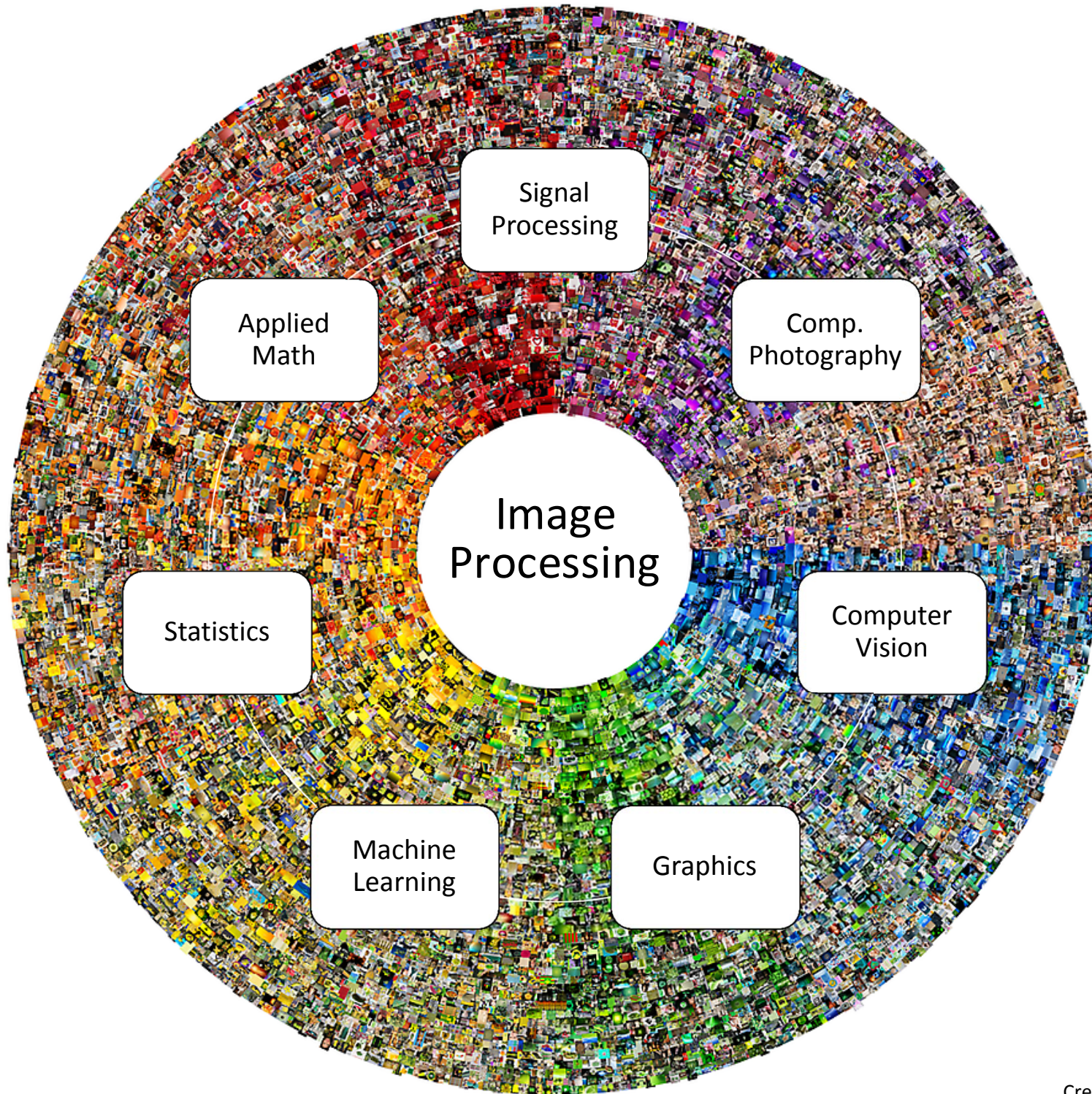
- About me
- About you
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Introduce yourselves

- Who are you?
- What do you know about image processing?
- Why you want to take BIL717?

Today

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- About you
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- Course outline and logistics



What does it mean, to see?

- *“The plain man’s answer (and Aristotle’s, too) would be, to know what is where by looking. In other words, vision is the process of discovering from images what is present in the world, and where it is.”* David Marr, Vision, 1982
- Our brain is able to use an image as an input, and interpret it in terms of objects and scene structures.



What does Salvador Dali's *Study for the Dream Sequence in Spellbound (1945)* say about our visual perception?



What does Paul Signac's *Place des Lices* (1893) say about our visual perception?

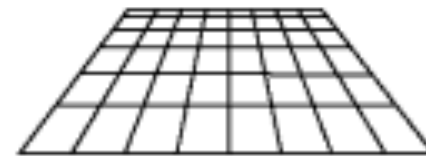
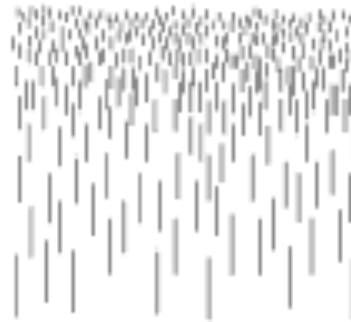


Why does vision appear easy to humans?

- Our brains are specialized to do vision.
- Nearly half of the cortex in a human brain is devoted to doing vision (cf. motor control ~20-30%, language ~10-20%)
- *“Vision has evolved to convert the ill-posed problems into solvable ones by adding premises: assumptions about how the world we evolved in is, on average, put together”*

Steven Pinker, How the Mind Works, 1997

- Gestalt Theory
(Laws of Visual Perception),
Max Wertheimer,
1912



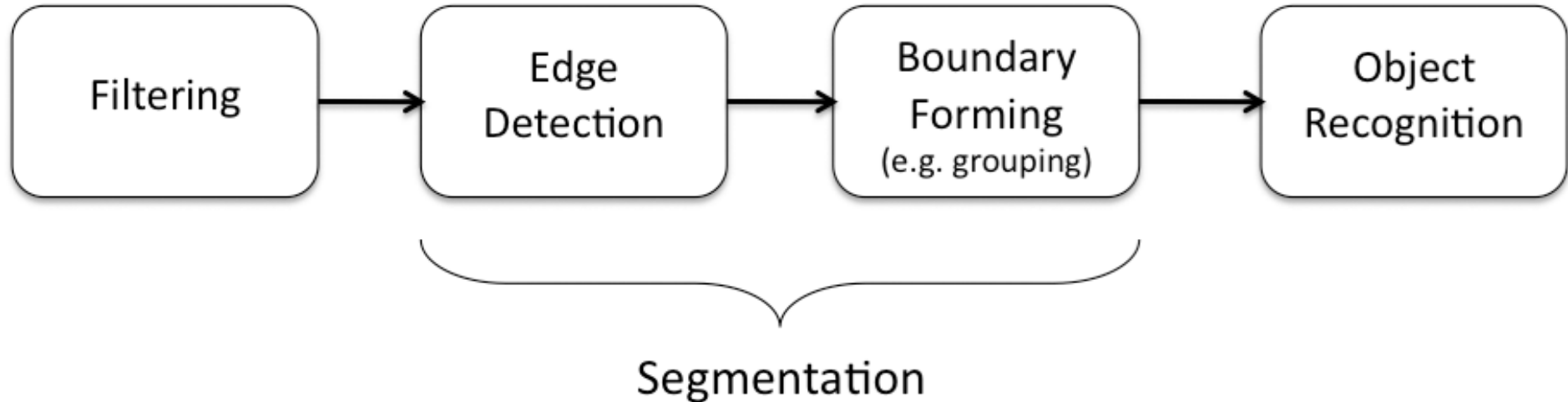
Computer Vision

- “Vision is a process that produces from images of the external world a description that is useful to the viewer and not cluttered with irrelevant information” ~David Marr
- The goal of Computer Vision:
To develop artificial machine vision systems that make inferences related to the scene being viewed through the images acquired with digital cameras.

Marr's observation: Studying vision at three different levels

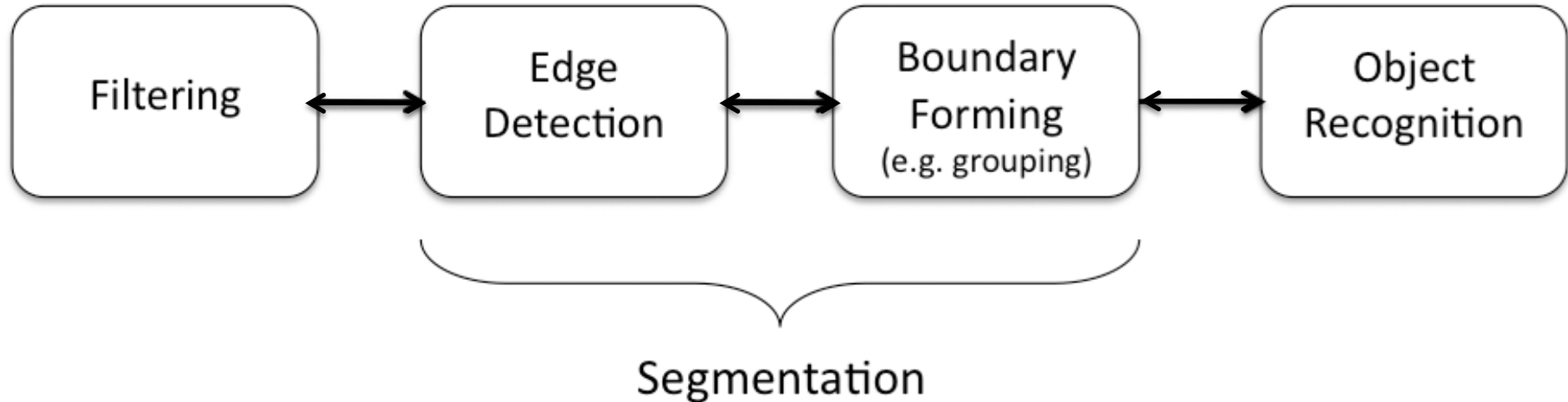
- Vision as an information processing task [David Marr, 1982]
- Three levels of understanding:
 1. Computational theory
 - What is computed? Why it is computed?
 2. Representation and Algorithm
 - How it is computed?
 - Input, Output, Transformation
 3. Physical Realization
 - Hardware

Visual Modules and the Information Flow



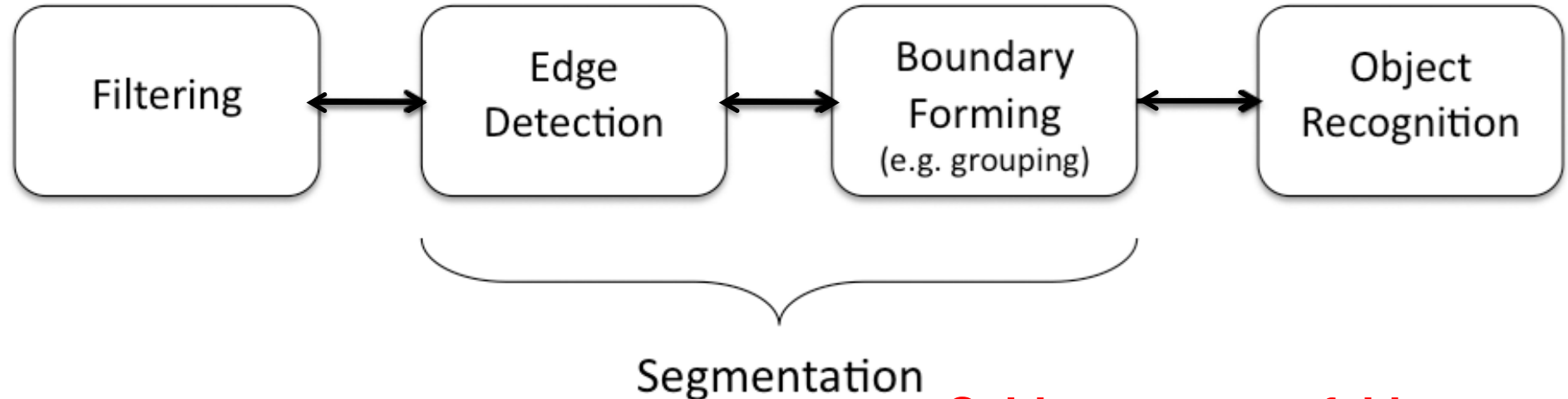
- Visual perception as a data-driven, bottom-up process (traditional view since D. Marr)
- Unidirectional information flow
- Simple low-level cues >> Complex abstract perceptual units

Visual Modules and the Information Flow



- Vision modules can be categorized into three groups according to their functionality:
 - Low-level vision: filtering out irrelevant image data
 - Mid-level vision: grouping pixels or boundary fragments together
 - High-level vision: complex cognitive processes

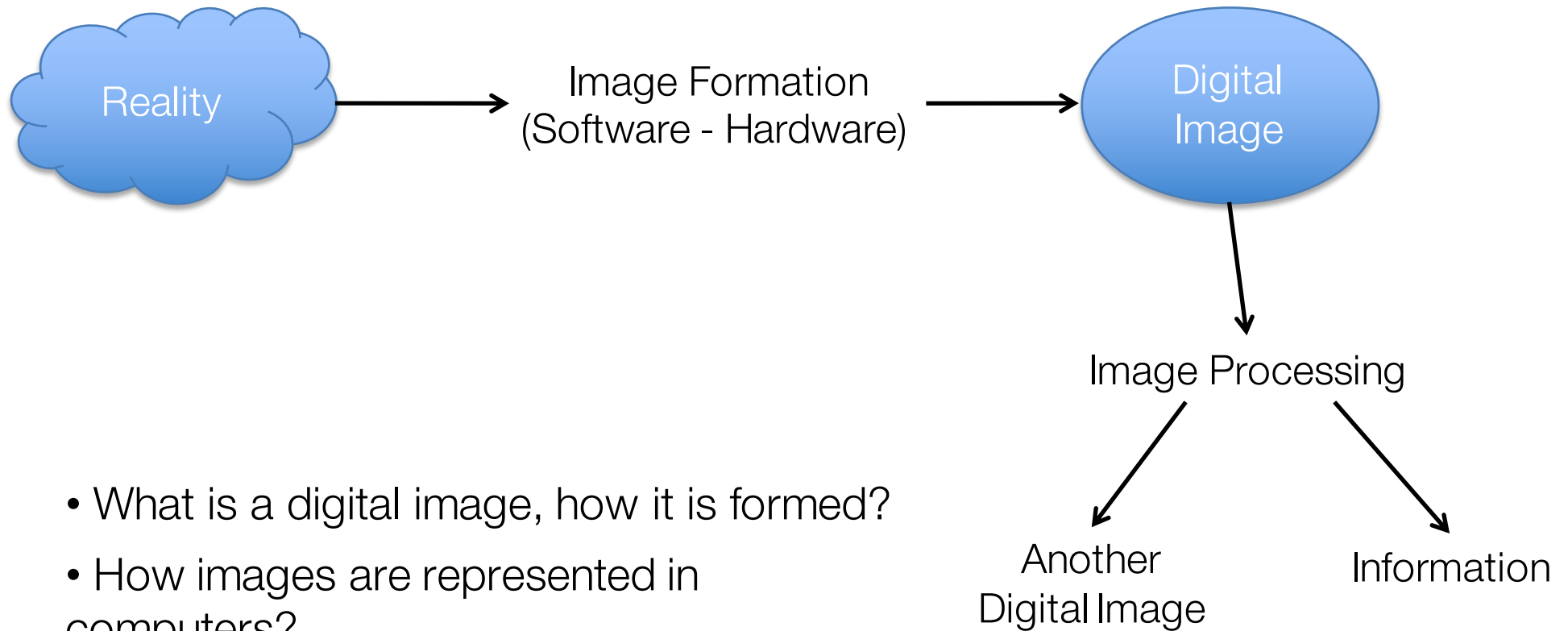
Visual Modules and the Information Flow



Subject matter of this course

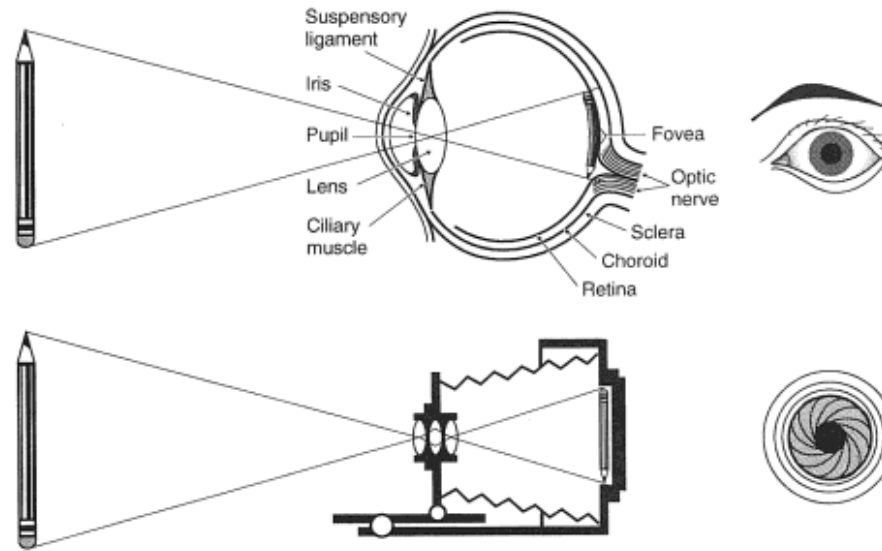
- Vision modules can be categorized into three groups according to their functionality:
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 - **Mid-level vision: grouping pixels or boundary fragments together**
 - High-level vision: complex cognitive processes

Fundamentals of Image Processing



- What is a digital image, how it is formed?
- How images are represented in computers?
- Why we process images?
- How we process images?

Image Formation



Three Dimensional World → Two Dimensional Image Space

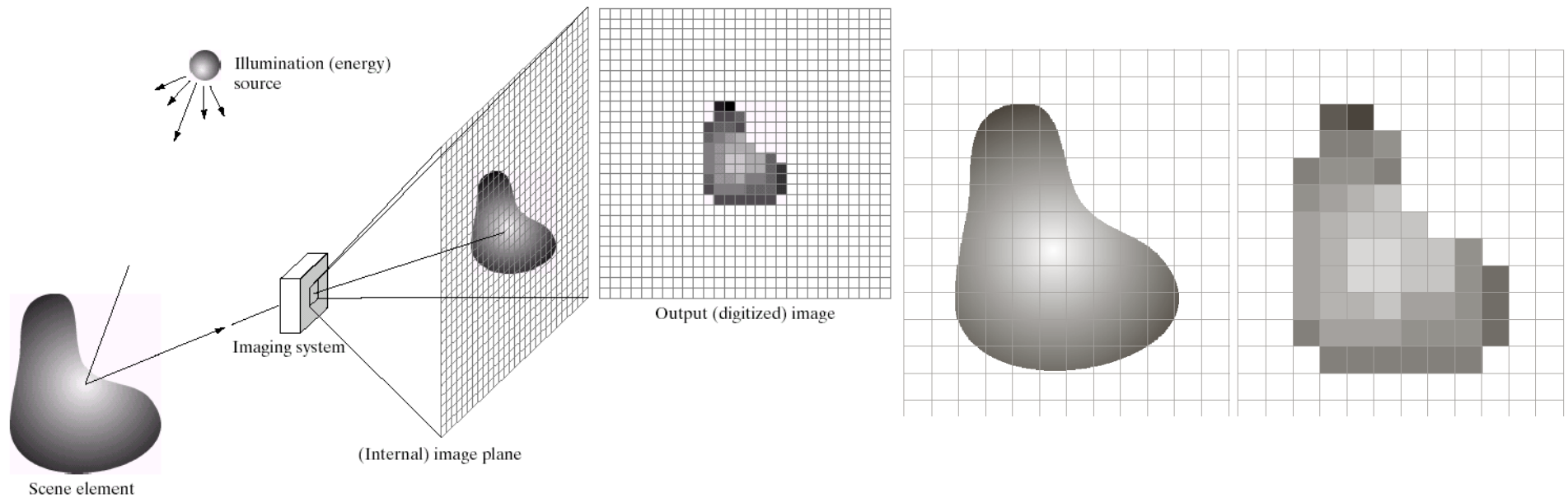
- What is measured in an image location?

- brightness
- color



viewpoint
illumination conditions
local geometry
local material properties

Image Formation



- Discretization
 - in image space - sampling
 - In image brightness - quantization

Image Representation

- **Digital image:** 2D discrete function f
- **Pixel:** Smallest element of an image $f(x,y)$

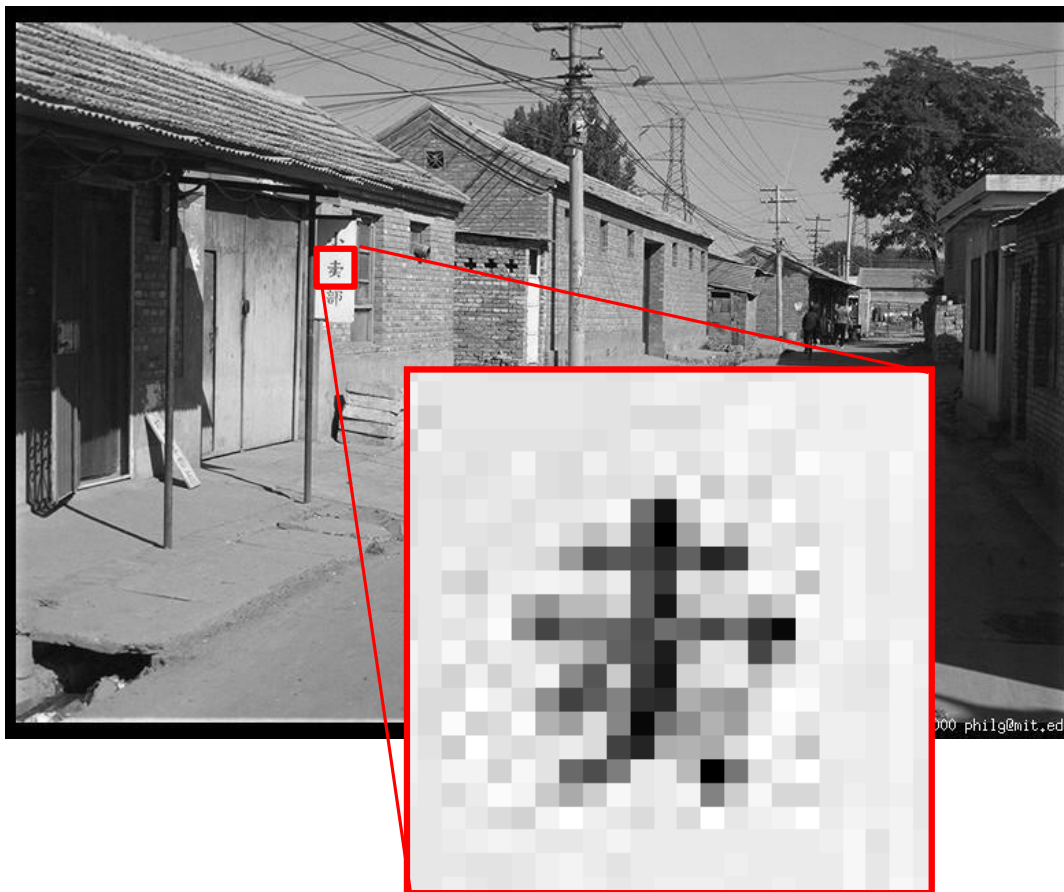


Figure: M. J. Black

Image Representation

- **Digital image:** 2D discrete function f
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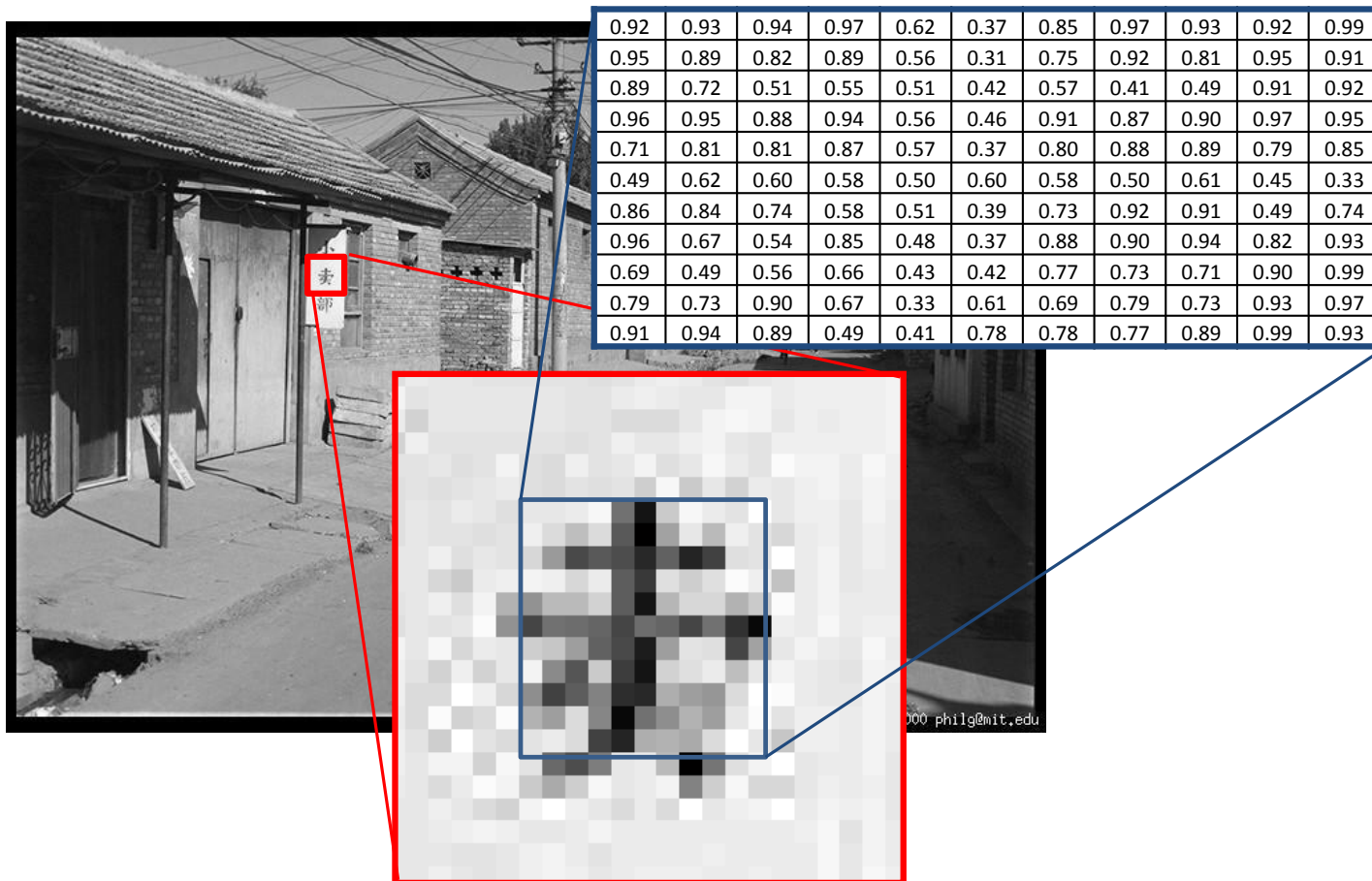


Figure: M. J. Black

Sample Problems and Techniques

- Edge Detection
- Image Denoising
- Image Smoothing
- Image Deblurring
- Image Segmentation
- Visual Saliency
- Semantic Segmentation
- PDEs
- Variational models
- MRFs
- Graph Theory
- Sparse Coding
- Deep Learning

Image Filtering

- Filtering out the irrelevant information

$$f(x) = u(x) + n(x)$$

↓ ↓ ↓

observed desired irrelevant
image image data

- Image denoising, image sharpening, image smoothing, image deblurring, etc.
- Edge detection

Edge Detection



Canny edge detector

- Edges: abrupt changes in the intensity
 - Uniformity of intensity or color
- Edges to object boundaries

Image Filtering

- **Difficulty:** Some of the irrelevant image information have characteristics similar to those of important image features

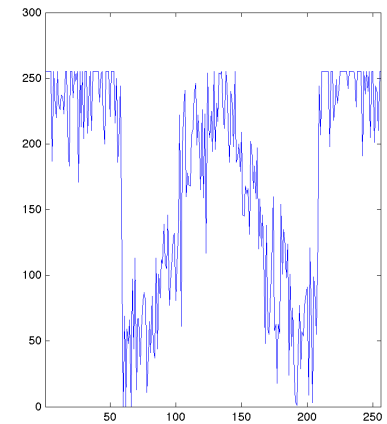
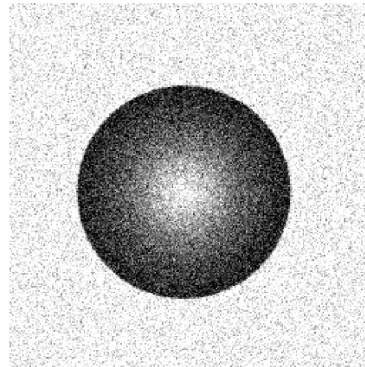
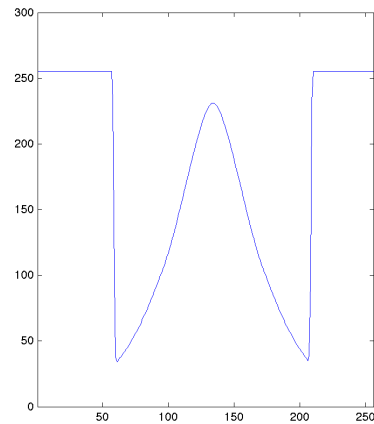
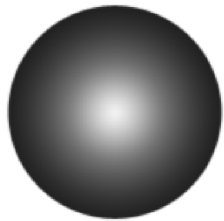


Image Smoothing - A Little Bit of History

- Gaussian Filtering / linear diffusion $\frac{\partial u}{\partial t} = \nabla \cdot (\nabla u) = \nabla^2 u$
 - the most widely used method



- mid 80's – unified formulations
 - methods that combine smoothing and edge detection
 - Geman & Geman'84, Blake & Zisserman'87, Mumford & Shah'89, Perona & Malik'90

Image Denoising

- Images are corrupted with 70% salt-and-pepper noise



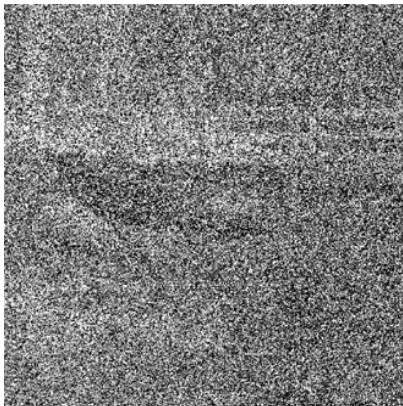
Noisy input



Recovered image



Original image



Noisy input



Recovered image



Original image

What do these examples demonstrate?

Non-local Means Denoising

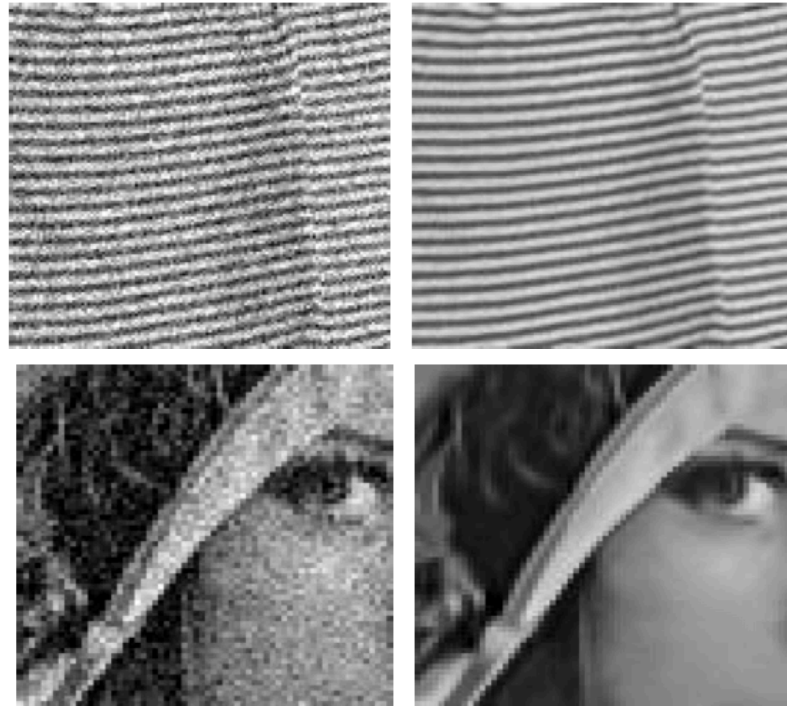
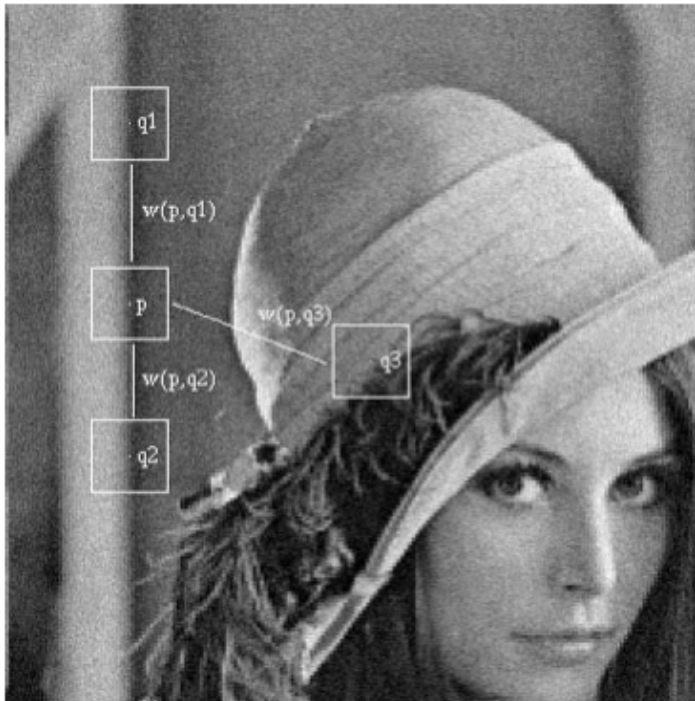
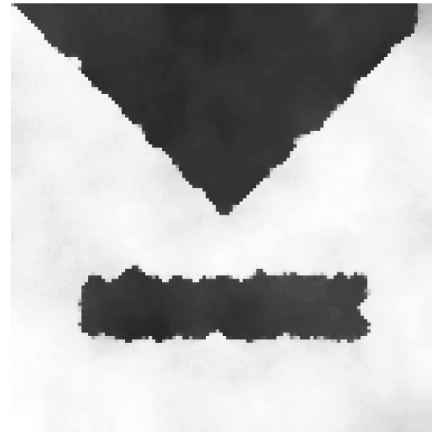
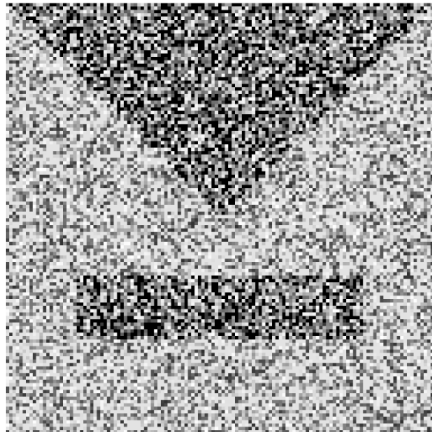


Figure 1. Scheme of NL-means strategy. Similar pixel neighborhoods give a large weight, $w(p,q1)$ and $w(p,q2)$, while much different neighborhoods give a small weight $w(p,q3)$.

Preserve fine image details and texture during denoising

Context-Guided Filtering

- Use local image context to steer filtering



Preserve main image structures during filtering



Image Smoothing



L. Xu, C. Lu, Y. Xu, J. Jia, Image Smoothing via L0 Gradient Minimization, ACM Trans. Graphics 2011 (SIGGRAPH Asia 2011)

Image Smoothing



L. Karacan, E. Erdem, A. Erdem, Structure Preserving Image Smoothing via Region Covariances, ACM Trans. Graphics 2013 (SIGGRAPH Asia 2013)

Image Deblurring

- Remove blur and restore a sharp image



from a given blurred image



find its latent sharp image

Image Deblurring

- Remove blur and restore a sharp image



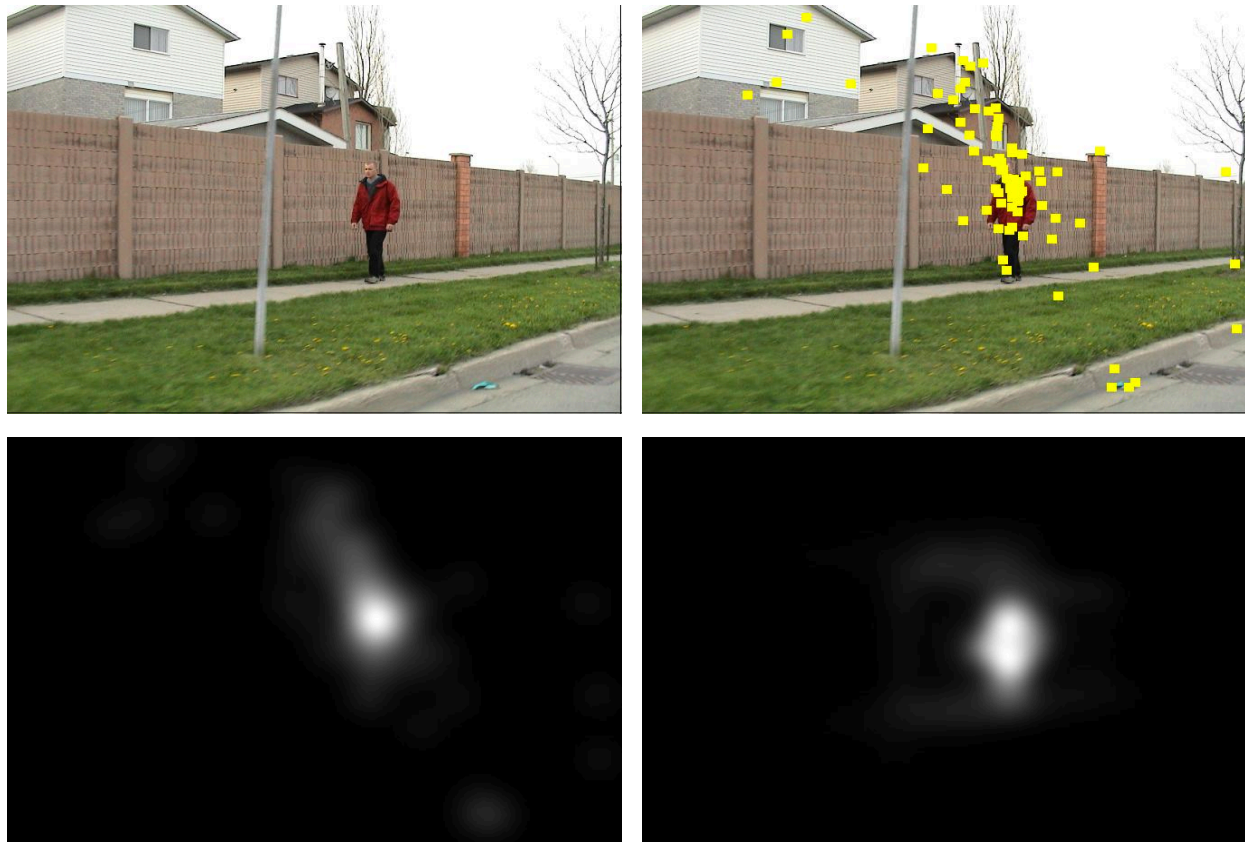
Input blurred image



Levin et al. CVPR 2010

Visual Saliency

- The problem of predicting where people look at images



The squares shows where the observers looked
in eye tracking experiments

Visual Saliency

- The problem of predicting where people look at images

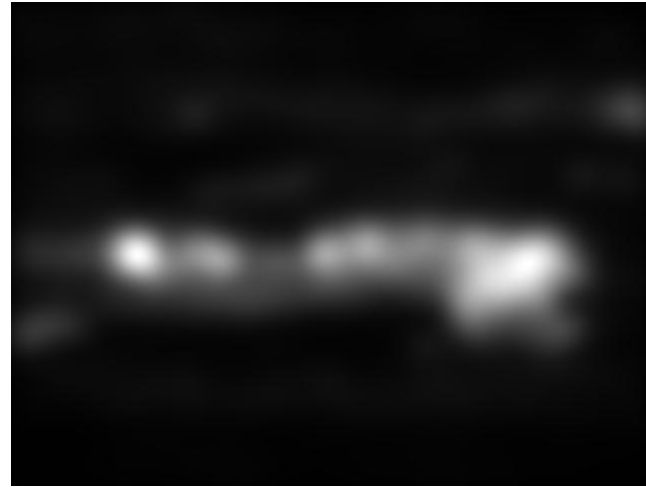


Image Retargetting

- automatically resize an image to arbitrary aspect ratios while preserving important image features

How we define the importance?



Image retargeting by Seam Carving with different importance maps

Input

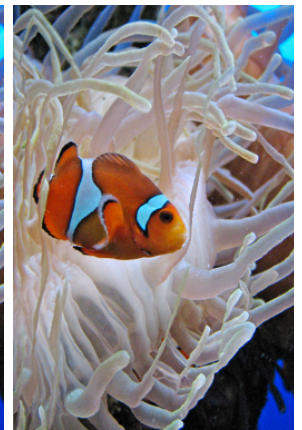
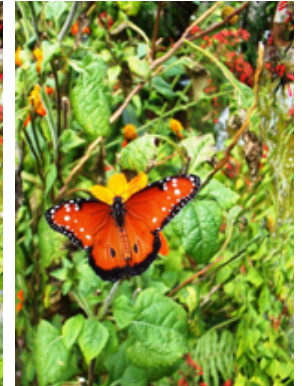
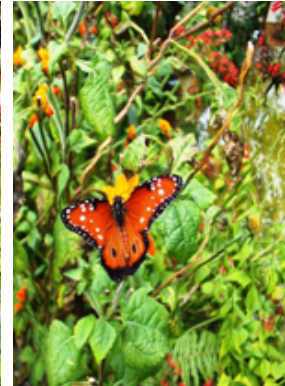
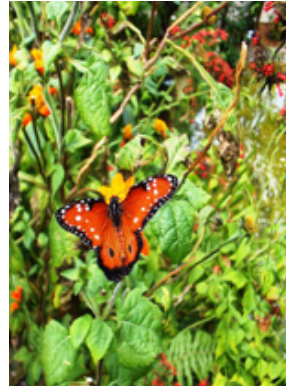
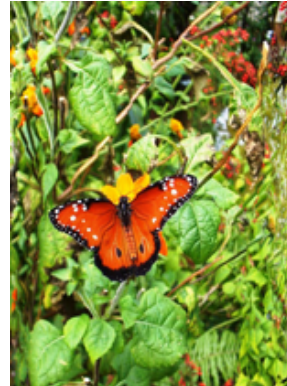
Seam Carving

GBVS

sigLab

sigRGB

CovSal



Sparse Coding

- The problem of finding a small number of representative atoms from a dictionary which when combined with right weights represent a given signal.

The diagram illustrates the sparse coding process. On the left is the target image y , a grayscale photo of a woman wearing sunglasses. This is equal to the product of a dictionary L (a 4x4 grid of 16 grayscale face images) and a sparse coefficient vector x (a plot with a y-axis from 0 to 250 and an x-axis from 0 to 200, showing a single prominent red spike at approximately x=180 and several smaller blue spikes). This product is then added to a residual image e , which is a dark grayscale image of the same woman's face, representing the error or noise.

$$y = Lx + e$$

Low-Rank Matrix Approximations

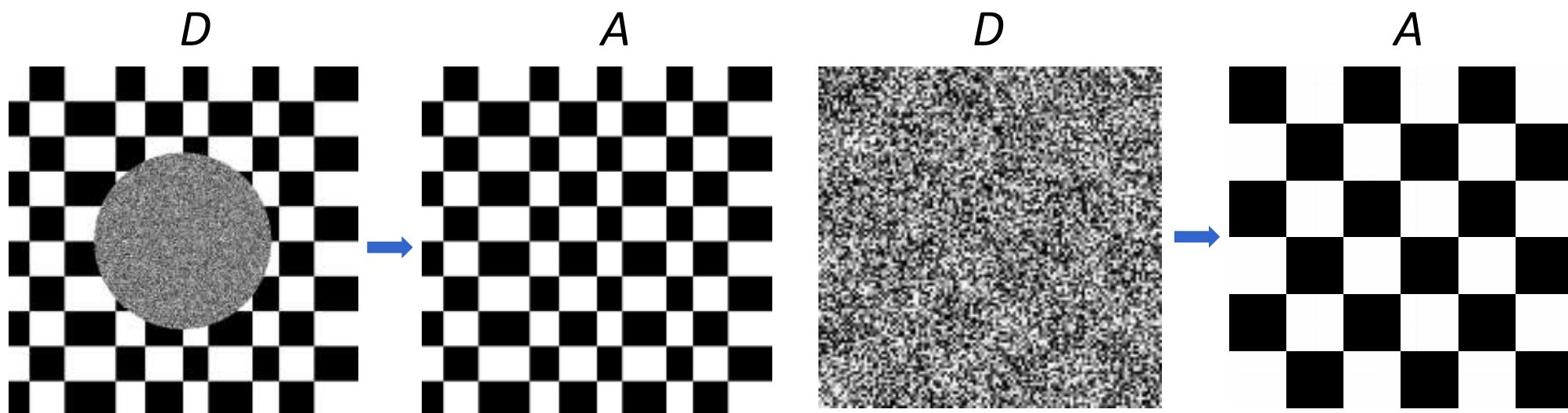
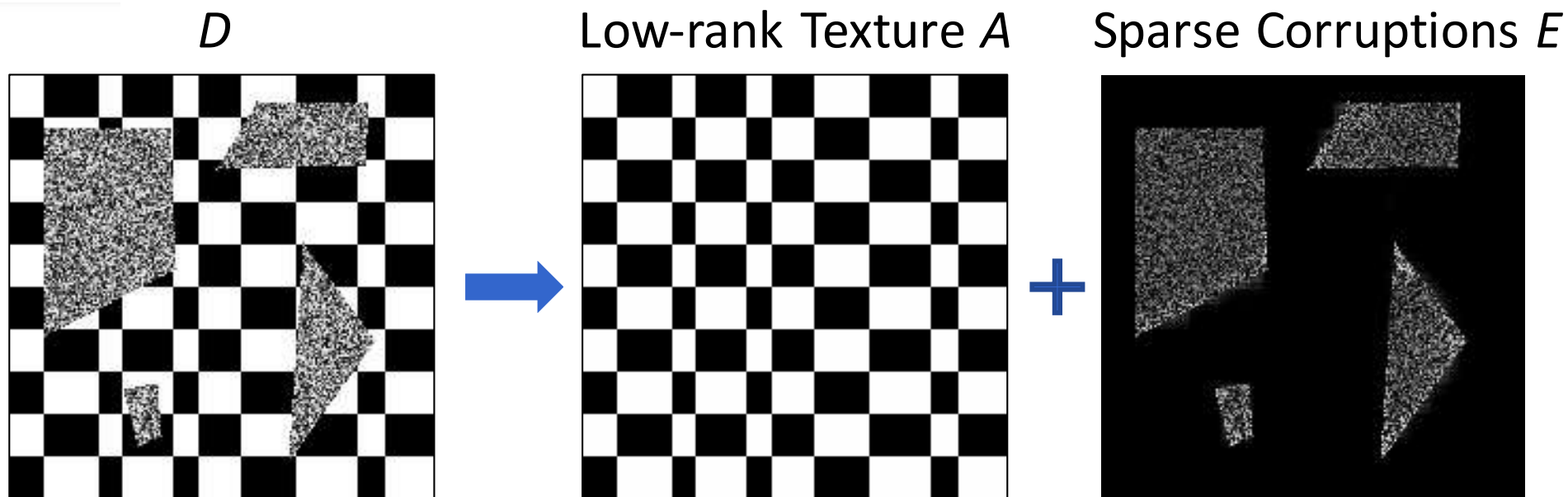


Image Inpainting

- Reconstructing lost or deteriorated parts of images



What do these examples demonstrate?



Image Segmentation

- Partition an image into meaningful regions that are likely to correspond to objects exist in the image



Grouping of pixels according to what criteria?

high-level object specific knowledge matters!

Image Segmentation

- Boundary-based segmentation
- Region-based segmentation
- Unified formulations

Snakes

- Curve Evolution - parametric curve formulation

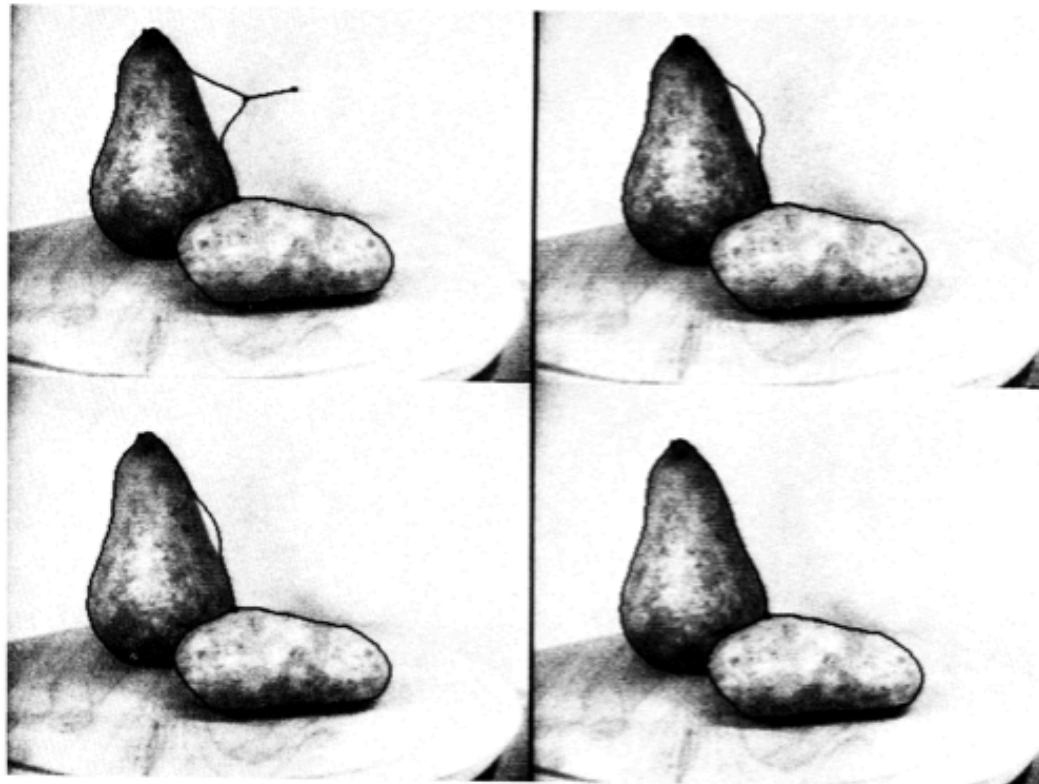
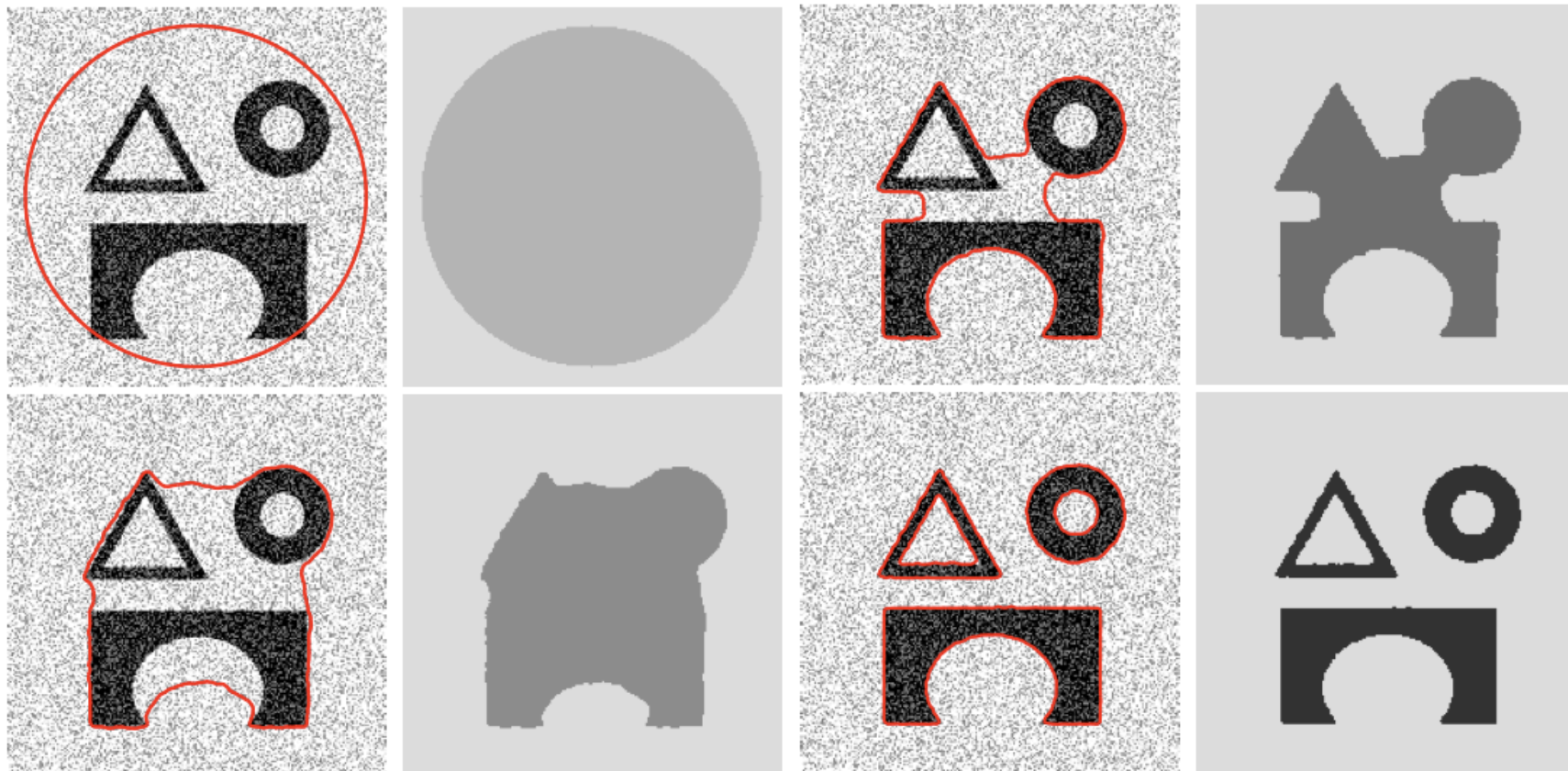


Fig. 3. Two edge snakes on a pear and potato. Upper-left: The user has pulled one of the snakes away from the edge of the pear. Others: After the user lets go, the snake snaps back to the edge of the pear.

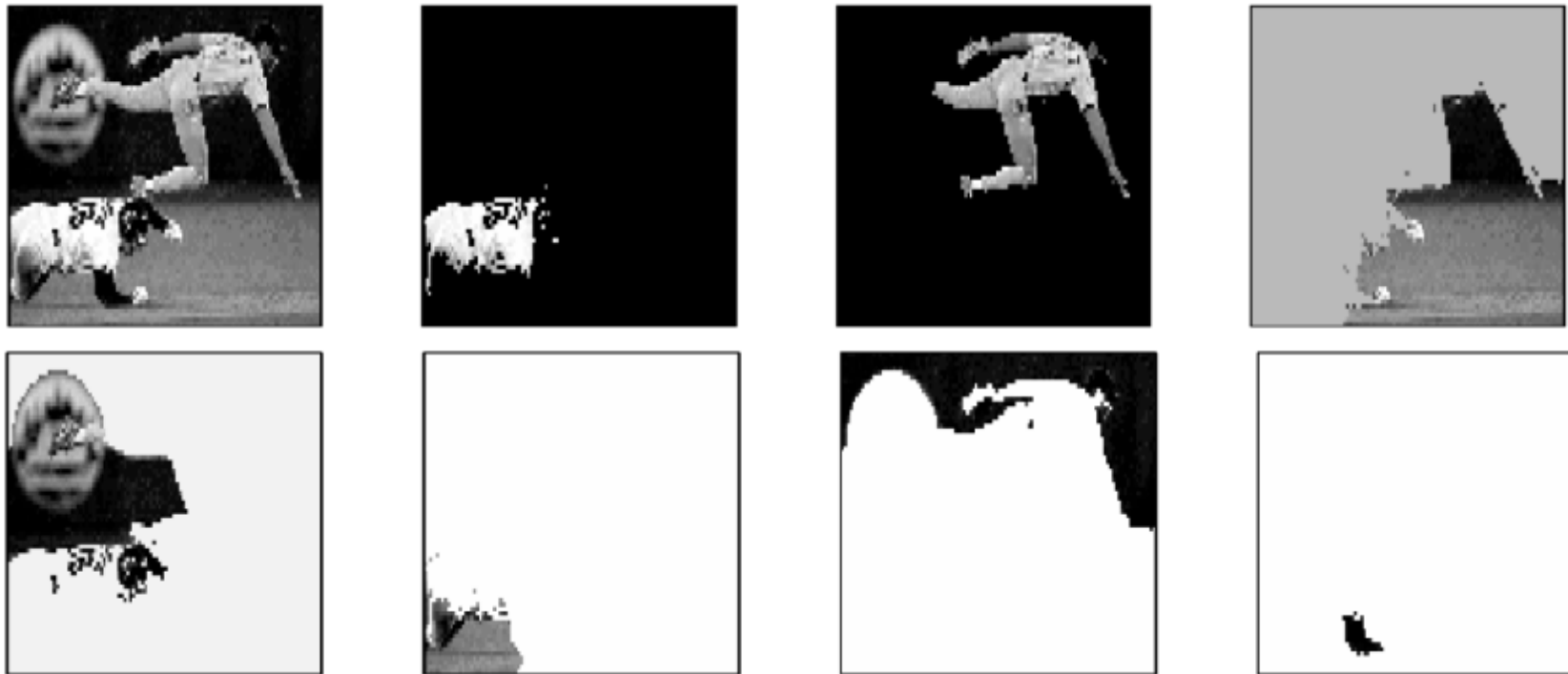
Active Contours Without Edges

- Curve Evolution – a level-set based curve formulation



Normalized Cuts

- A graph-theoretic formulation for segmentation



Normalized Cuts



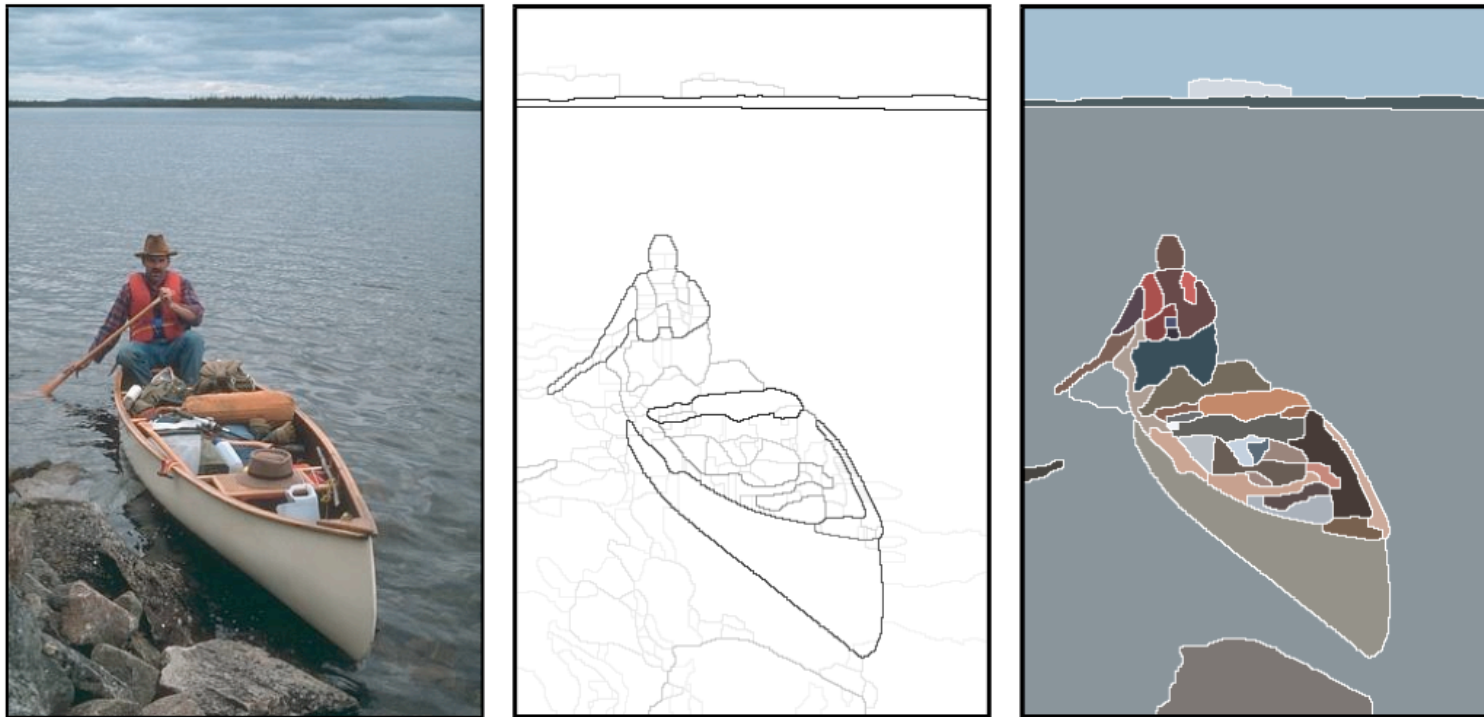
From contours to regions

- State-of-the-art: gPb-owt-ucm segmentation algorithm



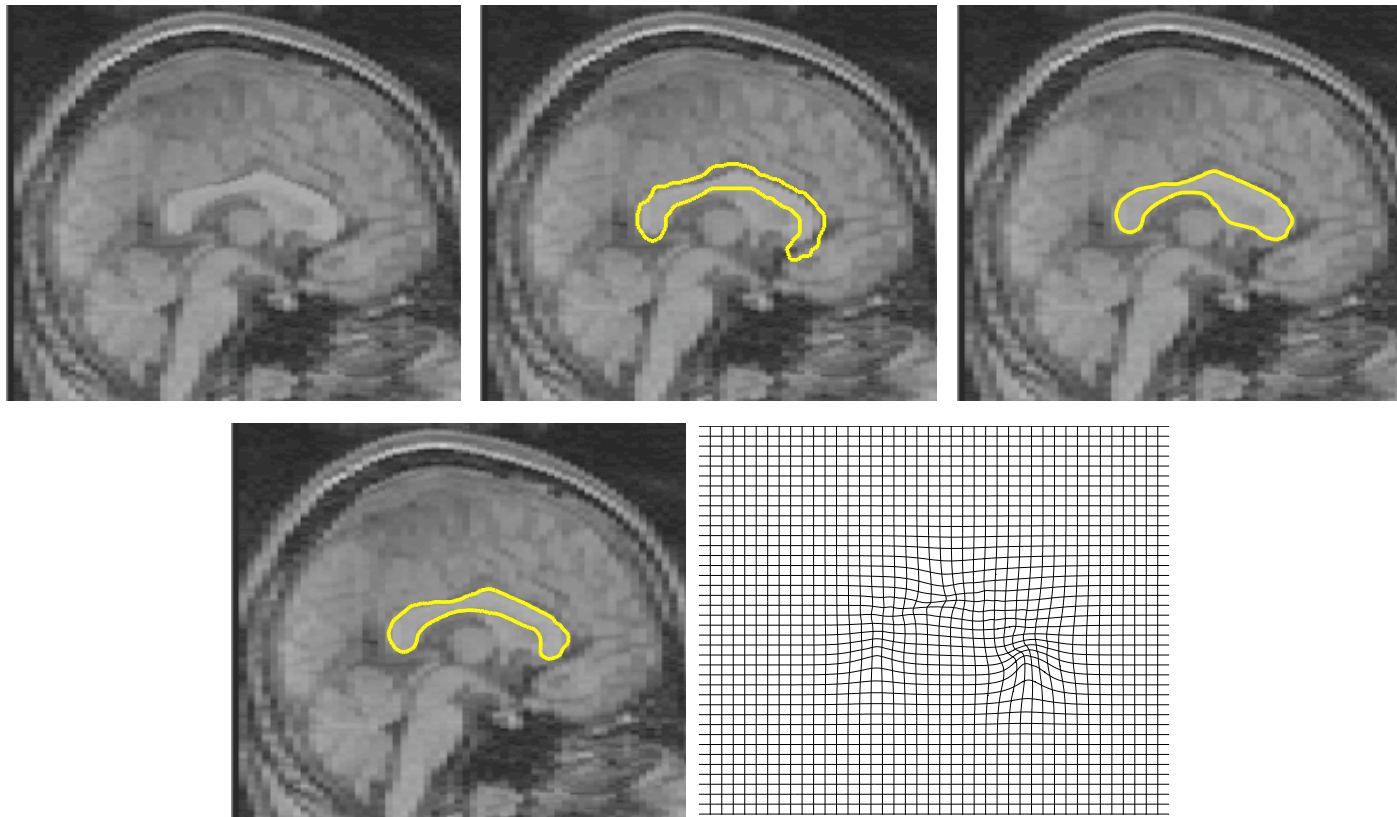
From contours to regions

- State-of-the-art: gPb-owt-ucm segmentation algorithm



Prior-Shape Guided Segmentation

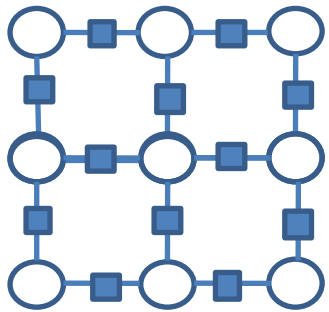
- Incorporate prior shape information into the segmentation process



Our result

Deformation map

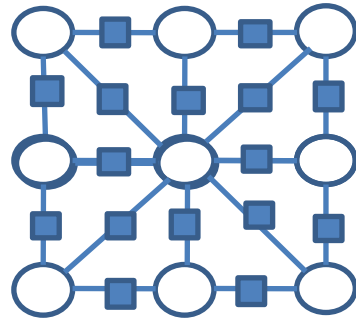
Graphical Models in Vision



4-connected;
pairwise MRF

$$E(x) = \sum_{i,j \in N_4} \theta_{ij}(x_i, x_j)$$

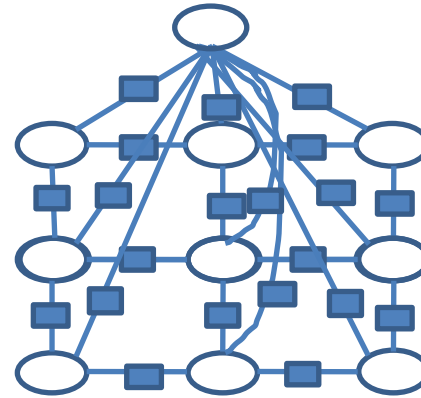
Order 2



higher(8)-connected;
pairwise MRF

$$E(x) = \sum_{i,j \in N_8} \theta_{ij}(x_i, x_j)$$

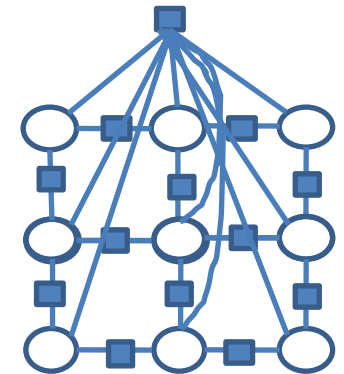
Order 2



MRF with
global variables

$$E(x) = \sum_{i,j \in N_8} \theta_{ij}(x_i, x_j)$$

Order 2

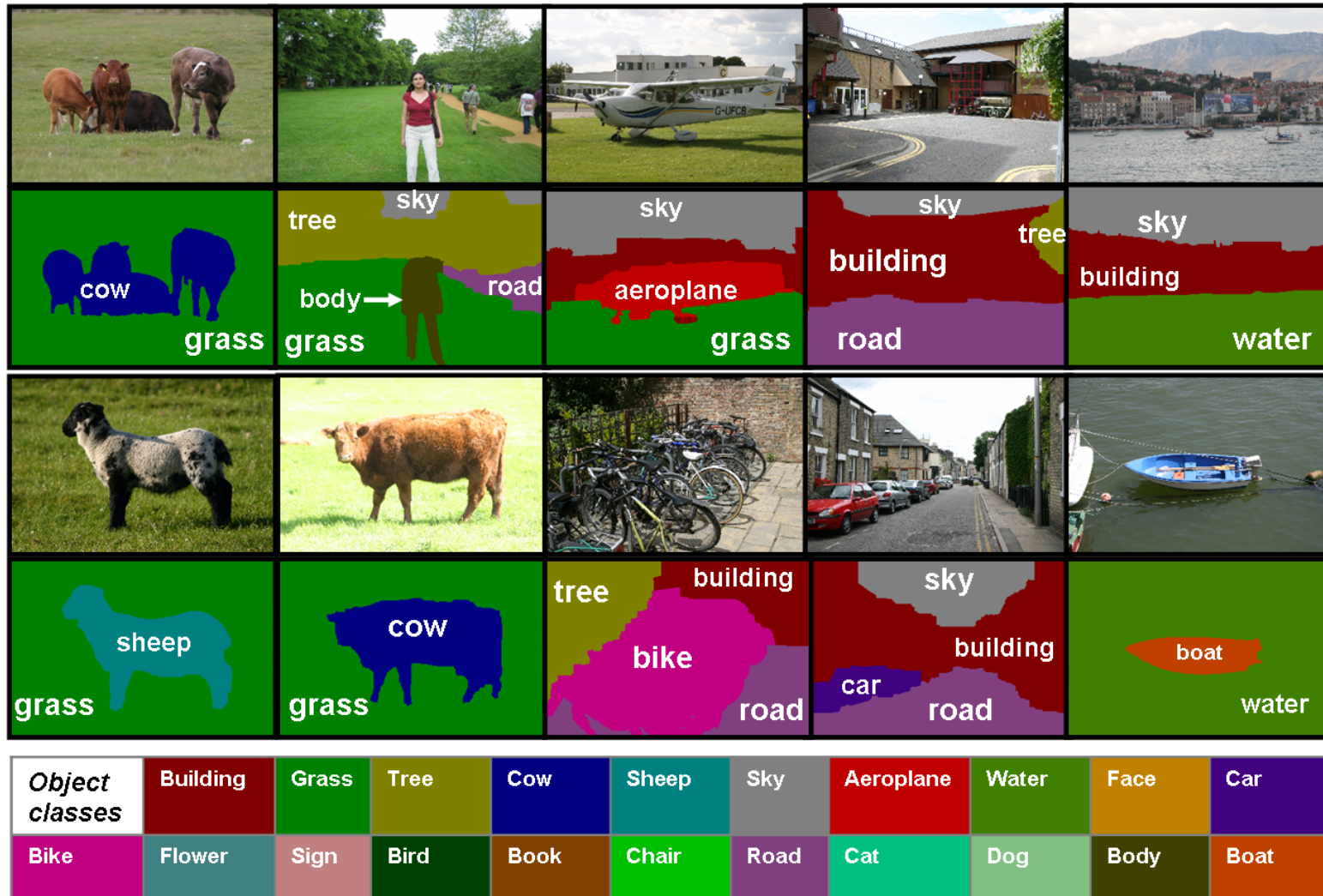


Higher-order MRF

$$E(x) = \sum_{i,j \in N_4} \theta_{ij}(x_i, x_j) + \theta(x_1, \dots, x_n)$$

Order n

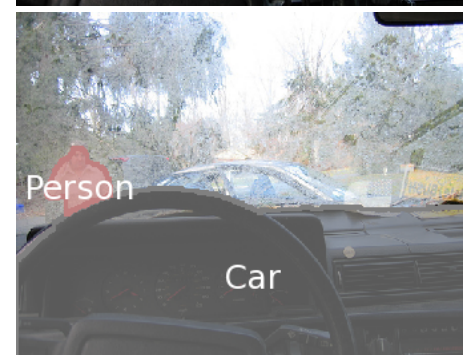
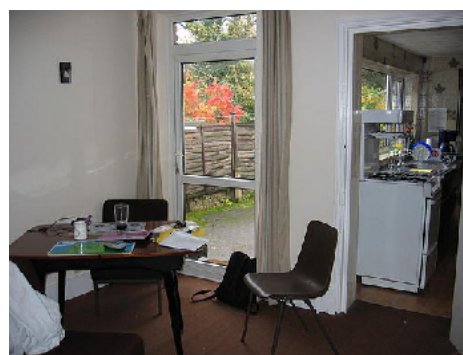
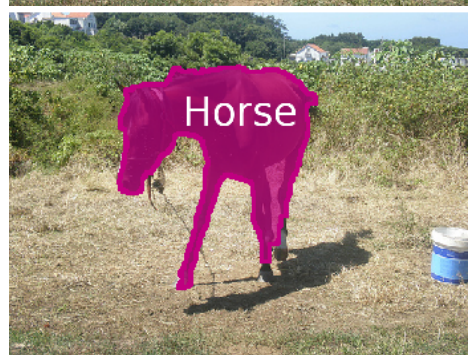
Semantic Segmentation



[TextonBoost; Shotton et al, '06]

Semantic Segmentation

- The problem of joint recognition and segmentation



Top-down Saliency

- Task-oriented models (e.g. searching for a target object from a specific category)



Top-down Saliency

- Task-oriented models (e.g. searching for a target object from a specific category)

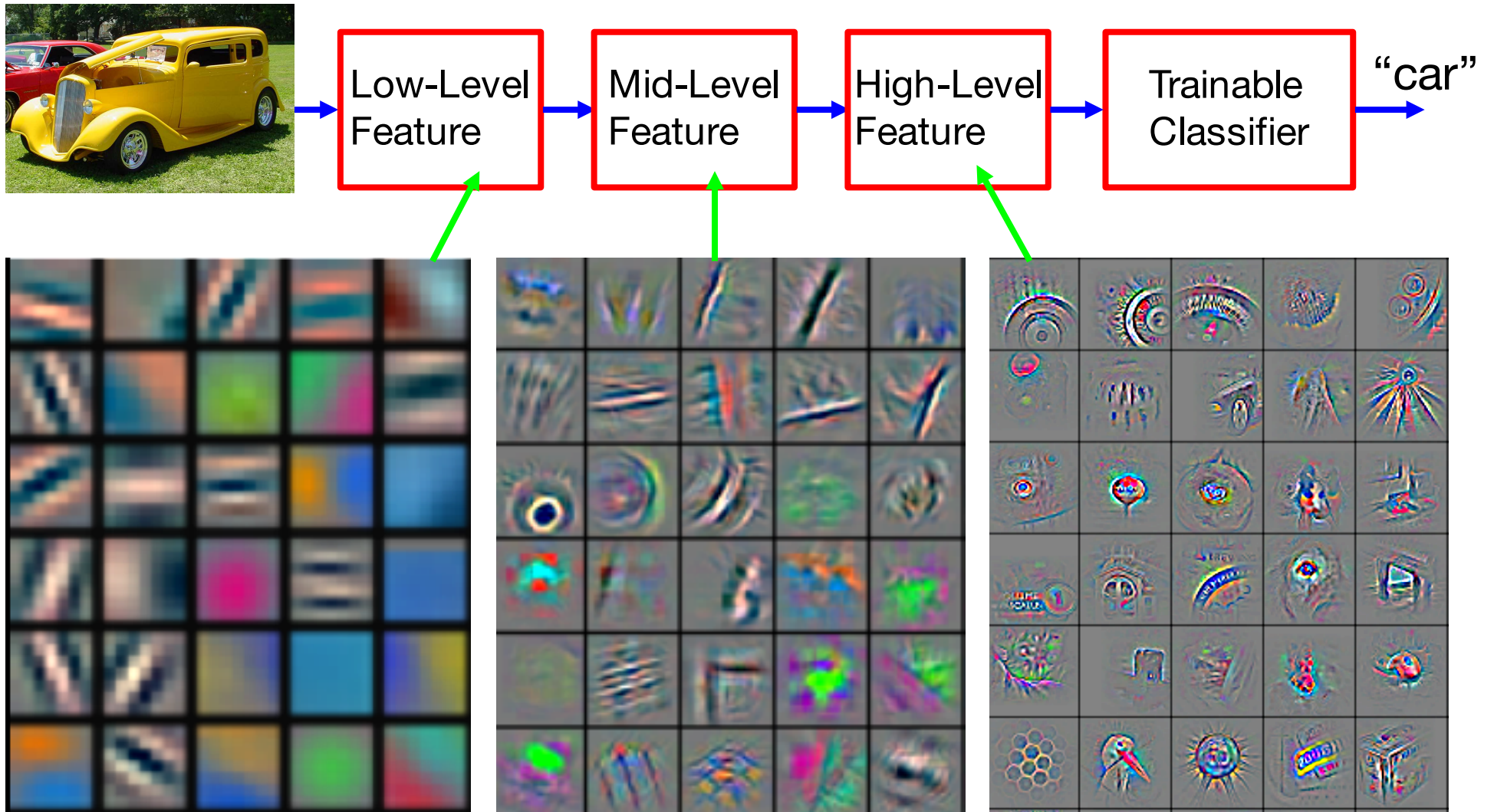


Top-down Saliency

- Task-oriented models (e.g. searching for a target object from a specific category)



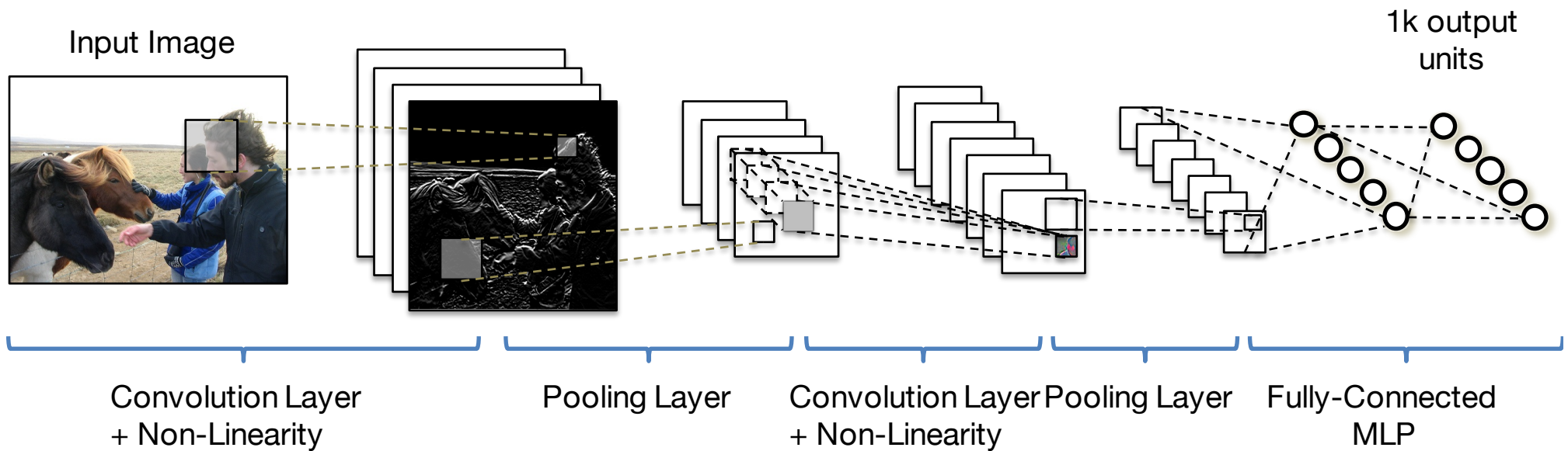
Deep Learning



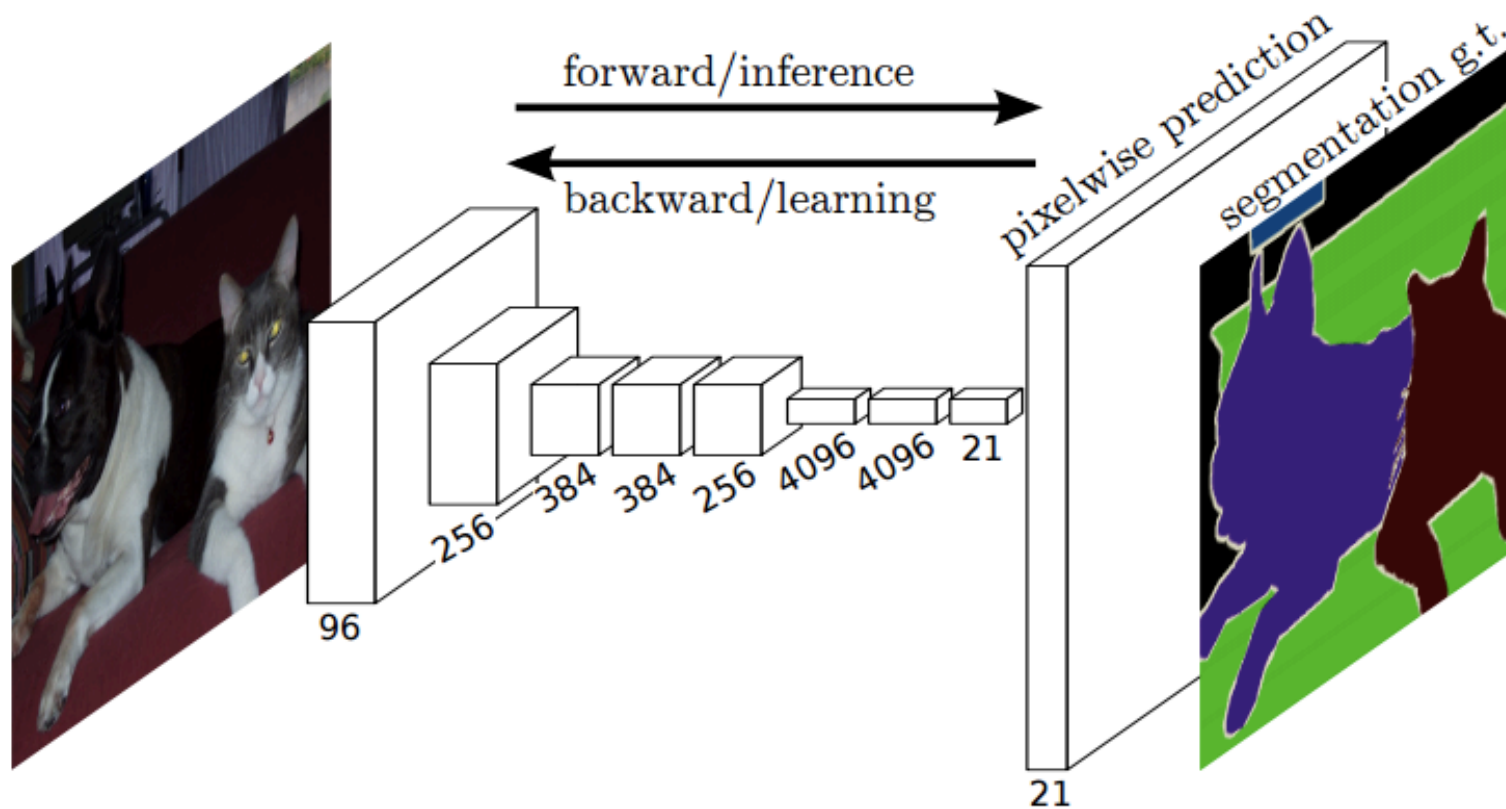
Feature visualization of convolutional net trained on ImageNet from [Zeiler & Fergus 2013]

Deep Learning

- [Krizhevsky et al. NIPS12]
 - 54 million parameters; 8 layers (5 conv, 3 fully-connected)
 - Trained on 1.4M images in ImageNet



Deep Learning



Fully Convolutional Networks for Semantic Segmentation[Long, Shelmer & Darrell 2015]

Today

- About me
- About you
- Introduction to Image Processing
- Course outline and logistics

Logistics

- Asst. Prof. Erkut ERDEM
- erkut@cs.hacettepe.edu.tr
- Office: 114

- Lectures: Monday, 13:30-16:30
- Office Hour: *By appointment.*

About BIL717

- This course provides a comprehensive overview of fundamental topics in image processing for graduate students.
- The goal of this course is to provide a deeper understanding of the state-of-the-art methods in image processing literature and to study their connections.
- The course makes the students gain knowledge and skills in key topics and provides them the ability to employ them in their advanced-level studies.

Communication

- The course webpage will be updated regularly throughout the semester with lecture notes, programming and reading assignments and important deadlines.

<http://web.cs.hacettepe.edu.tr/~erkut/bil717.s16>

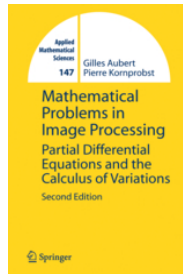
- All other communications will be carried out through Piazza. Please enroll it by following the link

<https://piazza.com/hacettepe.edu.tr/spring2016/bil717>

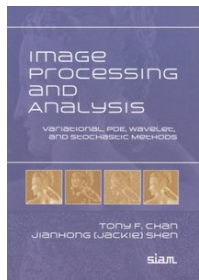
Prerequisites

- Programming skills
(C/C++, Matlab)
- Good math background
(Calculus, Linear Algebra, Statistical Methods)
- A prior, introductory-level course in image processing is highly recommended.

Reference Books



- Mathematical Problems in Image Processing: Partial Differential Equations and the Calculus of Variations, G. Aubert and P. Kornprobst, 2nd Edition, Springer-Verlag, 2006



- Image Processing And Analysis: Variational, PDE, Wavelet, And Stochastic Methods, T. Chan and J. Shen, Society for Industrial and Applied Mathematics, 2005



- Markov Random Fields For Vision And Image Processing, Edited by A. Blake, P. Kohli and C. Rother, MIT Press, 2011
- Deep Learning, Ian Goodfellow, Aaron Courville, and Yoshua Bengio, book in preparation for MIT Press

Reading Material

- Lecture notes and handouts
- Papers and journal articles

Related Conferences

- IEEE International Conference on Computer Vision (ICCV)
- European Conference on Computer Vision (ECCV)
- IEEE Conference on Computer Vision and Pattern Recognition (CVPR)
- IEEE Winter Conference on Applications of Computer Vision (WACV)
- British Machine Vision Conference (BMVC)
- ACM SIGGRAPH
- ACM SIGGRAPH Asia
- Advances in Neural Information Processing Systems (NIPS)
- IEEE International Conference on Pattern Recognition (ICPR)
- IEEE International Conference on Image Processing (ICIP)

Related Journals

- IEEE Transactions on Image Processing (IEEE TIP)
- IEEE Transactions on Pattern Analysis and Machine Intelligence (IEEE TPAMI)
- ACM Transactions on Graphics (TOG)
- International Journal of Computer Vision (IJCV)
- Computer Vision and Image Understanding (CVIU)
- Image and Vision Computing (IMAVIS)
- Pattern Recognition (PR)

Grading Policy

- 20% Quizzes
- 20% Programming Assignments
- 20% Paper presentations/Class participation
- 40% Project and final term paper

Paper presentations and Quizzes

- The students will be required to present at least one research paper either of their choice or from the suggested reading list.
- These papers should be read by every student as the quizzes about the presented papers will be given on the weeks of the presentations.
- The schedule for the presentations will be finalized on 15th of February.

Programming Assignments

- There will be three assignments related to the topics covered in the class.
- Each assignment will involve implementing an algorithm, carrying out a set of experiments to evaluate it, and writing up a report on the experimental results.
- All assignments have to be done individually, unless stated otherwise.

Project

- The aim of the project is to give the students some experience on conducting research.
- Students should work individually or groups in two.
- This project may involve
 - design of a novel approach and its experimental analysis,
 - an extension to a recent study (published after 2010) of non-trivial complexity and its experimental analysis,
 - an in-depth empirical evaluation and analysis of two or more related methods not covered in the class.

Project – Important Dates

- Project proposals: 29th of February
 - Project progress reports: 4th of April
 - Project progress presentations: 11th of April
 - Project presentations: *will be announced!*
 - Project final reports: 23rd of May
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- Late submissions will be penalized!

Tentative Outline

- (1 week) Overview of Image Processing
- (1 week) Edge Detection, Linear Filtering
- (1 week) Image Segmentation, Boundary Detection
- (1 week) Nonlinear Filtering
- (1 week) Snakes, Variational Segmentation Models
- (2 weeks) Modern Image Filtering
- (1 week) Image Deblurring

Tentative Outline

- (1 week) Sparse Coding
- (1 week) Graphical Models
- (1 week) Semantic Segmentation
- (1 week) Visual Saliency
- (1 week) Deep Learning