



Nonparametric Scene Parsing with Adaptive Feature Relevance and Semantic Context

Gautam Singh
Jana Kosecka

Emine Gül DANACI
N12129719
Master Student

Related Works

- J. Tighe and S. Lazebnik. Superparsing: Scalable nonparametric image parsing with superpixels. In ECCV (5), pages 352–365, 2010.
- D. Eigen and R. Fergus. Nonparametric image parsing using adaptive neighbor sets. In CVPR, pages 2799–2806, 2012.
- D. Ramanan and S. Baker. Local distance functions: A taxonomy, new algorithms, and an evaluation. PAMI, 33(4):794–806, 2011.
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Approach

- Local patches (gradient orientation, color, location features)
- k-NN
- Semantic Labelling

Semantic segmentation with small superpixels

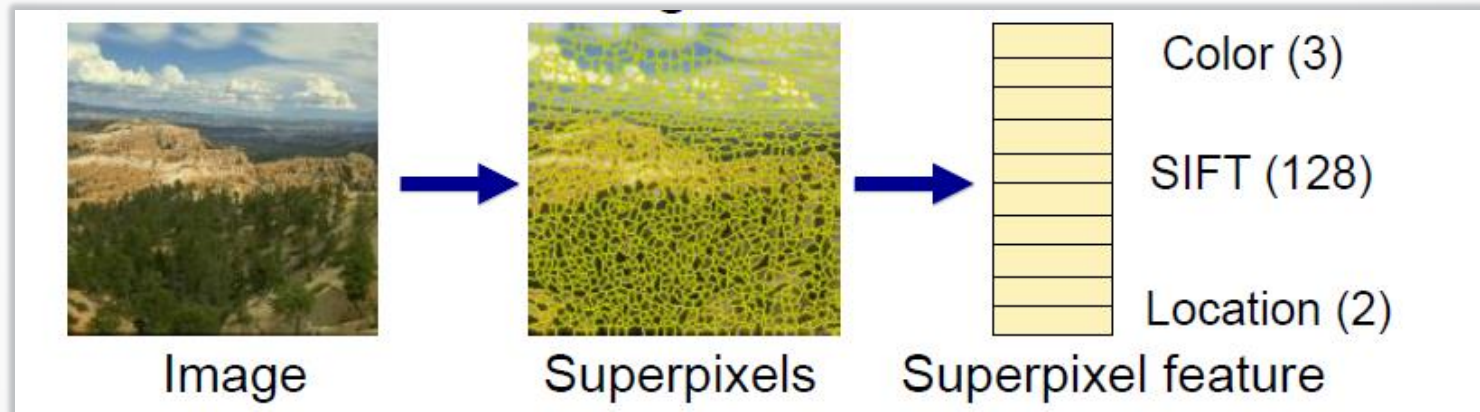
Posterior probability of labelling \mathbf{L}

$$P(\mathbf{L}|\mathbf{A}) = \frac{P(\mathbf{A}|\mathbf{L}) P(\mathbf{L})}{P(\mathbf{A})}.$$

Estimated value of labelling \mathbf{L} as MAP

$$\operatorname{argmax}_{\mathbf{L}} P(\mathbf{L}|\mathbf{A}) = \operatorname{argmax}_{\mathbf{L}} P(\mathbf{A}|\mathbf{L}) P(\mathbf{L}).$$

Supercixels and features



Retrieval set

- Global image features
 - GIST
 - Spatial Pyramid of quantized SIFT
 - RGB-Color Histograms
- Euclidean distance from the query image
- Ranking
- Re-ranking

Appearance likelihood

Naive Bayes assumption

$$P(\mathbf{A}|\mathbf{L}) \approx \prod_{i=1}^S P(\mathbf{a}_i|l_i).$$

Label likelihood score

$$L(\mathbf{a}_i, l_j) = \frac{n(l_j, N_{ik})/n(l_j, G)}{n(\bar{l}_j, N_{ik})/n(\bar{l}_j, G)}$$

- $\bar{l}_j = L \setminus l_j$ is the set of all labels excluding l_j ;
- N_{ik} is a neighbourhood around \mathbf{a}_i with exactly k points in it;
- $n(l_j, N_{ik})$ is the number of superpixels of class l_j inside N_{ik} ;
- $n(l_j, G)$ is the number of superpixels of class l_j in the set G

Weighted k-NN

Color, SIFT and location

$$d_f^{ij} = [d_c^{ij}, d_s^{ij}, d_l^{ij}]^\top$$

Weighted distance

$$d_w^{ij} = w^\top d_f^{ij} \quad w = [w_1, w_2, w_3] \in \mathbb{R}^3$$

Weight computation

i: feature channel

x: query point

N: neighbourhood

c: influence of weights

$$r_i(\mathbf{z}) = \sum_{l_j=1}^{nL} \frac{(P(l_j|\mathbf{z}) - \bar{P}(l_j|x_i = z_i))^2}{\bar{P}(l_j|x_i = z_i)}$$

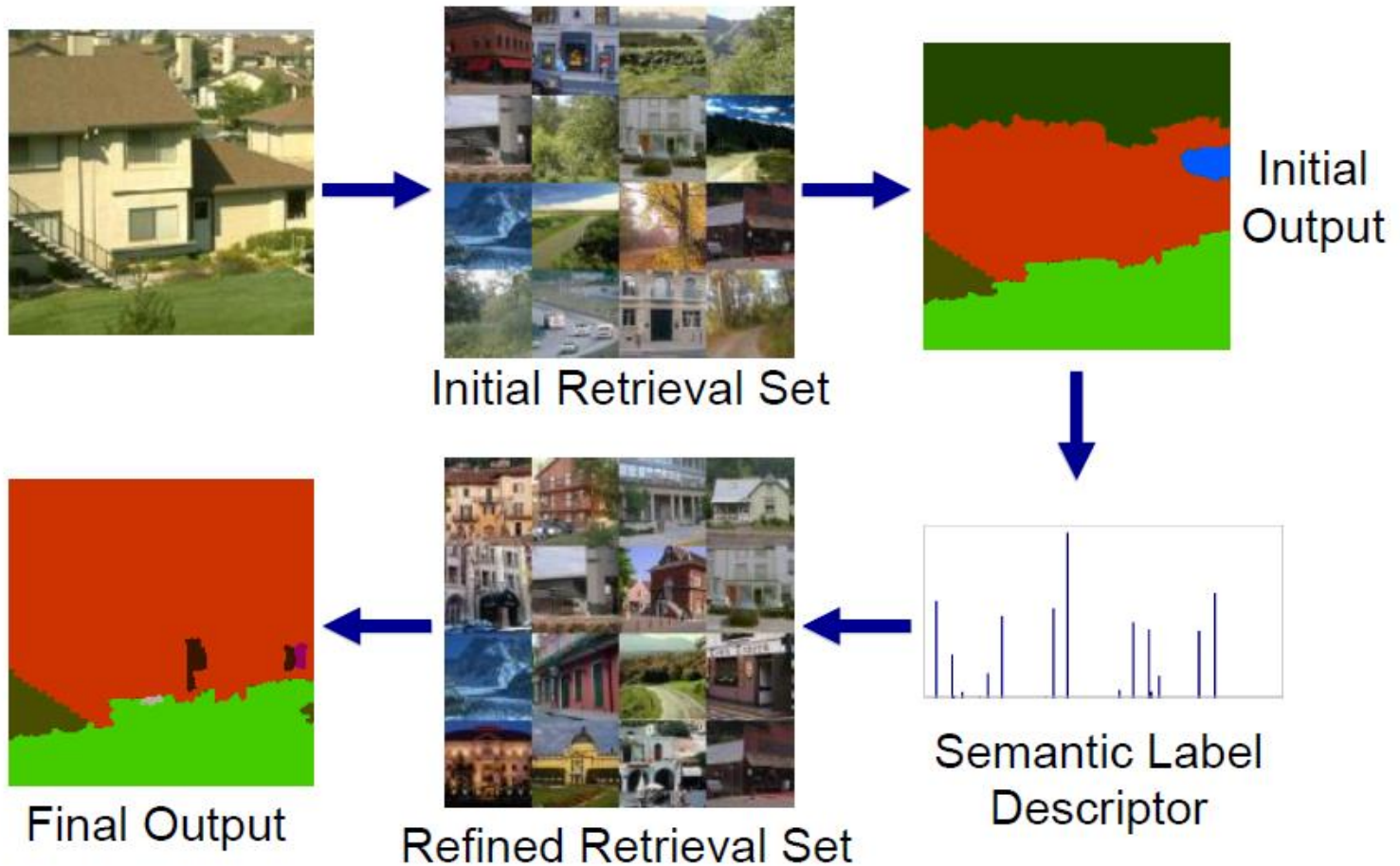
$$\bar{r}_i(\mathbf{x}_0) = \frac{1}{|N(\mathbf{x}_0)|} \sum_{\mathbf{z} \in N(\mathbf{x}_0)} r_i(\mathbf{z})$$

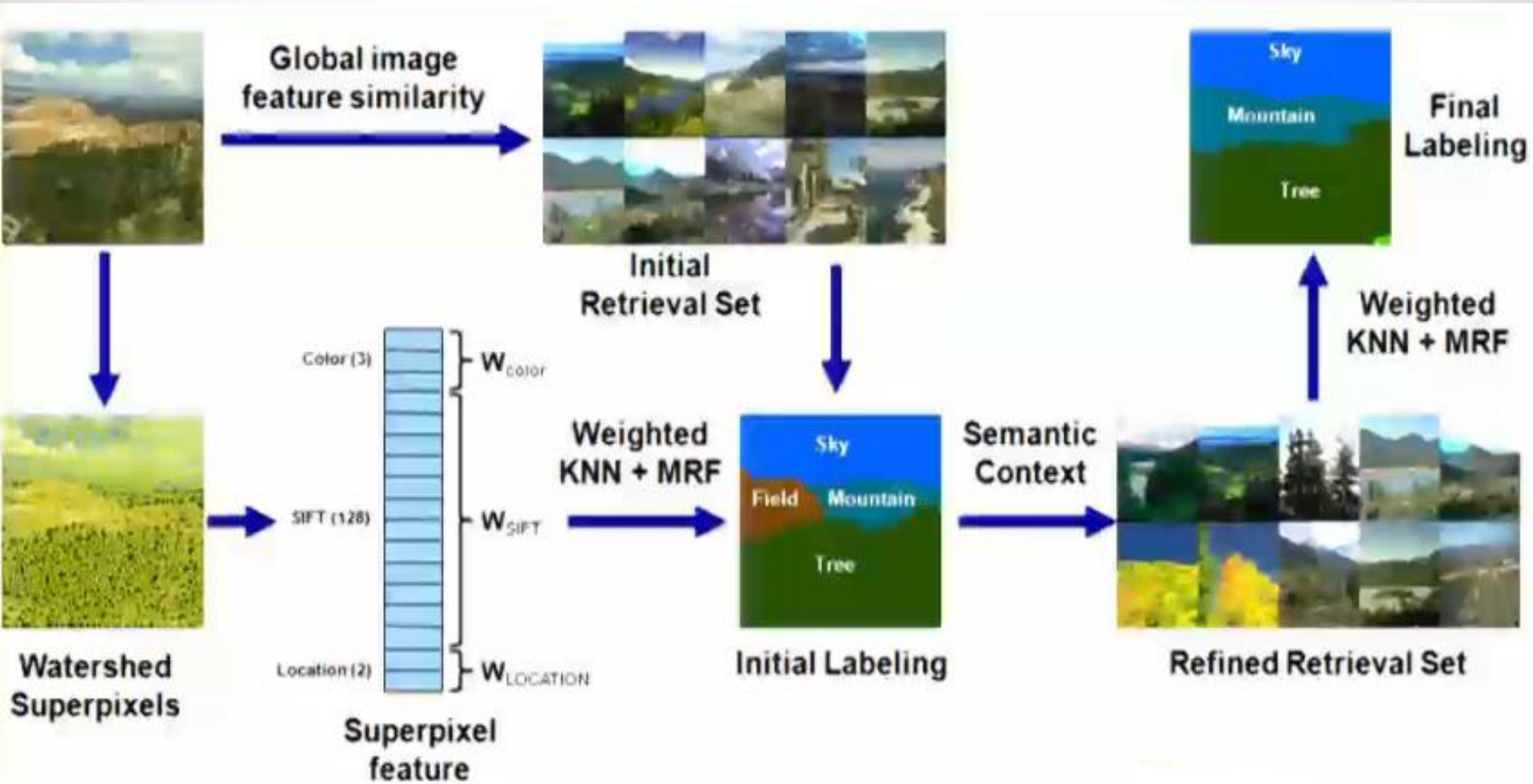
$$w_i(\mathbf{x}_0) = \frac{\exp(cR_i(\mathbf{x}_0))}{\sum_{p=1}^m \exp(cR_p(\mathbf{x}_0))}$$

Query based algorithm

- 1) Initialize w to uniform weights
- 2) At query point x_0 , find set N_0 of K_0 nearest neighbors using current w
- 3) For each feature channel, compute relevance estimate using points in N_0
- 4) Update w using relevance estimates from 3
- 5) Repeat steps 2-4 (five times in our experiments)

Semantic retrieval set





Experiments

- Datasets
 - SiftFlow – 2688 images with 33 semantic categories
 - 2488 for training 200 for testing
 - SUN09 – fully labeled, 107 semantic categories
 - 4352 for training 4310 for testing
 - Google Street View – labeled data, 320 images
 - 160 for training 160 for testing
 - Stanford Background – semantic and geometric labeled 715 images
 - 572 for training 143 for testing

Results

System	Per-Pixel	Per-Class
Liu et al. [15]	76.7	-
Tighe et al. [26]	76.9	29.4
Eigen et al. [4]	77.1	32.5
UKNN-MRF	75.6	27.9
WKNN-MRF	77.2	29.3
WLKNN-MRF	78.5	32.0
WAKNN-MRF	79.2	33.8
WKNN-MRF (with HOG)	76.7	27.4

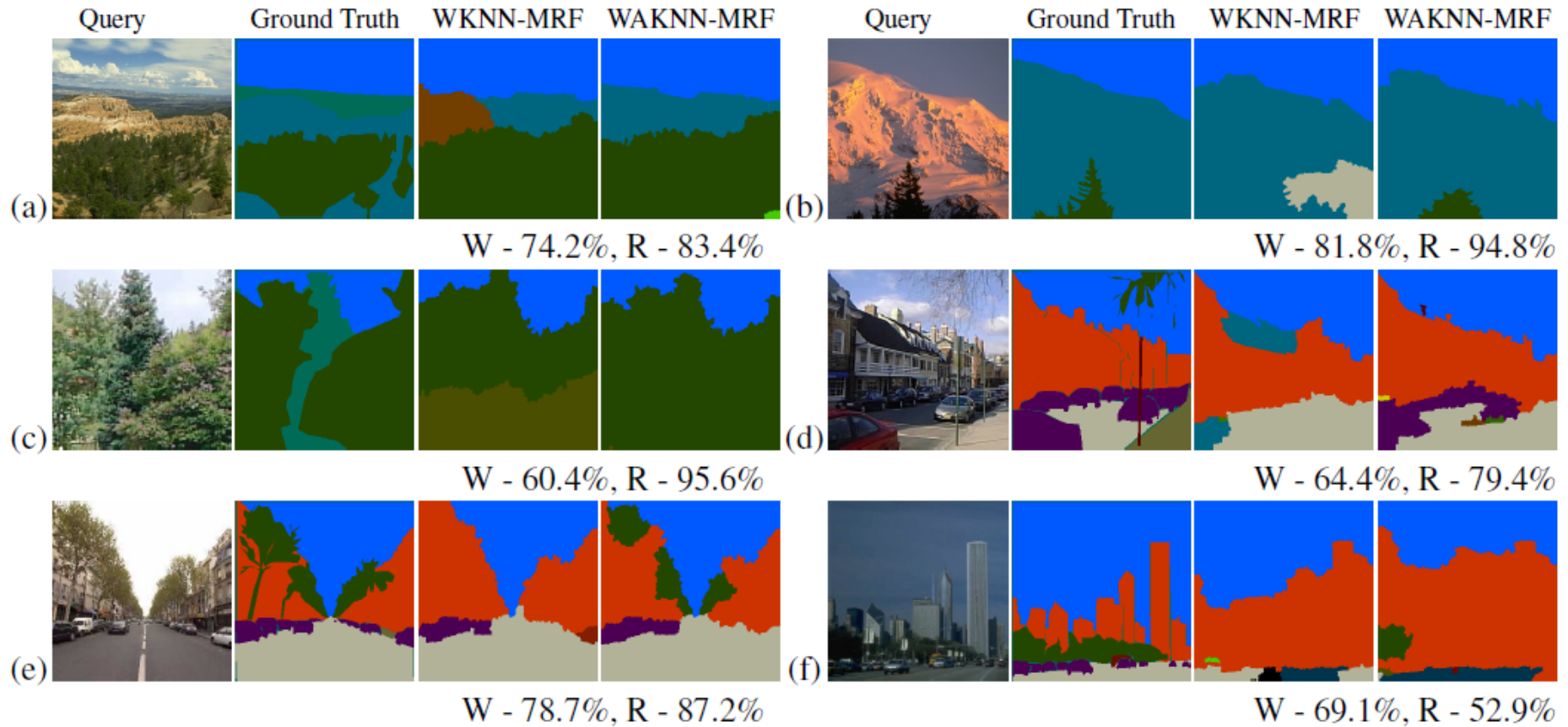
Table 1. Semantic labelling performance on the SiftFlow dataset

Results

Dataset and System	Per-Pixel	Per-Class
SUN09		
Choi et al. [1]	33.0	10.6
[25] CascALE Expert	49.3	16.7
[25] CascALE Sharing	52.8	15.2
WKNN-MRF	49.5	8.7
WAKNN-MRF	53.1	12.1
Google Streetview		
Zhang et al. [32]	88.4	80.4
Zhang et al. [31]	93.2	73.1
Singh et al. [24]	94.4	81
WAKNN-MRF	93.7	76.4
Stanford background		
[6] Pixel CRF	74.3	66.6
[6] Region Energy	76.4	65.5
[20] Leaf Level	72.8	58.0
[20] Hierarchy	76.9	66.2
WKNN-MRF	73.6	61.2
WAKNN-MRF	74.1	62.2

Table 2. Performance on the SUN09, Google-Streetview and Stanford background datasets.

Results



THANK YOU!