

Category-Independent Object-level Saliency Detection

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Introduction

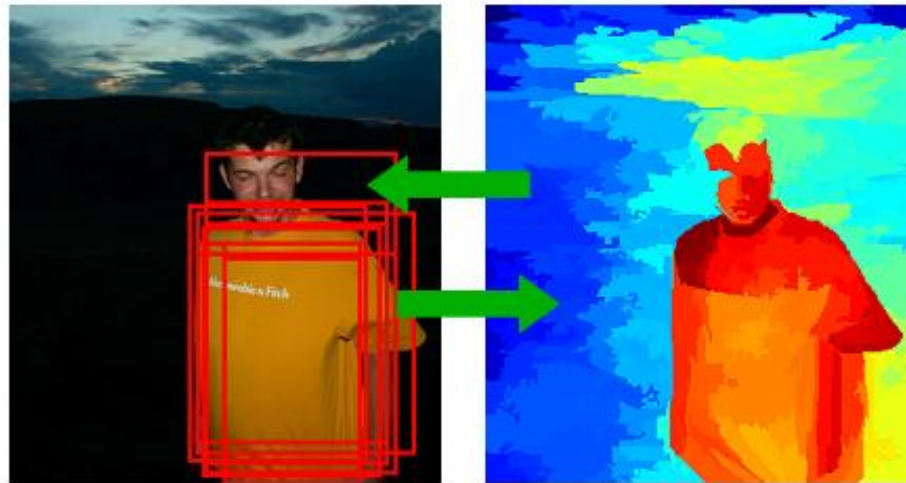
- Computer vision applications may benefit from understanding where humans focus given a scene
- Finding salient regions and objects in the images helps various tasks such as speeding up object detection, image and video compression...

Introduction

- Saliency estimation methods can be implemented by following three distinct models: bottom-up model, top-down model and combination of both.
- The proposed approach fuses top-down object level information and bottom-up pixel appearances to obtain a final saliency map that identifies the most interesting regions in the image.

Related Work

- *Fusing Generic Objectness and Visual Saliency for Salient Object Detection (ICCV-2011)*: first to adopt a high-level object information as saliency prior



Related Work

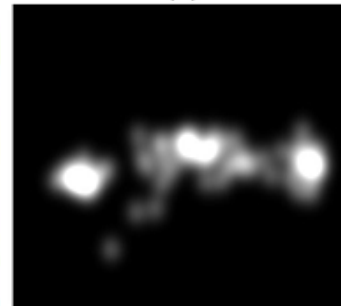
- *Learning to Predict Where Humans Look(ICCV-2009)*:
 - method extracts low-, mid-, high-level features(33 features)
 - uses a learning approach to train a classifier directly from human eye tracking data.



(a)



(b)



(c)



(d)

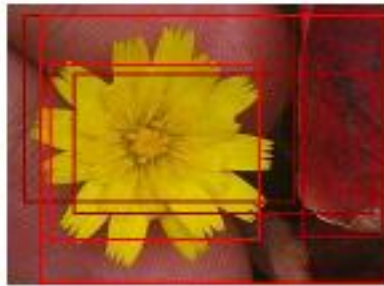
Method

- The proposed method gets high-level object information and low-level pixel appearance then fuse them with a fully-connected Markov random field
- Two steps;
 1. Object detection for high-level information
 2. Saliency computation with MRF

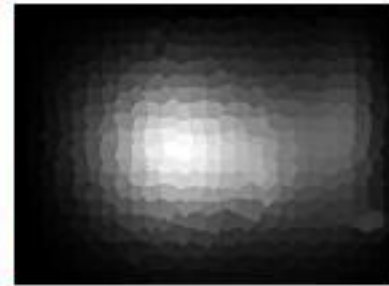
Method



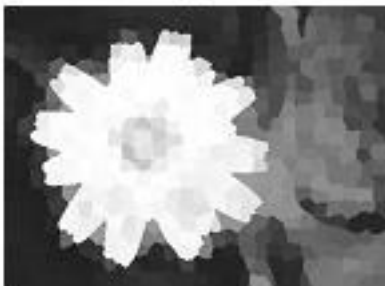
(a)



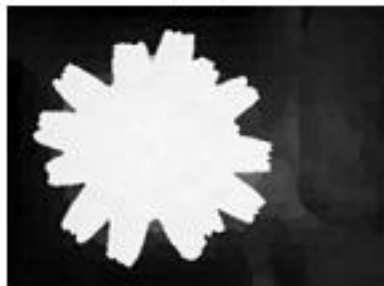
(b)



(c)



(d)



(e)



(f)

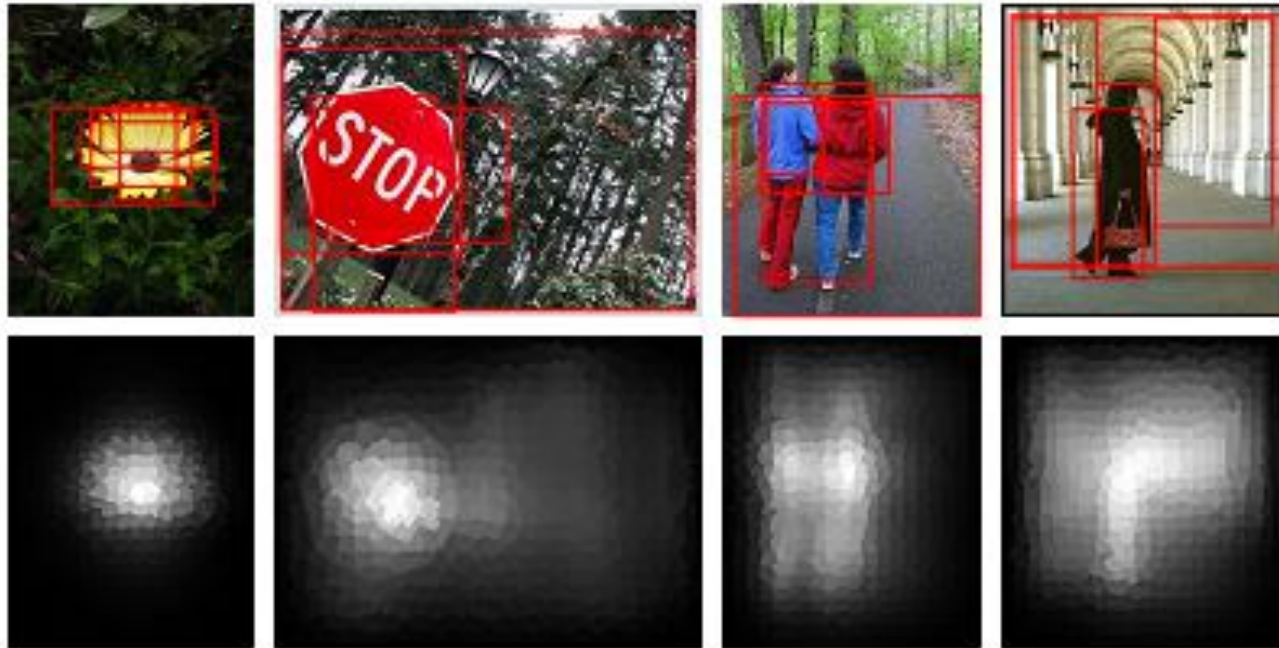
Method

1. Object Detection

- An objectness algorithm is used for detection: *What is an object?*, (Bogdan Alexe, Thomas Deselaers, Vittorio Ferrari – CVPR 2010)
- *It adopts four different low-level cues: Multiscale saliency, color contrast, edge density, superpixel straddling.*

Method

1. Object Detection



Method

1. Object Detection

- Pixel level objectness scores

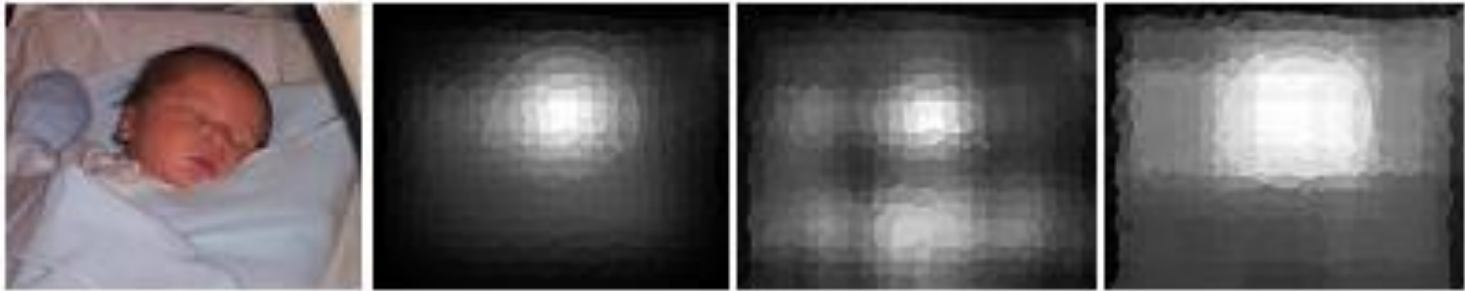
$$s_p = \left[\sum_{i=1}^N b_i^2 I(p \in B_i) \exp\{-\lambda d(p, B_i)\} \right]^{1/2}$$

- To reduce the computation cost for subsequent steps they adopted the idea of superpixels and averaged the saliency values of pixels inside each superpixel.
- Turbopixel algorithm is used to product superpixel that have similar sizes.

Method

1. Object Detection

- Pixel level objectness scores



Image

rss

ave

no smooth

Method

2. Saliency Computation

- objectness bounding boxes are often over-complete, and the saliency map is often very coarse
- low-level appearance based information to be helpful in refining the saliency maps.
- The proposed method extracts features for individual pixels, and use a MRF to enforce agreement between salient regions in the image, based on the similarities between pixel level features.

Method

2. Saliency Computation

- They use fully connected MRF where any two super-pixels are connected :

$$W_{ij} = \exp\left(\frac{-\|p_i, p_j\|_2^2}{2\sigma^2}\right)$$

$$DD_i = \sum_j \left(W_{ij} s_j + (1 - W_{ij})(1 - s_j) \right)$$

Method

$$DD_i \leftarrow \left(\frac{DD_i}{\max_j DD_j} \right)^\gamma$$
















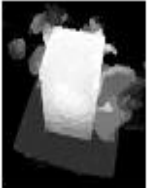





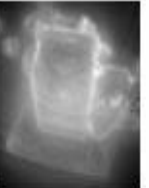









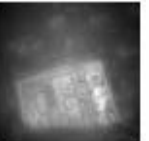
Method

2. Saliency Computation

$$G_{ij} = \frac{DD_i + DD_j}{2} W_{ij}$$

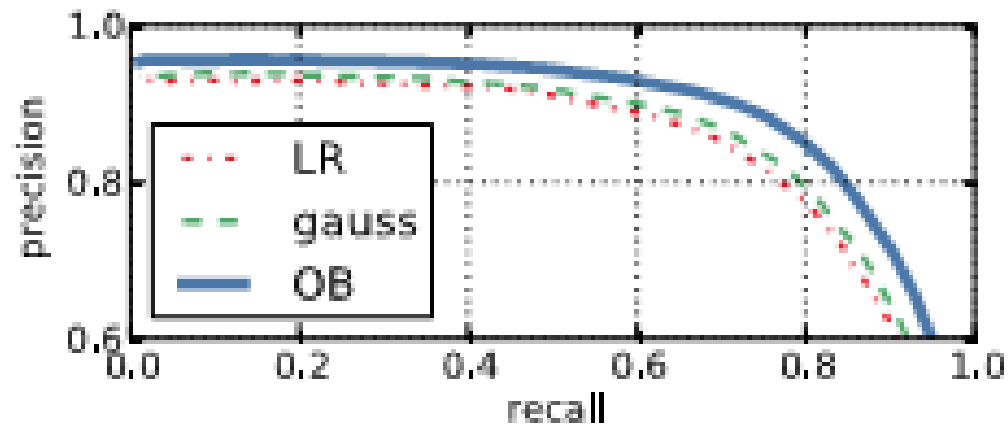
$$\hat{\mathbf{s}} = \left(\text{diag}(\mathbf{G}\mathbf{1}) - \mathbf{G} \right)^+ \begin{bmatrix} \mathbf{s} & \mathbf{1} - \mathbf{s} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Method

Image	GT	OB	GS	SF	LR	RC	SV	IG	JD
									
									
									

Method

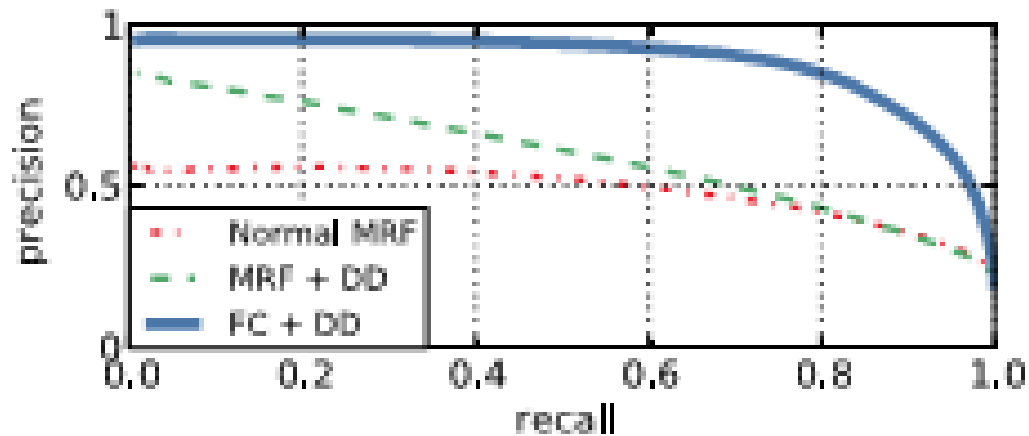
- The prior effect



(a) Different Prior

Method

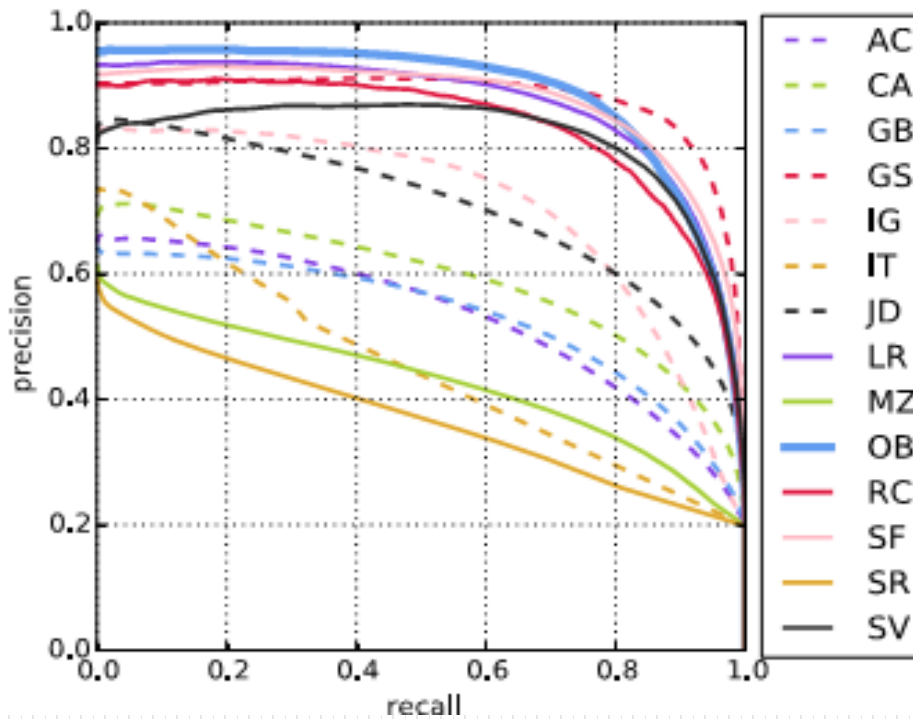
- The graph effect



(b) Different Graph

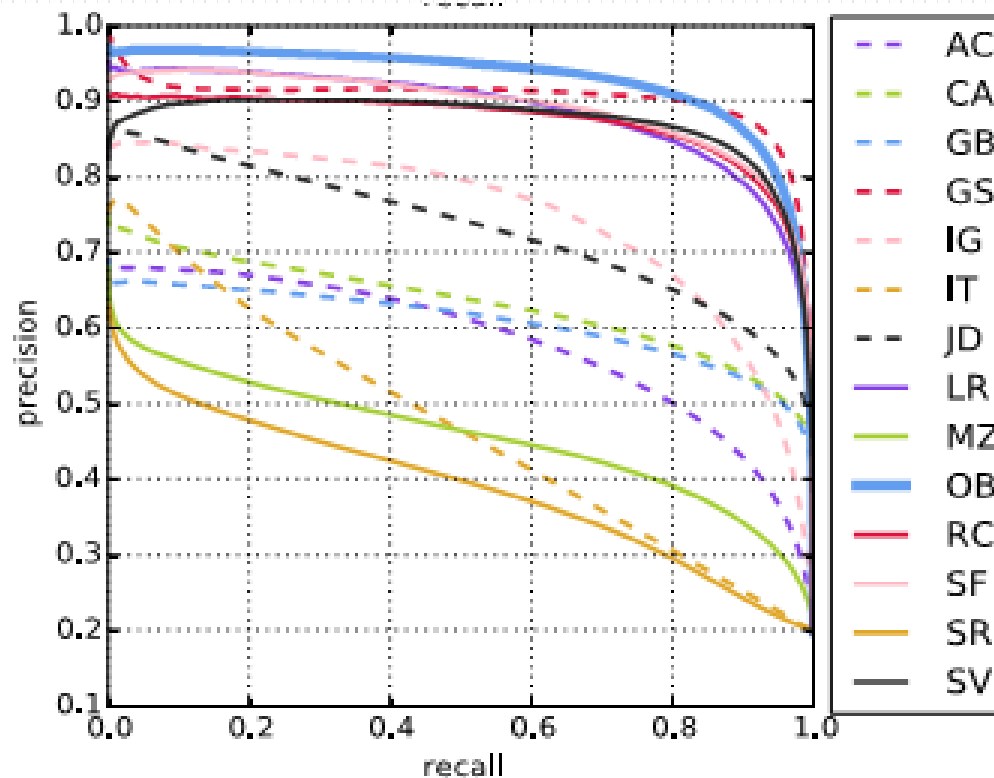
Results

- MSRA Dataset
 - PR-overall:



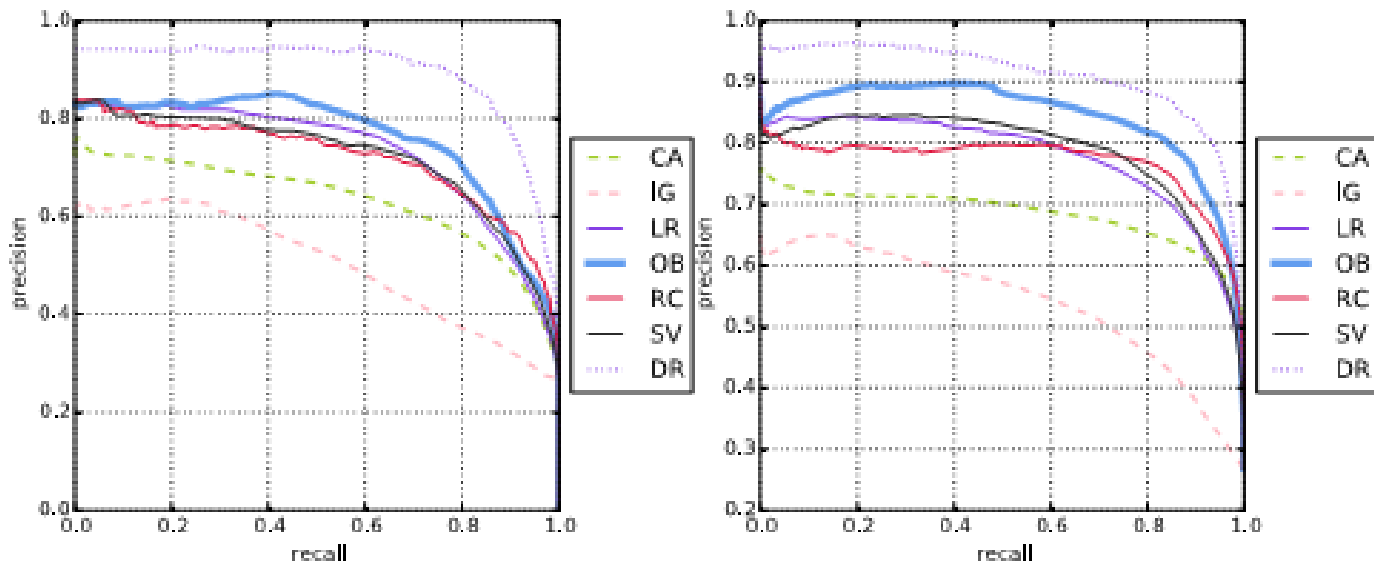
Results

- MSRA Dataset
 - PR- individual :



Results

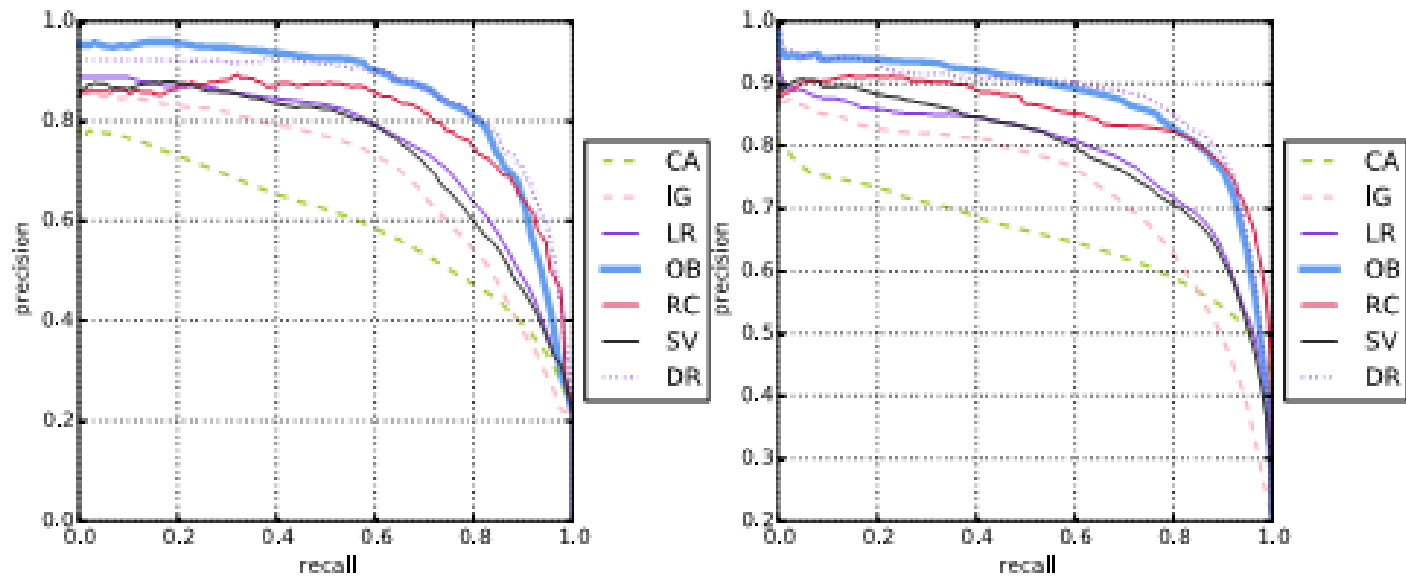
- Weizmann Dataset



(a) Weizmann 1 Object Dataset

Results

- Weizmann Dataset



(b) Weizmann 2 Object Dataset

References

- B. Alexe, T. Deselaers, and V. Ferrari. What is an object? In CVPR, 2010
- K.Y. Chang, T.L. Liu, H.T. Chen, and S.H. Lai. Fusing generic objectness and visual saliency for salient object detection. In CVPR. IEEE, 2011
- T. Judd, K. Ehinger, F. Durand, and A. Torralba. Learning to predict where humans look. In ICCV, 2009

Thanks